

SOLVABILITY FOR TIME-FRACTIONAL SEMILINEAR PARABOLIC EQUATIONS WITH SINGULAR INITIAL DATA

MARIUS GHERGU, YASUHIITO MIYAMOTO, AND MASAMITSU SUZUKI

ABSTRACT. We discuss the existence and nonexistence of a local and global-in-time solution to the fractional problem

$$\begin{cases} \partial_t^\alpha u = \Delta u + f(u) & x \in \Omega, 0 < t < T, \\ u = 0 & x \in \partial\Omega, 0 < t < T, \\ u(x, 0) = u_0(x) & x \in \Omega, \end{cases}$$

where $\Omega \subset \mathbb{R}^N$ ($N \geq 1$) is a bounded domain with C^2 boundary, $0 < T \leq \infty$, $u_0 \in L^r(\Omega)$ ($1 \leq r < \infty$) and ∂_t^α ($0 < \alpha < 1$) is the Caputo fractional derivative. We assume that $f(u)$ is a continuous function such that for some $p > 1$ one has $|f(\xi) - f(\eta)| \leq C(1 + |\xi| + |\eta|)^{p-1}|\xi - \eta|$ for all $\xi, \eta \in \mathbb{R}$. Particular attention is paid to the doubly critical case $(p, r) = (1 + 2/N, 1)$.

1. INTRODUCTION AND MAIN RESULTS

Let $\Omega \subset \mathbb{R}^N$ ($N \geq 1$) be a bounded domain with C^2 boundary and $0 < \alpha < 1$. We are interested in existence and nonexistence of a solution of the time fractional spatially homogeneous parabolic problem

$$(1.1) \quad \begin{cases} \partial_t^\alpha u = \Delta u + f(u) & x \in \Omega, 0 < t < T, \\ u = 0, & x \in \partial\Omega, 0 < t < T, \\ u(x, 0) = u_0(x) & x \in \Omega, \end{cases}$$

where $0 < T \leq \infty$. The operator ∂_t^α denotes the Caputo fractional derivative defined by

$$\partial_t^\alpha u(t) = \frac{d}{dt} \int_0^t \frac{1}{\Gamma(1-\alpha)} \frac{u(s) - u(0)}{(t-s)^\alpha} ds,$$

where Γ is the usual Gamma function. If $u(t)$ is smooth enough, then the above derivative can be written as

$$\partial_t^\alpha u(t) = \frac{1}{\Gamma(1-\alpha)} \int_0^t \frac{\partial_s u(s)}{(t-s)^\alpha} ds.$$

In the last two decades various models involving fractional time derivatives have been devised to discuss real life phenomena ranging from hydrology [3] and earth sciences [29] to medical image enhancement [18] and biosciences [20].

Date: November 14, 2021.

2020 Mathematics Subject Classification. Primary: 35R11, secondary 35K55, 35K10.

Key words and phrases. Fractional parabolic problems; Existence and nonexistence; Critical exponents.

YM was supported by JSPS KAKENHI Grant Numbers 19H01797, 19H05599.

MS was supported by Grant-in-Aid for JSPS Fellows No. 20J11985.

From mathematical point of view, the Caputo fractional derivative has been recently discussed in the frame of diffusion equation [2,8], Hamilton-Jacobi equation [6], predator-prey models [11], transport equation [19], acoustic wave equations [14], porous medium equation [26] and Ginzburg-Landau equation [27]. A maximum principle for differential equations involving Caputo fractional derivative is studied in [15].

In the present work we investigate the influence of the Caputo fractional derivative in the parabolic problem (1.1). We assume that $f : \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function that fulfils:

(F1) there is $C > 0$ such that

$$|f(\xi) - f(\eta)| \leq C(1 + |\xi| + |\eta|)^{p-1}|\xi - \eta| \text{ for } \xi, \eta \in \mathbb{R}.$$

When we discuss the existence of a global-in-time solution, we replace (F1) above with the slightly stronger condition, namely

(F1') $f(0) = 0$ and there is $C > 0$ such that

$$|f(\xi) - f(\eta)| \leq C(|\xi| + |\eta|)^{p-1}|\xi - \eta| \text{ for } \xi, \eta \in \mathbb{R}.$$

In defining the notion of a solution to (1.1) we follow [10, Section 3]. We consider the following Wright type function

$$\Phi_\alpha(z) = \sum_{n=0}^{\infty} \frac{(-z)^n}{n! \Gamma(-\alpha n + 1 - \alpha)}, \quad z \in \mathbb{C}.$$

It is known that $\Phi_\alpha(t)$ satisfies

$$\Phi_\alpha(t) \geq 0 \text{ for } t \geq 0 \text{ and } \int_0^\infty \Phi_\alpha(t) dt = 1,$$

and hence $\Phi_\alpha(t)$ is a probability density function. Moreover,

$$\int_0^\infty t^p \Phi_\alpha(t) dt = \frac{\Gamma(p+1)}{\Gamma(\alpha p + 1)}, \quad p > -1, \quad 0 < \alpha < 1.$$

Let Δ be the Dirichlet Laplacian on Ω in the Lebesgue $L^r(\Omega)$, $1 \leq r < \infty$, equipped with the norm $\|\cdot\|_r$ whose domain is $\{u \in W^{2,r}(\Omega); u = 0 \text{ in } \partial\Omega\}$. Then Δ generates a strongly continuous semigroup $\{S(t)\}_{t \geq 0}$ on $L^r(\Omega)$. For $t > 0$ we define

$$S_\alpha(t), P_\alpha(t) : L^r(\Omega) \rightarrow L^r(\Omega)$$

by

$$(1.2) \quad \begin{cases} S_\alpha(t)v = \int_0^\infty \Phi_\alpha(\tau) S(\tau t^\alpha) v d\tau, \\ P_\alpha(t)v = \alpha t^{\alpha-1} \int_0^\infty \tau \Phi_\alpha(\tau) S(\tau t^\alpha) v d\tau, \end{cases} \quad \text{for all } v \in L^r(\Omega).$$

Let us consider the nonhomogeneous problem

$$(1.3) \quad \begin{cases} \partial_t^\alpha u = \Delta u + f(x, t, u), & x \in \Omega, 0 < t < T, \\ u = 0, & x \in \partial\Omega, 0 < t < T, \\ u(x, 0) = u_0(x), & x \in \Omega, \end{cases}$$

where $f : \Omega \times [0, \infty) \times \mathbb{R} \rightarrow \mathbb{R}$ is a measurable function that satisfies, instead of (F1) and (F1') above, the nonhomogeneous conditions:

- (i) there exists $c : \Omega \times [0, \infty) \rightarrow (0, \infty)$ and $p \geq 1$ such that for all $\xi \in \mathbb{R}$ and a.e. $(x, t) \in \Omega \times (0, T)$ there holds

$$(1.4) \quad |f(x, t, \xi)| \leq c(x, t)(1 + |\xi|^p);$$

- (ii) For all $\xi, \eta \in \mathbb{R}$ and a.e. $(x, t) \in \Omega \times (0, T)$ there holds

$$(1.5) \quad |f(x, t, \xi) - f(x, t, \eta)| \leq c(x, t)(1 + |\xi| + |\eta|)^{p-1}|\xi - \eta|.$$

Here,

$$(1.6) \quad \left(\int_0^T \|c(\cdot, t)\|_{L^{q_1}(\Omega)}^{q_2} dt \right)^{1/q_2} < \infty,$$

for $q_1, q_2 \in [1, \infty)$, with the obvious modifications when $q_1 = \infty$ and $q_2 = \infty$.

We adopt the following definition of a mild solution of (1.3) from [10, Definition 3.1.1].

Definition 1.1. We say that a measurable function u a solution of (1.3) if there exists $T \in (0, \infty]$ such that the following conditions (a)–(e) hold:

- (a) $u(\cdot, t) \in L^1(\Omega)$ for all $0 < t < T$;
- (b) $f(\cdot, t, u(\cdot, t)) \in L^1(\Omega)$ for a.e. $0 < t < T$;
- (c) $\int_0^t \|f(\cdot, s, u(\cdot, s))\|_1 ds < \infty$ for $0 < t < T$;
- (d) $u(\cdot, t)$ satisfies

$$u(\cdot, t) = S_\alpha(t)u_0 + \int_0^t P_\alpha(t-s)f(\cdot, s, u(\cdot, s))ds \quad \text{for } 0 < t < T,$$

where the integral in the above equality is an absolutely converging Bochner integral in $L^1(\Omega)$;

- (e) The initial condition holds in the following sense:

$$\|u(\cdot, t) - u_0\|_r \rightarrow 0 \quad \text{as } t \rightarrow 0$$

for $u_0 \in L^r(\Omega)$ if $1 \leq r < \infty$.

It follows from [10, Remark 3.1.2] that the property (e) in the Definition 1.1 holds if and only if

$$(1.7) \quad \|u(\cdot, t) - S_\alpha(t)u_0\|_r \rightarrow 0 \quad \text{as } t \rightarrow 0,$$

which is equivalent to the convergence to zero in the norms of the integral term in Definition 1.1 (d).

The aim of the paper is to develop an L^r -theory for the Cauchy-Dirichlet problem (1.1), $1 \leq r < \infty$ with a particular focus on the case $r = 1$. A solution u of (1.1) is defined similarly to Definition 1.1 above where $f(x, t, u) = f(t, u)$. The homogeneous version of [10, Theorem 3.1.4] that applies to (1.1) reads as follows:

Proposition 1.2 (Local existence in $L^r(\Omega)$). *Let $N \geq 1$ and $0 < \alpha < 1$. Assume that $f \in C(\mathbb{R})$ satisfies (F1) and that one of the following holds:*

- (i) (Subcritical case) $1 \leq r < \infty$ and $1 \leq p < 1 + 2r/N$,
- (ii) (Critical case) $1 < r < \infty$ and $1 < p = 1 + 2r/N$.

Then, for each initial function $u_0 \in L^r(\Omega)$, (1.1) has a local-in-time solution in the sense of Definition 1.1.

On the other hand, the nonexistence of a solution to (1.1) is not completely understood, apart from the case of pure-power nonlinearities $f(u)$ (see [23]). The first main result of this work discusses the nonexistence of a nonnegative solution of (1.1) which shows the sharpness of the two conditions (i), (ii) in Proposition 1.2.

Theorem 1.3 (Nonexistence in $L^r(\Omega)$, $1 \leq r < \infty$). *Let $N \geq 1$ and $0 < \alpha < 1$. Suppose that $f : \mathbb{R} \rightarrow \mathbb{R}$ is nonnegative and nondecreasing. If $1 \leq r < \infty$ and*

$$(1.8) \quad \limsup_{s \rightarrow \infty} \frac{f(s)}{s^{1+2r/N}} = \infty,$$

then there exists a nonnegative $u_0 \in L^r(\Omega)$ such that (1.1) has no nonnegative solution in the sense of Definition 1.1.

For

$$(1.9) \quad f(x, t, u) = c(x, t)|u|^{p-1}u \quad (x, t, u) \in \Omega \times [0, \infty) \times \mathbb{R},$$

the nonexistence of a local-in-time solution to (1.3) was obtained in [23]. To the best of our knowledge, Theorem 1.3 is new for general nonlinearities $f(u)$.

For nonlinearities $f(x, t, u)$ given by (1.9), the nonexistence of a solution to (1.3) with a general partial differential operator A instead of Δ is conjectured in [10, Problem 2 in p.154]. In the Laplacian case the conjecture reads as follows: Let $q_1, q_2 \in [1, \infty]$ be given in (1.6). If

$$(1.10) \quad \frac{N}{2q_1} + \frac{1}{\alpha q_2} + \frac{N(p-1)}{2r} > 1,$$

then (1.3) does not have a solution for some initial data $u_0 \in L^r(\Omega)$. When $q_1 = q_2 = \infty$, (1.10) becomes $p > 1 + 2r/N$. By (1.8) we see that Theorem 1.3 gives an affirmative answer for the homogeneous nonlinearity $f = f(u)$.

Let us consider the case $f(u) = |u|^{p-1}u$. For each $r \in (1, \infty)$, Theorem 1.3 indicates that Proposition 1.2 is sharp in this case, i.e., if $1 < p \leq 1 + 2r/N$, then (1.1) with $u_0 \in L^r(\Omega)$ has a solution. On the other hand, if $p > 1 + 2r/N$, there is a nonnegative initial function $u_0 \in L^r(\Omega)$ such that (1.1) has no nonnegative solution. The semilinear case $\alpha = 1$ is discussed in Weissler [25].

Let us next comment on the case $r = 1$ in the setting of pure power nonlinearities $f(u) = |u|^{p-1}u$. By Proposition 1.2 and Theorem 1.3 we see the following:

- If $1 \leq p < 1 + 2/N$, then (1.1) with $u_0 \in L^1(\Omega)$ has a solution;
- If $p > 1 + 2/N$, then (1.1) with $u_0 \in L^1(\Omega)$ does not always have a nonnegative solution.

The doubly critical case $(p, r) = (1 + 2/N, 1)$ is not covered by neither the above Proposition 1.2 and Theorem 1.3. This requires a more delicate analysis as both exponents reach the critical threshold.

In the semilinear case $\alpha = 1$ and $(p, r) = (1 + 2/N, 1)$, it is known that there is a nonnegative initial function $u_0 \in L^1(\Omega)$ such that (1.1) has no nonnegative solution; see [5, 7] for a nonexistence result in the case $\Omega = \mathbb{R}^N$ and [7, 17] in the case where Ω is bounded.

In the recent paper [21] it is shown that the problem

$$\begin{cases} \partial_t u = \Delta u + |u|^{2/N}u & x \in \mathbb{R}^N, 0 < t < T, \\ u(\cdot, 0) = u_0 \in L^1(\mathbb{R}^N) & x \in \mathbb{R}^N, \end{cases}$$

has solutions if and only if

$$\int_{\mathbb{R}^N} |u_0| (\log(|u_0| + e))^{N/2} dx < \infty.$$

Local existence of a solution to (1.1) is studied in an abstract setting in [1, 12, 24]. However, those methods are not applicable to our present setting, since a local Lipschitz (or Hölder) condition in a function space is assumed.

Our second main result concerns the existence of a local-in-time solution to (1.1) in the critical case $(p, r) = (1 + 2/N, 1)$.

Theorem 1.4 (Local solution in $L^1(\Omega)$). *Let $N \geq 1$, $0 < \alpha < 1$ and $p = 1 + 2/N$. Suppose that $f \in C(\mathbb{R})$ satisfies (F1).*

Then, for each initial function $u_0 \in L^1(\Omega)$, (1.1) has a local-in-time solution in the sense of Definition 1.1.

Theorem 1.4 shows a sharp contrast in terms of existence of local-in-time solutions to (1.1) in comparison to the semilinear case $\alpha = 1$.

Our third main result discusses the existence of a global-in-time solution to (1.1) in the critical case $(p, r) = (1 + 2/N, 1)$. This time we require f satisfies (F1') instead (F1).

Theorem 1.5 (Global solution in $L^1(\Omega)$). *Let $N \geq 1$, $0 < \alpha < 1$ and $p = 1 + 2/N$. Suppose that $f \in C(\mathbb{R})$ satisfies (F1').*

Then, there exists $\varepsilon > 0$ such that for all $u_0 \in L^1(\Omega)$ with $\|u_0\|_1 \leq \varepsilon$ there exists a global-in-time solution u of (1.1) in the sense of Definition 1.1 with $T = \infty$.

Moreover, if u_0 is nontrivial and nonnegative and $\|u_0\|_1 \leq \varepsilon$, then (1.1) has a nontrivial nonnegative global-in-time solution.

When $\alpha = 1$, $f(u) = u^p$ and $\Omega = \mathbb{R}^N$, Fujita [9] showed the following: If $1 < p < 1 + 2/N$, then (1.1) with a nontrivial nonnegative initial data blows up in finite time. If $p > 1 + 2/N$, then there is a small nontrivial nonnegative

initial function u_0 such that (1.1) has a global-in-time solution. It is proved in [13,16] that a nontrivial nonnegative solution blows up in the threshold case $p = 1 + 2/N$.

This shows again a sharp contrast with the fractional case $0 < \alpha < 1$. For $f(u) = u^p$ and $\Omega = \mathbb{R}^N$ it is shown in [28] that (1.1) may have a nontrivial nonnegative global-in-time solution. Our Theorem 1.5 is in line with the result in [28] in the sense that the existence of a global-in-time solution still holds for small L^1 data in the case of bounded smooth domains Ω .

Theorem 1.6 (Uniqueness of solution). *Let $N \geq 1$, $0 < \alpha < 1$, $p = 1 + 2/N$ and $\beta = \alpha/p$. Suppose that $f \in C(\mathbb{R})$ satisfies (F1).*

Then, (1.1) has a unique solution in the class

$$K := \left\{ u(t) \in C([0, T], L^1(\Omega)) \text{ for some } 0 < T \leq \infty \text{ and } \sup_{0 < t < T_1} t^\beta \|u(t)\|_p < \infty \right\},$$

in the sense that if $u(t) \in C([0, T_1], L^1(\Omega))$ and $v(t) \in C([0, T_2], L^1(\Omega))$ are two solutions in the above class K then

$$u(t) = v(t) \text{ in } L^1(\Omega) \text{ for } 0 \leq t < \min\{T_1, T_2\}.$$

The remaining of the paper is organised as follows. In Section 2 we recall the L^r -theory ($1 < r < \infty$) for (1.3) and a monotone iterative method. A supersolution to (1.1) is constructed by using a solution of (1.3). Then, a monotone iterative method enables us to construct a nonnegative solution of (1.1) under a mild condition on f . In Section 3 we describe the L^p - L^q estimates for $S_\alpha(t)$, $P_\alpha(t)$ and construct a local-in-time solution of (1.1) in $L^1(\Omega)$. We also construct a nonnegative solution of (1.1) in $L^1(\Omega)$ under a mild condition on f using a monotone iterative method. In Section 4 an existence of a global-in-time solution of (1.1) for a small initial data in $L^1(\Omega)$ is proved. In Section 5 we establish a nonexistence theorem in $L^r(\Omega)$, $1 \leq r < \infty$. The method used in Section 5 is based on the approach developed in [17,23]. Combining existence and nonexistence results, we obtain a necessary and sufficient condition on the growth of f for the existence of a nonnegative solution to (1.1) in $L^r(\Omega)$. Finally, in Section 6 we prove the uniqueness of a solution of (1.1) in the set K given in Theorem 1.6.

2. EXSITENCE OF A SOLUTION IN $L^r(\Omega)$, $1 < r < \infty$

Let us start with a quick overview on the monotone iteration techniques in the fractional setting. Consider the problem

$$(2.1) \quad \begin{cases} \partial_t^\alpha u = \Delta u + f_0(x, t, u), & x \in \Omega, 0 < t < T, \\ u = 0, & x \in \partial\Omega, 0 < t < T, \\ u(x, 0) = u_0(x), & x \in \Omega, \end{cases}$$

where $\Omega \subset \mathbb{R}^N$ ($N \geq 1$) is a bounded domain with smooth boundary and $f_0 : \Omega \times [0, \infty) \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function such that:

$$(F2) \quad f_0(x, t, \xi) \text{ is nonnegative and it is nondecreasing in } \xi.$$

Definition 2.1. We say that a measurable function u is a solution of (2.1) if there exists $T \in (0, \infty]$ such that the following conditions (a)–(e) hold:

- (a) $u(\cdot, t) \in L^1(\Omega)$ for all $0 < t < T$;
- (b) $f_0(\cdot, t, u(\cdot, t)) \in L^1(\Omega)$ for a.e. $0 < t < T$;
- (c) $\int_0^t \|f_0(\cdot, s, u(\cdot, s))\|_1 ds < \infty$ for $0 < t < T$;
- (d) $u(\cdot, t)$ satisfies

$$u(\cdot, t) = S_\alpha(t)u_0 + \int_0^t P_\alpha(t-s)f_0(\cdot, s, u(\cdot, s))ds \quad \text{for } 0 < t < T,$$

where the integral in the above equality is an absolutely converging Bochner integral in $L^1(\Omega)$;

- (e) The initial condition holds in the following sense:

$$\|u(\cdot, t) - u_0\|_r \rightarrow 0 \quad \text{as } t \rightarrow 0$$

for $u_0 \in L^r(\Omega)$ if $1 \leq r < \infty$.

We call \bar{u} a supersolution of (2.1) if \bar{u} satisfies Definition 2.1 (a)–(c) and the following (d') and (e') hold:

- (d') \bar{u} satisfies the inequality:

$$\bar{u}(\cdot, t) \geq S_\alpha(t)u_0 + \int_0^t P_\alpha(t-s)f_0(\cdot, s, \bar{u}(\cdot, s))ds \quad \text{for } 0 < t < T,$$

- (e') \bar{u} satisfies

$$\left\| \int_0^t P_\alpha(t-s)f_0(\cdot, s, \bar{u}(\cdot, s))ds \right\|_r \rightarrow 0 \quad \text{as } t \rightarrow 0,$$

where $u_0 \in L^r(\Omega)$ for some $1 \leq r < \infty$.

Proposition 2.2. *Let $0 < T \leq \infty$. Suppose that the function $f_0(x, t, \xi)$ satisfies (F2).*

If (2.1) has a nonnegative supersolution $\bar{u}(t)$ on $0 < t < T$, then (2.1) has a solution $u(t)$ in the sense of Definition 1.1 on $0 < t < T$ such that $0 \leq u(t) \leq \bar{u}(t)$.

For the reader's convenience we provide a quick proof (see [22, Theorem 2.1] for details).

Proof. Let \bar{u} be a nonnegative supersolution of (2.1) for $0 < t < T$. Set $u_1 = S(t)u_0$ and for $n \geq 2$ define u_n by

$$u_n = \mathcal{F}(u_{n-1}),$$

where

$$\mathcal{F}(u) = S_\alpha(t)u_0 + \int_0^t P_\alpha(t-s)f_0(\cdot, s, u(\cdot, s))ds.$$

Then, an induction argument yields

$$0 \leq u_1 \leq u_2 \leq \dots \leq u_n \leq \dots \leq \bar{u} < \infty \quad \text{for a.e. } x \in \mathbb{R}^N, \quad 0 < t < T.$$

This indicates that the limit $u(x, t) := \lim_{n \rightarrow \infty} u_n(x, t)$ exists for almost all $x \in \mathbb{R}^N$ and $0 < t < T$. By the monotone convergence theorem we see that

$$\lim_{n \rightarrow \infty} \mathcal{F}(u_{n-1}) = \mathcal{F}(u),$$

and hence $u = \mathcal{F}(u)$. It is clear that

$$(2.2) \quad 0 \leq u(t) \leq \bar{u}(t) \quad \text{for a.e } x \in \mathbb{R}^N, \quad 0 < t < T.$$

We check that $u(t)$ satisfies the conditions in Definition 1.1. Since \bar{u} satisfies Definition 1.1 (a)–(c), by (F2) and (2.2) we see that u also satisfies (a)–(c). Since $u = \mathcal{F}(u)$, u satisfies (d). By (F2) and (2.2) we obtain

$$\begin{aligned} \|u(t) - S_\alpha(t)u_0\|_r &= \left\| \int_0^t P_\alpha(t-s) f_0(\cdot, s, u(\cdot, s)) ds \right\|_r \\ &\leq \left\| \int_0^t P_\alpha(t-s) f_0(\cdot, s, \bar{u}(\cdot, s)) ds \right\|_r. \end{aligned}$$

Since \bar{u} satisfies (e'), we have

$$\|u(t) - S_\alpha(t)u_0\|_r \rightarrow 0 \quad \text{as } t \rightarrow 0,$$

and hence (e) holds. Thus, u satisfies Definition 1.1 (a)–(e), and hence u is a solution of (2.1). \square

Theorem 2.3. *Suppose that $f_0(x, t, \xi)$ satisfies (F2). Suppose that there exists a function $f_1(x, t, \xi)$ such that f_1 satisfies (1.4) and (1.5) with*

$$p \in [1, \infty), \quad q_1 \in [1, \infty] \cap \left(\frac{N}{2}, \infty\right], \quad q_2 \in \left(\frac{1}{\alpha}, \infty\right]$$

and

$$(2.3) \quad f_0(x, t, \xi) \leq f_1(x, t, \xi) \quad \text{for } x \in \Omega, \quad t \geq 0 \quad \text{and } \xi \geq 0.$$

Then, for each nonnegative initial function $u_0 \in L^r(\Omega)$, (2.1) has a nonnegative local-in-time solution if one of the following holds:

(i) $p \in (1, \infty)$, $r \in (1, \infty)$ and

$$(2.4) \quad \frac{N}{2q_1} + \frac{1}{\alpha q_2} + \frac{(p-1)N}{2r} \leq 1.$$

(ii) $p \in [1, \infty)$, $r \in [1, \infty)$ and

$$\frac{N}{2q_1} + \frac{1}{\alpha q_2} + \frac{(p-1)N}{2r} < 1.$$

Proof. Since all the assumptions in [10, Theorem 3.1.4] are satisfied in both of the above cases (i) and (ii), it follows from [10, Theorem 3.1.4] that the problem

$$(2.5) \quad \begin{cases} \partial_t^\alpha u = \Delta u + f_1(x, t, u), & x \in \Omega, \quad 0 < t < T, \\ u = 0, & x \in \partial\Omega, \quad 0 < t < T, \\ u(x, 0) = u_0(x), & x \in \Omega \end{cases}$$

has a local-in-time solution, which is denoted by $\bar{u}(t)$, in the sense of Definition 1.1. By (F2) and (2.3) we see that $f_1(x, t, \xi) \geq 0$ for $\xi \geq 0$. Since $u_0 \geq 0$, it is clear from Definition 1.1 (d) that the solution $\bar{u}(t)$ is nonnegative. We show that \bar{u} is a supersolution of (2.1). Since \bar{u} is a solution of (2.5), it is clear

that \bar{u} satisfies Definition 1.1 (a)–(c) with f_0 . Because of (2.3), (d') clearly holds. Using the equivalence of (e) and (1.7), we have

$$\begin{aligned} \left\| \int_0^t P_\alpha(t-s) f_0(\cdot, s, \bar{u}(\cdot, s)) ds \right\|_r &\leq \left\| \int_0^t P_\alpha(t-s) f_1(\cdot, s, \bar{u}(\cdot, s)) ds \right\|_r \\ &= \|\bar{u}(t) - S_\alpha(t)u_0\|_r \rightarrow 0. \end{aligned}$$

Therefore, (e') holds, and hence \bar{u} is a supersolution. Since $\bar{u}(t)$ is a supersolution of (2.1), by Proposition 2.2 we see that (2.1) has a nonnegative solution. \square

Theorem 2.4. *Suppose that $f \in C(\mathbb{R})$ is nonnegative and nondecreasing. Then, for each nonnegative initial function $u_0 \in L^r(\Omega)$, (1.1) has a nonnegative local-in-time solution if one of the following holds:*

(i) $1 < r < \infty$ and

$$(2.6) \quad \limsup_{s \rightarrow \infty} \frac{f(s)}{s^{1+2r/N}} < \infty.$$

(ii) $r = 1$ and there exists $p \in (0, 1 + 2r/N)$ such that

$$\limsup_{s \rightarrow \infty} \frac{f(s)}{s^p} < \infty.$$

Proof. First, we prove the case (i). Let $p = 1 + 2r/N$. We define $f_0(x, t, \xi) = f(u)$. Because of (2.6), there exists $A > 0$ such that $f(\xi) \leq A(1 + |\xi|^p)$ for $\xi \geq 0$. We define $f_1(x, t, \xi) = A(1 + |\xi|^p)$. It is clear that $f_1(x, t, \xi)$, which is defined on $\Omega \times [0, \infty) \times \mathbb{R}$, satisfies (1.4) and (1.5). Because f_1 does not depend on (x, t) , $c(x, t)$'s in (1.4) and (1.5) are constants, and hence $q_1 = \infty$ and $q_2 = \infty$. Then, p, q_1, q_2, r satisfy all assumptions in Theorem 2.3 (i), including (2.4). Then, (2.1) has a nonnegative local-in-time solution for every nonnegative initial $u_0 \in L^r(\Omega)$. The proof of the case (i) is complete.

Using Theorem 2.3 (ii), one can prove the case (ii) in a similar way. We omit the details. The proof of the theorem is complete. \square

In Section 3 we show that Theorem 2.4 holds for $r = 1$ and $p = 1 + 2/N$.

3. EXISTENCE OF A SOLUTION IN $L^1(\Omega)$

We recall the following estimates on $S_\alpha(t)$ and $P_\alpha(t)$.

Proposition 3.1. (i) *Let $N \geq 1$ and $1 \leq p \leq q \leq \infty$. Then, for each $\phi \in L^p(\Omega)$,*

$$\|S(t)\phi\|_q \leq t^{-\frac{N}{2}(\frac{1}{p}-\frac{1}{q})} \|\phi\|_p \quad \text{for } t > 0.$$

(ii) *Let $N \geq 1$ and $1 \leq p < q \leq \infty$. Then, for each $C_* > 0$ and $\phi \in L^p(\Omega)$, there is $t_0 = t_0(C_*, \phi_0)$ such that*

$$\|S(t)\phi\|_q \leq C_* t^{-\frac{N}{2}(\frac{1}{p}-\frac{1}{q})} \quad \text{for } 0 < t < t_0.$$

The multiplicative constant in (i) can be taken to be 1 (see [5, Lemma 7]). The constant C_* in (ii) can be taken arbitrarily small. The proof of Proposition 3.1 (ii) can be found in [5, Lemma 8].

Proposition 3.2. (see [10, Lemma 2.2.2])

Let $N \geq 1$ and $1 \leq p \leq q \leq \infty$. Then the following hold:

(i) If $\frac{N}{2} \left(\frac{1}{p} - \frac{1}{q} \right) < 1$, then there exists $C > 0$ such that, for each $\phi \in L^p(\Omega)$,

$$\|S_\alpha(t)\phi\|_q \leq Ct^{-\frac{N\alpha}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} \|\phi\|_p \quad \text{for } t > 0.$$

(ii) If $\frac{N}{2} \left(\frac{1}{p} - \frac{1}{q} \right) < 2$, then there exists $C > 0$ such that, for each $\phi \in L^p(\Omega)$,

$$\|t^{1-\alpha}P_\alpha(t)\phi\|_q \leq Ct^{-\frac{N\alpha}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} \|\phi\|_p \quad \text{for } t > 0.$$

A similar result to Proposition 3.2 (ii) holds for $S_\alpha(t)$.

Lemma 3.3. Let $N \geq 1$ and $1 \leq p < q \leq \infty$ such that $\frac{N}{2} \left(\frac{1}{p} - \frac{1}{q} \right) < 1$. Then, for each $C_* > 0$ and $\phi \in L^p(\Omega)$, there is $t_0 = t_0(C_*, \phi)$ such that

$$\|S_\alpha(t)\phi\|_q \leq C_*t^{-\frac{N\alpha}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} \quad \text{for } 0 < t < t_0.$$

We can take an arbitrarily small $C_* > 0$.

Proof. Let $\varepsilon > 0$ be fixed. By Proposition 3.1 (ii) we see that there is $t_1 > 0$ such that

$$\|S(t)\phi\|_q \leq \varepsilon t^{-\frac{N}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} \quad \text{for } 0 < t < t_1.$$

Then, if $0 < \tau t^\alpha < t_1$, then

$$\|S(\tau t^\alpha)\phi\|_q \leq \varepsilon \tau^{-\frac{N}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} t^{-\frac{N\alpha}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} \quad \text{for } 0 < \tau t^\alpha < t_1,$$

and hence

$$\begin{aligned} \int_0^{t_1 t^{-\alpha}} \Phi_\alpha(\tau) \|S(\tau t^\alpha)\phi\|_q d\tau &\leq \varepsilon t^{-\frac{N\alpha}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} \int_0^{t_1 t^{-\alpha}} \Phi_\alpha(\tau) \tau^{-\frac{N}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} d\tau \\ (3.1) \qquad \qquad \qquad &\leq \varepsilon t^{-\frac{N\alpha}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} \frac{\Gamma\left(1 - \frac{N}{2}\left(\frac{1}{p} - \frac{1}{q}\right)\right)}{\Gamma\left(1 - \frac{N\alpha}{2}\left(\frac{1}{p} - \frac{1}{q}\right)\right)}. \end{aligned}$$

Note that (3.1) holds for all $t > 0$. On the other hand, there is $t_2 > 0$ such that if $0 < t < t_2$, then

$$\begin{aligned} \int_{t_1 t^{-\alpha}}^\infty \Phi_\alpha(\tau) \|S(\tau t^\alpha)\phi\|_q d\tau &\leq \|\phi\|_p t^{-\frac{N\alpha}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} \int_{t_1 t^{-\alpha}}^\infty \Phi_\alpha(\tau) \tau^{-\frac{N}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} d\tau \\ (3.2) \qquad \qquad \qquad &\leq \varepsilon t^{-\frac{N\alpha}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} \|\phi\|_p, \end{aligned}$$

since

$$\int_0^\infty \Phi_\alpha(\tau) \tau^{-\frac{N}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} d\tau < \infty.$$

By (3.1) and (3.2) we have

$$\|S_\alpha(t)\phi\|_q \leq \varepsilon C_1 t^{-\frac{N\alpha}{2}\left(\frac{1}{p}-\frac{1}{q}\right)} \quad \text{for all } 0 < t < t_1,$$

where

$$C_1 = \frac{\Gamma\left(1 - \frac{N}{2}\left(\frac{1}{p} - \frac{1}{q}\right)\right)}{\Gamma\left(1 - \frac{N\alpha}{2}\left(\frac{1}{p} - \frac{1}{q}\right)\right)} + \|\phi\|_p.$$

We can take an arbitrarily small $\varepsilon > 0$ if $t_1 > 0$ is small enough. Therefore, we can take $\varepsilon > 0$ such that $C_* = C_1\varepsilon$, and hence the conclusion holds. \square

Proof of Theorem 1.4. Let

$$(3.3) \quad E = L^\infty((0, T), L^1(\Omega)) \cap \left\{ u \in L^\infty_{\text{loc}}((0, T), L^p(\Omega)); t^\beta u \in L^\infty((0, T), L^p(\Omega)) \right\},$$

where $\beta = \frac{N\alpha}{2} \left(1 - \frac{1}{p}\right) = \frac{\alpha}{p} < 1$ and T will be determined later.

We define the metric $d : E \times E \rightarrow [0, \infty)$ by

$$(3.4) \quad d(u, v) = \sup_{0 < t < T} t^\beta \|u(t) - v(t)\|_p \quad \text{for all } u, v \in E.$$

Let $M \geq \|u_0\|_1$ and

$$K = \left\{ u \in E : \|u(t)\|_1 \leq C_1 M + 1 \text{ and } t^\beta \|u(t)\|_p \leq \delta \text{ for } 0 < t < T \right\},$$

where $C_1 > 0$ and $\delta > 0$ are chosen later. Then, (K, d) is a nonempty complete metric space. We define $\mathcal{F} : K \rightarrow E$ by

$$(3.5) \quad \mathcal{F}(u)(t) = S_\alpha(t)u_0 + \int_0^t P_\alpha(t-s)f(u(s))ds \quad \text{for all } t \geq 0.$$

Because of (F1), the following holds:

$$(3.6) \quad \text{There exists } C > 0 \text{ such that } |f(\xi)| \leq C(1 + |\xi|^p) \text{ for } \xi \in \mathbb{R}.$$

By (3.6) it follows that

$$(3.7) \quad \|f(u(s))\|_1 \leq C(1 + \|u(s)\|_p^p).$$

Using the estimate (3.7) together with Proposition 3.2(ii) (for $p = q = 1$) we have

$$(3.8) \quad \begin{aligned} \|\mathcal{F}(u)(t)\|_1 &\leq C_1 \|u_0\|_1 + C_2 \int_0^t (t-s)^{-1+\alpha} \left(1 + \|u(s)\|_p^p\right) ds \\ &\leq C_1 \|u_0\|_1 + \frac{C_2}{\alpha} t^\alpha + C_2 \int_0^t (t-s)^{-1+\alpha} s^{-\alpha} \left(s^\beta \|u(s)\|_p\right)^p ds \\ &\leq C_1 \|u_0\|_1 + \frac{C_2}{\alpha} t^\alpha + C_2 \left(\sup_{0 < t < T} t^\beta \|u(t)\|_p\right)^p \int_0^1 (1-\tau)^{-1+\alpha} \tau^{-\alpha} d\tau \\ &\leq C_1 \|u_0\|_1 + \frac{C_2}{\alpha} t^\alpha + C'_2 \delta^p. \end{aligned}$$

Here, we used $p\beta = \alpha$ and the fact that with the change of variable $s = \tau t$ one has

$$\int_0^t (t-s)^{-1+\alpha} s^{-\alpha} ds = \int_0^1 (1-\tau)^{-1+\alpha} \tau^{-\alpha} d\tau < \infty.$$

Therefore,

$$(3.9) \quad \|\mathcal{F}(u)(t)\|_1 < C_1 M + 1$$

if

$$(3.10) \quad C'_2 \delta^p < \frac{1}{2}$$

and

$$(3.11) \quad C_1 \alpha^{-1} T^\alpha < \frac{1}{2}.$$

Next, by Proposition 3.2(ii) (with $q = 1$) and (3.7) we have

$$\begin{aligned}
(3.12) \quad t^\beta \|\mathcal{F}(u)(t)\|_p &\leq \sup_{0 < t < T} t^\beta \|S_\alpha(t)u_0\|_p + C_3 t^\beta \int_0^t (t-s)^{-1+\alpha-\beta} \left(1 + \|u(s)\|_p^p\right) ds \\
&\leq \sup_{0 < t < T} t^\beta \|S_\alpha(t)u_0\|_p + \frac{C_3}{\alpha - \beta} t^\alpha \\
&\quad + C_3 t^\beta \left(\sup_{0 < t < T} t^\beta \|u(t)\|_p \right)^p \int_0^t (t-s)^{-1+\alpha-\beta} s^{-p\beta} ds \\
&\leq \sup_{0 < t < T} t^\beta \|S_\alpha(t)u_0\|_p + \frac{C_3}{\alpha - \beta} t^\alpha + C_3 \delta^p \int_0^1 (1-\tau)^{-1+\alpha-\beta} \tau^{-\alpha} d\tau \\
&\leq \sup_{0 < t < T} t^\beta \|S_\alpha(t)u_0\|_p + \frac{C_3}{\alpha - \beta} t^\alpha + C'_3 \delta^p.
\end{aligned}$$

In the above sequence of estimates we used the change of variable $s = \tau t$ so that

$$\int_0^t (t-s)^{-1+\alpha-\beta} s^{-p\beta} ds = t^{-\beta} \int_0^1 (1-\tau)^{-1+\alpha-\beta} \tau^{-\alpha} d\tau \leq Ct^{-\beta}.$$

Therefore,

$$(3.13) \quad \sup_{0 < t < T} t^\beta \|\mathcal{F}(u)(t)\|_p \leq \sup_{0 < t < T} t^\beta \|S_\alpha(t)u_0\|_p + \frac{\delta}{2}$$

if

$$(3.14) \quad C'_3 \delta^{p-1} < \frac{1}{4}$$

and

$$(3.15) \quad \frac{C_3}{\alpha - \beta} T^\alpha < \frac{\delta}{4}.$$

Since

$$\begin{aligned}
\int_\Omega |f(u(s)) - f(v(s))| dx &\leq C_4 \int_\Omega (1 + |u(s)| + |v(s)|)^{p-1} |u(s) - v(s)| dx \\
&\leq C'_4 \int_\Omega (1 + |u(s)|^{p-1} + |v(s)|^{p-1}) |u(s) - v(s)| dx \\
&\leq C''_4 \|u(s) - v(s)\|_p \\
&\quad + C'_4 \left(\|u(s)\|_p^{p-1} + \|v(s)\|_p^{p-1} \right) \|u(s) - v(s)\|_p,
\end{aligned}$$

we have

$$\begin{aligned}
(3.16) \quad t^\beta \|\mathcal{F}(u)(t) - \mathcal{F}(v)(t)\|_p &\leq C_3 t^\beta \int_0^t (t-s)^{-1+\alpha-\beta} \|f(u(s)) - f(v(s))\|_1 ds \\
&\leq C_3 t^\beta \left(C''_4 \int_0^t (t-s)^{-1+\alpha-\beta} s^{-\beta} ds \right. \\
&\quad \left. + 2\delta^{p-1} C'_4 \int_0^t (t-s)^{-1+\alpha-\beta} s^{-p\beta} ds \right) \sup_{0 < t < T} t^\beta \|u(t) - v(t)\|_p \\
&\leq C_3 \left(C''_4 C_5 t^{\alpha-\beta} + 2C'_4 C_6 \delta^{p-1} \right) \sup_{0 < t < T} t^\beta \|u(t) - v(t)\|_p,
\end{aligned}$$

where

$$C_5 = \int_0^1 (1-\tau)^{-1+\alpha-\beta} \tau^{-\beta} d\tau \quad \text{and} \quad C_6 = \int_0^1 (1-\tau)^{-1+\alpha-\beta} \tau^{-\alpha} d\tau.$$

Therefore,

$$(3.17) \quad \sup_{0 < t < T} t^\beta \|\mathcal{F}(u)(t) - \mathcal{F}(v)(t)\|_p \leq \frac{1}{2} d(u, v)$$

if

$$(3.18) \quad 2C_3 C_4' C_6 \delta^{p-1} < \frac{1}{4}$$

and

$$(3.19) \quad C_3 C_4'' C_5 T^{\alpha-\beta} < \frac{1}{4}.$$

We fix any small $\delta > 0$ such that (3.18), (3.14) and (3.10) hold. Because of Lemma 3.3, we can choose $T > 0$ such that (3.19), (3.15) and (3.11) hold and

$$(3.20) \quad \sup_{0 < t < T} t^\beta \|S_\alpha(t)u_0\|_p \leq \frac{\delta}{2}.$$

Then, by (3.20), (3.13) and (3.9) we see that $\mathcal{F} : K \rightarrow K$. Moreover, it follows from (3.17) that \mathcal{F} is a contraction mapping on K . Thus, $\mathcal{F} : K \rightarrow K$ has a unique fixed point in K which is denoted by $u(t)$.

We check that $u(t)$ satisfies Definition 1.1 (a)–(e). Since $u(t) \in K$, (a) holds. Since $t^\beta \|u(t)\|_p \leq \delta$ and $p\beta = \alpha$, by (3.6) we have

$$(3.21) \quad \|f(u(t))\|_1 \leq C(1 + \|u(t)\|_p^p) \leq C(1 + \delta t^{-\alpha}) < \infty \quad \text{for } 0 < t < T.$$

Thus, (b) holds. Let $t \in (0, T)$. Integrating (3.21) over $(0, t)$, we see that (c) holds. We can easily check that $\int_0^t \|P_\alpha(t-s)f(u(s))\|_1 ds < \infty$ for $0 < t < T$ which indicates that $u(t) \in C((0, T), L^1(\Omega))$. Therefore, $u(t) = \mathcal{F}(u)(t)$ for a.e. $x \in \Omega$ and $0 < t < T$. Hence, (d) holds. As in (3.8) we have

$$\|u(t) - S_\alpha(t)u_0\|_1 \leq C_1 \alpha^{-1} t^\alpha + C_2' \delta^p.$$

Since $\delta > 0$ and $t > 0$ can be chosen arbitrarily small, by the local uniqueness of the fixed point we have

$$\|u(t) - S_\alpha(t)u_0\|_1 \rightarrow 0,$$

which indicates that (e) holds. Thus, $u(t)$ is a solution of (1.1) in the sense of Definition 1.1. \square

Corollary 3.4. *Suppose that $f \in C(\mathbb{R})$ is nonnegative and nondecreasing. Then, for each nonnegative initial function $u_0 \in L^1(\Omega)$, (1.1) has a nonnegative solution if*

$$(3.22) \quad \limsup_{s \rightarrow \infty} \frac{f(s)}{s^{1+2/N}} < \infty.$$

Proof. The proof is similar to that of Theorem 2.4. Let $p = 1 + 2/N$. Because of (3.22), there is $C > 0$ such that $f(\xi) \leq C(1 + \xi^p)$ for $\xi \geq 0$. Let $f_1(\xi) = C(1 + |\xi|^p)$. Then it follows from Theorem 1.4 that (1.1) with f_1 has a nonnegative solution \bar{u} for each nonnegative initial data $u_0 \in L^1(\Omega)$. By Proposition 2.2 we

can construct a nonnegative solution for (1.1) with f , since \bar{u} is a supersolution for (1.1). The details are omitted. \square

4. GLOBAL-IN-TIME SOLUTION IN $L^1(\Omega)$

Proof of Theorem 1.5. We follow a similar strategy to that in the proof of Theorem 1.4. Let E (resp. d) be defined by (3.3) with $T = \infty$ (resp. by (3.4) with $T = \infty$). Here, $\beta = \frac{N\alpha}{2} \left(1 - \frac{1}{p}\right) = \frac{\alpha}{p} < 1$. We define K by

$$K = \left\{ u \in E; \sup_{t>0} \|u(t)\|_1 + \sup_{t>0} t^\beta \|u(t)\|_p \leq \delta \right\},$$

where $\delta > 0$ is determined later. Then, (K, d) is a nonempty complete metric space. We define \mathcal{F} by (3.5). Hereafter we assume that $\|u_0\|_1 \leq \varepsilon$. By (F1') we see that there is $C > 0$ such that $|f(u)| \leq C|u|^p$. By a calculation similar to (3.8) we have

$$\|\mathcal{F}(u)(t)\|_1 \leq C_1 \|u_0\| + C'_2 \delta^p.$$

Therefore,

$$(4.1) \quad \|\mathcal{F}(u)(t)\|_1 \leq \delta$$

if

$$(4.2) \quad C_1 \varepsilon \leq \frac{\delta}{2}$$

and

$$(4.3) \quad C'_2 \delta^{p-1} \leq \frac{1}{2}.$$

By a calculation similar to (3.12) we have

$$t^\beta \|\mathcal{F}(u)(t)\|_p \leq \sup_{t>0} t^\beta \|S_\alpha(t)u_0\|_p + C'_3 \delta^p.$$

Therefore,

$$(4.4) \quad \sup_{t>0} t^\beta \|\mathcal{F}(u)(t)\|_p \leq \sup_{t>0} t^\beta \|S_\alpha(t)u_0\|_p + \frac{\delta}{2}$$

if

$$(4.5) \quad C'_3 \delta^{p-1} \leq \frac{1}{2}.$$

By a calculation similar to (3.16) we have

$$t^\beta \|\mathcal{F}(u)(t) - \mathcal{F}(v)(t)\|_p \leq 2C_3 C'_4 C_6 \delta^{p-1} \sup_{t>0} t^\beta \|u(t) - v(t)\|_p.$$

Here we used (F1'), and hence the term $C_3 C'_4 C_5 t^{\alpha-\beta}$ in (3.16) does not appear. Therefore,

$$(4.6) \quad \sup_{t>0} t^\beta \|\mathcal{F}(u)(t) - \mathcal{F}(v)(t)\|_p \leq \frac{1}{2} d(u, v)$$

if

$$(4.7) \quad 2C_3 C'_4 C_6 \delta^{p-1} \leq \frac{1}{2}.$$

We fix $\delta > 0$ such that (4.7), (4.5) and (4.3) hold. By Proposition 3.2 (i) we see that

$$(4.8) \quad \sup_{t>0} t^\beta \|S_\alpha(t)u_0\|_p \leq C\varepsilon.$$

We can choose $\varepsilon > 0$ such that $C\varepsilon \leq \frac{\delta}{2}$ and (4.2) holds. Then, it follows from (4.8) and (4.4) that

$$(4.9) \quad \sup_{t>0} t^\beta \|\mathcal{F}(u)(t)\|_p \leq \delta.$$

By (4.9) and (4.1) we see that $\mathcal{F} : K \rightarrow K$. Moreover, by (4.6) we see that \mathcal{F} is a contraction mapping on K . Thus, $\mathcal{F} : K \rightarrow K$ has a unique fixed point in K which is denoted by $u(t)$.

We can check that $u(t)$ satisfies Definition 1.1 (a)–(e) with $T = \infty$ in the same way as in the proof of Theorem 1.4. We omit details.

The existence of a nontrivial nonnegative solution with small nonnegative initial function easily follows from a nonnegativity of a solution with nontrivial nonnegative initial function.

The proof is complete. \square

Corollary 4.1. *Suppose that $f \in C(\mathbb{R})$ is nonnegative and nondecreasing. If*

$$(4.10) \quad \sup_{t>0} \frac{f(s)}{s^{1+2/N}} < \infty,$$

then there is $\varepsilon > 0$ such that for each nonnegative initial function $u_0 \in L^1(\Omega)$ with $\|u_0\|_1 \leq \varepsilon$, there exists a global-in-time solution $u(t)$ of (1.1) in the sense of Definition 1.1 with $T = \infty$.

Proof. Let $p = 1 + 2/N$. Because of (4.10), there is $C > 0$ such that $f(\xi) \leq C\xi^p$ for $\xi \geq 0$. Let $f_1(\xi) = C\xi^p$. Since f_1 satisfies (F1'), it follows from Theorem 1.5 that there is $\varepsilon > 0$ such that (1.1) with f_1 has a nonnegative global-in-time solution \bar{u} for each nonnegative initial data $u_0 \in L^1(\Omega)$ with $\|u_0\|_1 \leq \varepsilon$. By Proposition 2.2 we can construct a nonnegative global-in-time solution for (1.1) with f , since \bar{u} is a supersolution of (1.1) with $T = \infty$. The proof is complete. \square

5. NONEXISTENCE OF A SOLUTION IN $L^r(\Omega)$, $1 \leq r < \infty$

Let $G(x, y, t)$ denote the Dirichlet heat kernel on Ω . When $u_0 \in L^r(\Omega)$, we see that $S(t)u_0(x) = \int_\Omega G(x, y, t)u_0(y)dy$ and that $S(t)u_0$ gives a solution of the heat equation $\partial_t u = \Delta u$ on Ω with the Dirichlet boundary condition.

Proposition 5.1 (see e.g., [4, Corollary 2.2]). *Let $\delta > 0$ be such that $B_{2\delta} \subset \Omega$. Then,*

$$G(x, y, t) \geq c_* t^{-N/2} \text{ for all } x, y \in B_\delta \text{ and } 0 \leq t \leq \delta^2$$

such that $|x - y| \leq \sqrt{t}$. Here, c_ depends on N and δ .*

Proof of Theorem 1.3. Let $p = 1 + 2r/N$ and denote by ω_N the volume of the unit ball in \mathbb{R}^N . If c_* is the constant given in Proposition 5.1, we define

$$c_0 = \frac{c_* \omega_N}{2^N} \int_{1/4}^1 \Phi_\alpha(\tau) d\tau,$$

which depends only on c_* , N and α . By (1.8) we can choose $\{a_k\}_{k=1}^\infty$ such that

$$(5.1) \quad a_k \geq k \quad \text{and} \quad f(c_0 a_k) \geq a_k^p e^{k/r} \quad \text{for all } k \geq 1.$$

Let $\rho_k = \varepsilon a_k^{-r/N} k^{-2r/N}$. By taking $\varepsilon > 0$ small enough, we may assume $B_{3\rho_k} \subset \Omega$ for all $k \geq 1$. Let

$$u_0(x) = \sum_{k=1}^{\infty} u_k \quad \text{where} \quad u_k = a_k \chi_{\rho_k},$$

where for $\rho > 0$, χ_ρ denotes the indicator function of the ball $B_\rho \subset \mathbb{R}^N$.

Since

$$\|u_k\|_r^r = \omega_N \rho_k^N a_k^r = \omega_N \frac{\varepsilon^N}{k^{2r}},$$

we have

$$\|u_0\|_r \leq \sum_{k=1}^{\infty} \|u_k\|_r = \omega_N^{1/N} \varepsilon^{N/r} \sum_{k=1}^{\infty} \frac{1}{k^2} < \infty.$$

Suppose that (1.1) with the above defined initial data $u_0 \in L^r(\mathbb{R}^N)$ has a nonnegative solution $u(t)$ for small $t > 0$. Then,

$$u(t) = S_\alpha(t)u_0 + \int_0^t P_\alpha(t-s)f(u(s))ds.$$

Since $u \geq 0$ and $f \geq 0$, we have

$$u(t) \geq S_\alpha(t)u_0 \geq S_\alpha(t)u_k.$$

Hence, for any $k \geq 1$,

$$(5.2) \quad u(t) \geq \int_0^t P_\alpha(t-s)f(S_\alpha(s)u_k)ds,$$

since f is nondecreasing.

For $k \geq 1$, let $s > 0$ be small such that $\sqrt{s^\alpha} \leq \rho_k/2$ and $0 < \tau \leq 1$. By Proposition 5.1 applied for $t = \tau s^\alpha$ and $\delta = t^2$ one has

$$\begin{aligned} S(\tau s^\alpha)\chi_{\rho_k} &= \int_{|y| \leq \rho_k} G(x, y, \tau s^\alpha) dy \\ &\geq \chi_{\sqrt{\tau s^\alpha}/2} \int_{|x-y| \leq \sqrt{\tau s^\alpha}/2} c_*(\tau s^\alpha)^{-N/2} dy \\ &= \frac{c_* \omega_N}{2^N} \chi_{\sqrt{\tau s^\alpha}/2}. \end{aligned}$$

Hence, from (1.2) we find

$$(5.3) \quad \begin{aligned} S_\alpha(s)u_k &\geq \int_{1/4}^1 \Phi_\alpha(\tau) S(\tau s^\alpha)[a_k \chi_{\rho_k}] d\tau \\ &\geq \frac{c_* \omega_N a_k}{2^N} \int_{1/4}^1 \Phi_\alpha(\tau) \chi_{\sqrt{\tau s^\alpha}/2} d\tau \\ &\geq \frac{c_* \omega_N a_k}{2^N} \chi_{\sqrt{s^\alpha}/4} \int_{1/4}^1 \Phi_\alpha(\tau) d\tau = c_0 a_k \chi_{\sqrt{s^\alpha}/4}. \end{aligned}$$

On the other hand, if $t > 0$ is small and

$$(5.4) \quad \frac{\sqrt{\tau(t-s)^\alpha}}{2} \leq \frac{\sqrt{s^\alpha}}{8}, \quad \frac{t}{3} \leq s \leq \frac{t}{2}$$

then

$$(5.5) \quad \begin{aligned} S(\tau(t-s)^\alpha)[\chi_{\sqrt{s^\alpha}/4}] &= \int_{|y| \leq \sqrt{s^\alpha}/4} G(x, y, \tau(t-s)^\alpha) dy \\ &\geq \chi_{\sqrt{\tau(t-s)^\alpha}/2} \int_{|x-y| \leq \sqrt{\tau(t-s)^\alpha}/2} c_* \{\tau(t-s)^\alpha\}^{-N/2} dy \\ &= \frac{c_* \omega_N}{2^N} \chi_{\sqrt{\tau(t-s)^\alpha}/2} > c_0 \chi_{\sqrt{\tau(t-s)^\alpha}/2}. \end{aligned}$$

Let $\tau_0 = \frac{1}{16 \cdot 2^\alpha}$. If $\tau_0/4 \leq \tau \leq \tau_0$, then

$$\sqrt{\tau(t-s)^\alpha}/2 \leq \sqrt{s^\alpha}/8 \quad \text{for all } s, t > 0 \text{ such that } t/3 \leq s \leq t/2.$$

Since (5.4) holds for $\tau_0/4 \leq \tau \leq \tau_0$, by (5.3) and (5.5) we see that if

$$\sqrt{s^\alpha} \leq \rho_k/2, \quad t/3 \leq s \leq t/2 \quad \text{and} \quad t \geq 0 \text{ is small,}$$

then

$$\begin{aligned} P_\alpha(t-s)[f(S_\alpha(s)u_k)] &\geq P_\alpha(t-s)[f(c_0 a_k) \chi_{\sqrt{s^\alpha}/4}] \\ &\geq f(c_0 a_k) \alpha (t-s)^{\alpha-1} \int_{\tau_0/4}^{\tau_0} \tau \Phi_\alpha(\tau) S(\tau(t-s)^\alpha) [\chi_{\sqrt{s^\alpha}/4}] d\tau \\ &\geq f(c_0 a_k) \alpha (t-s)^{\alpha-1} \int_{\tau_0/4}^{\tau_0} \tau \Phi_\alpha(\tau) c_0 \chi_{\sqrt{\tau(t-s)^\alpha}/2} d\tau \\ &\geq f(c_0 a_k) \alpha (t-s)^{\alpha-1} c_0 \chi_{\sqrt{\tau(t-s)^\alpha}/4} \int_{\tau_0/4}^{\tau_0} \tau \Phi_\alpha(\tau) d\tau \\ &= c_1 f(c_0 a_k) \alpha (t-s)^{\alpha-1} \chi_{\sqrt{\tau_0(t-s)^\alpha}/4}. \end{aligned}$$

Therefore, if $t > 0$ is small and

$$(5.6) \quad \sqrt{\left(\frac{t}{2}\right)^\alpha} \leq \frac{\rho_k}{2},$$

then

$$\begin{aligned} \int_0^t P_\alpha(t-s)[f(S_\alpha(s)u_k)] ds &\geq c_1 f(c_0 a_k) \alpha \int_{t/3}^{t/2} (t-s)^{\alpha-1} \chi_{\sqrt{\tau_0(t-s)^\alpha}/4} ds \\ &\geq c_1 f(c_0 a_k) \left\{ \left(\frac{2}{3}\right)^\alpha - \left(\frac{1}{2}\right)^\alpha \right\} t^\alpha \chi_{\sqrt{\tau_0(t/2)^\alpha}/4}. \end{aligned}$$

Thus, from (5.1) and (5.2) we deduce

$$\|u(t)\|_r^r \geq c_2 f(c_0 a_k)^r t^{\alpha r} t^{N\alpha/2} \geq c_2 a_k^{rp} t^{\alpha(r+\frac{N}{2})} e^k.$$

It follows from (5.6) that $t \leq 2^{1-2/\alpha} \rho_k^{2/\alpha}$, and hence we can choose $t = 2^{1-2/\alpha} \rho_k^{2/\alpha}$. Then,

$$\|u(t)\|_r^r \geq c_3 a_k^{rp} \rho_k^{N+2r} e^k = c_4 k^{-2rp} e^k \rightarrow \infty \text{ as } k \rightarrow \infty.$$

This means that $\|u(t)\|_r^r \rightarrow \infty$ as $t \rightarrow 0$, since $t = 2^{1-2/\alpha} \rho_k^{2/\alpha} \rightarrow 0$ as $k \rightarrow \infty$. Therefore, $\|u(t) - u_0\|_r \geq \|u(t)\|_r - \|u_0\|_r \rightarrow \infty$, and hence Definition 1.1 (e) does not hold. Thus, (1.1) with the initial function u_0 has no nonnegative solution. \square

Corollary 5.2. *Let $1 \leq r < \infty$. Suppose that $f \in C[0, \infty)$ is nonnegative and nondecreasing. The problem (1.1) has a nonnegative solution for every nonnegative initial data $u_0 \in L^r(\Omega)$ if and only if*

$$\limsup_{s \rightarrow \infty} \frac{f(s)}{s^{1+2r/N}} < \infty.$$

Proof. When $1 < r < \infty$, the sufficient part follows from Theorem 2.4 (i) and the necessary part follows from Theorem 1.3 with $1 < r < \infty$. When $r = 1$, the sufficient part follows from Corollary 3.4 and the necessary part follows from Theorem 1.3 with $r = 1$. \square

6. UNIQUENESS

In this section we provide the proof of Theorem 1.6. Let $u(t)$ and $v(t)$ be two solutions of (1.1) in the class K defined for $0 < t < T_1$ and $0 < t < T_2$, respectively. Without loss of generality we assume $T_1 \leq T_2$.

$$A = \{t \in [0, T_1]; u(t) = v(t) \text{ in } L^1(\Omega)\}.$$

Since $u(0) = v(0) = u_0$, it follows that $0 \in A$, so A is nonempty. Let $U \subset [0, T_1]$ be the connected component of A that contains 0. Because of the definition, U is a closed set of $[0, T_1]$. Hereafter, we show that U is an open set. Since $[0, T_1]$ is a connected set, this yields $U = [0, T_1]$.

Suppose that $u(t) = v(t)$ in $L^1(\Omega)$ for $0 \leq t \leq T$ where $0 \leq T < T_1$. By the fact that $u(t), v(t) \in K$ there is $M > 0$ such that

$$\sup_{0 < t < T_1} t^\beta \|u(t)\|_p < M \quad \text{and} \quad \sup_{0 < t < T_2} t^\beta \|v(t)\|_p < M.$$

Let $0 < \varepsilon < T_1 - T$. With a similar calculation to (3.16), for $T \leq t \leq T + \varepsilon$ we have

$$\begin{aligned} t^\beta \|u(t) - v(t)\|_p &\leq C_3 t^\beta \int_0^t (t-s)^{-1+\alpha-\beta} \|f(u(s)) - f(v(s))\|_1 ds \\ &\leq C_3 t^\beta \int_T^{T+\varepsilon} (t-s)^{-1+\alpha-\beta} \|f(u(s)) - f(v(s))\|_1 ds \\ &\leq C_3 t^\beta \left(C_4'' \int_T^{T+\varepsilon} (t-s)^{-1+\alpha-\beta} s^{-\beta} ds \right. \\ &\quad \left. + 2M^{p-1} C_4' \int_T^{T+\varepsilon} (t-s)^{-1+\alpha-\beta} s^{-p\beta} ds \right) \sup_{T \leq t < T+\varepsilon} t^\beta \|u(t) - v(t)\|_p. \end{aligned}$$

Observe that as $\varepsilon \rightarrow 0$ we have

$$t^\beta \int_T^{T+\varepsilon} (t-s)^{-1+\alpha-\beta} s^{-\beta} ds \rightarrow 0 \quad \text{and} \quad t^\beta \int_T^{T+\varepsilon} (t-s)^{-1+\alpha-\beta} s^{-p\beta} ds \rightarrow 0.$$

Hence, from the above estimate it follows that

$$t^\beta \|u(t) - v(t)\|_p \leq o(1) \sup_{T \leq t < T+\varepsilon} t^\beta \|u(t) - v(t)\|_p \quad \text{as } \varepsilon \rightarrow 0.$$

By taking $\varepsilon > 0$ small one derives

$$\sup_{T \leq t < T+\varepsilon} t^\beta \|u(t) - v(t)\|_p \leq \frac{1}{2} \sup_{T \leq t < T+\varepsilon} t^\beta \|u(t) - v(t)\|_p.$$

so $u(t) = v(t)$ in $L^p(\Omega)$ on $[0, T + \varepsilon]$. Because of the continuous embedding $L^p(\Omega) \hookrightarrow L^1(\Omega)$, we see that $u(t) = v(t)$ in $L^1(\Omega)$ for $0 \leq t < T + \varepsilon$. Hence, U is an open set which yields $U = [0, T_1]$. This completes the proof. \square

REFERENCES

- [1] B. de Andrade, A. Carvalho, P. Carvalho-Neto and P. Marín-Rubio, *Semilinear fractional differential equations: global solutions, critical nonlinearities and comparison results*, Topol. Methods Nonlinear Anal. **45** (2015), 439–467.
- [2] B. de Andrade, G. Siracusa and A. Viana, *A nonlinear fractional diffusion equation: Well-posedness, comparison results, and blow-up*, J. Math. Analysis Appl. **505** (2022) Article No. 125524.
- [3] D.A. Benson, M.M. Meerschaert, J. Revielle, *Fractional calculus in hydrologic modeling: a numerical perspective*, Adv. Water Resour. **51** (2013) 479–497.
- [4] M. van den Berg, *Heat equation and the principle of not feeling the boundary*, Proc. Roy. Soc. Edinburgh Sect. A **112** (1989), 257–262.
- [5] H. Brezis and T. Cazenave, *A nonlinear heat equation with singular initial data*, J. Anal. Math. **68** (1996), 277–304.
- [6] F. Camilli, R. De Maio and E. Iacomini, *A Hopf-Lax formula for Hamilton-Jacobi equations with Caputo time-fractional derivative*, J. Math. Analysis Appl. **477** (2019) 1019–1032.
- [7] C. Celik and Z. Zhou, *No local L^1 solution for a nonlinear heat equation*, Comm. Partial Differential Equations **28** (2003), 1807–1831.
- [8] D.K. Durdiev, A.A. Rahmonov and Z.R. Bozorov, *A two-dimensional diffusion coefficient determination problem for the time-fractional equation*, Math. Methods Appl. Sci. **44** (2021), 10753–10761.
- [9] H. Fujita, *On the blowing up of solutions of the Cauchy problem for $u_t = \Delta u + u^{1+\alpha}$* , J. Fac. Sci. Univ. Tokyo Sect. I **13** (1966), 109–124.
- [10] C. Gal and M. Warma, *Fractional-in-time semilinear parabolic equations and applications*, *Mathématiques & Applications (Berlin)*, **84**. Springer, 2020. 184 pp. ISBN: 978-3-030-45042-7.
- [11] B. Ghanbari, *Chaotic behaviors of the prevalence of an infectious disease in a prey and predator system using fractional derivatives*, Math. Methods Appl. Sci. **44** (2021), 9998–10013.
- [12] B. Guswanto and T. Suzuki, *Existence and uniqueness of mild solutions for fractional semilinear differential equations*, Electron. J. Differential Equations 2015, No. 168, 16pp.
- [13] K. Hayakawa, *On nonexistence of global solutions of some semilinear parabolic equations*, Proc. Japan Acad. Ser. A Math. Sci. **49** (1973), 403–525.
- [14] M. Jleli, M. Kirane and B. Samet, *Solution blow-up for a fractional in time acoustic wave equation*, Math. Methods Appl. Sci. **43** (2020), 6566–6575.
- [15] M. Kirane and B. Torebek, *Maximum principle for space and time-space fractional partial differential equations*, Z. Anal. Anwend. **40** (2021), 277–301.
- [16] K. Kobayashi, T. Sirao and H. Tanaka, *On the blowing up problem for semilinear heat equations*, J. Math. Soc. Japan **29** (1977), 407–424.
- [17] R. Laister, J. Robinson, M. Sierżęga and A. Vidal-López, *A complete characterisation of local existence for semilinear heat equations in Lebesgue spaces*, Ann. Inst. H. Poincaré Anal. Non Linéaire **33** (2016), 1519–1538.
- [18] B. Li, W. Xie, *Adaptive fractional differential approach and its application to medical image enhancement*, Comput. Electr. Eng. **45** (2015) 324–335.
- [19] Y. Luchko, A. Suzuki, M. Yamamoto, *On the maximum principle for the multi-term fractional transport equation* J. Math. Analysis Appl. **505** (2022) Article No. 125579.

- [20] R.L. Magin, *Fractional Calculus in Bioengineering*, Begell House Publishers, 2006.
- [21] Y. Miyamoto, *A doubly critical semilinear heat equation in the L^1 space*, J. Evol. Equ. **21** (2021), 151–166.
- [22] J. Robinson and M. Sierżęga, *Supersolutions for a class of semilinear heat equations*, Rev. Mat. Complut. **26** (2013), 341–360.
- [23] M. Suzuki, *Local existence and nonexistence for fractional in time weakly coupled reaction-diffusion systems*, SN Partial Differential Equations and Applications **2** (2021), Article number: 2.
- [24] R. Wang, D. Chen and T. Xiao, *Abstract fractional Cauchy problems with almost sectorial operators*, J. Differential Equations **252** (2012), 202–235.
- [25] F. Weissler, *Local existence and nonexistence for semilinear parabolic equations in L^p* , Indiana Univ. Math. J. **29** (1980), 79–102.
- [26] P. Wittbold, P. Wolejko and R. Zacher, *Bounded weak solutions of time-fractional porous medium type and more general nonlinear and degenerate evolutionary integro-differential equations*, J. Math. Analysis Appl. **499** (2021) Article No. 125007.
- [27] Q. Zhang, Y. Li and M. Su, *The local and global existence of solutions for a time fractional complex Ginzburg-Landau equation*, J. Math. Analysis Appl. **469** (2019) 16–43.
- [28] Q. Zhang and H. Sun, *The blow-up and global existence of solutions of Cauchy problems for a time fractional diffusion equation*, Topol. Methods Nonlinear Anal. **46** (2015), 69–92.
- [29] Y. Zhang, H. Sun, H.H. Stowell, M. Zayernouri, S.E. Hansen, *A review of applications of fractional calculus in Earth system dynamics*, Chaos Solitons Fractals **102** (2017) 29–46.

SCHOOL OF MATHEMATICS AND STATISTICS, UNIVERSITY COLLEGE DUBLIN, BELFIELD, DUBLIN 4, IRELAND

INSTITUTE OF MATHEMATICS SIMION STOILOW OF THE ROMANIAN ACADEMY, 21 CALEA GRIVITEI ST., 010702 BUCHAREST, ROMANIA
Email address: marius.ghergu@ucd.ie

GRADUATE SCHOOL OF MATHEMATICAL SCIENCES, THE UNIVERSITY OF TOKYO, 3-8-1 KOMABA, MEGURO-KU, TOKYO 153-8914, JAPAN
Email address: miyamoto@ms.u-tokyo.ac.jp

GRADUATE SCHOOL OF MATHEMATICAL SCIENCES, THE UNIVERSITY OF TOKYO, 3-8-1 KOMABA, MEGURO-KU, TOKYO 153-8914, JAPAN
Email address: masamitu@ms.u-tokyo.ac.jp