

1 **Particle collisions control stable bed configuration**  
2 **under weak bedload transport conditions**

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6 **Key Points:**

- 7 • Experiments highlight differences in particle behavior over stable and unstable pla-  
8 nar topography.  
9 • Planar topography is unstable when particle collision events are more frequent than  
10 entrainment events.  
11 • A theoretical stability field for lower-stage plane bed topography is proposed.

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12 **Abstract**

13 Sedimentary bed configurations that are stable under weak fluid-driven transport  
 14 conditions can be divided into two groups: (1) meso-scale features that influence flow  
 15 and sediment transport through roughness and drag partitioning effects (“mesoforms”),  
 16 and (2) grain-scale features that can effectively be ignored at the macroscopic scale (“mi-  
 17 croforms”). These groups produce distinct sedimentary structures and are thought to  
 18 be separated by transition in process regime characterized by the onset of nonlinear coars-  
 19 ening associated with flow separation and scour. However, the physical mechanisms re-  
 20 sponsible for this transition are poorly understood. Previous studies suggest that inter-  
 21 actions between moving particles lead to stabilized bed disturbances that initiate non-  
 22 linear morphodynamic feedbacks. This study presents a quantitative interpretation of  
 23 this hypothesis that is tested using experimental observations of particle motion over sta-  
 24 ble and unstable quasi-planar topography. We find that the microform/mesoform tran-  
 25 sition corresponds to the transition from rarefied to congested transport quantified by  
 26 the dimensionless ratio of particle collision frequency to particle entrainment frequency.  
 27 Combined with empirical relations for bedload flux and particle travel time, theory pre-  
 28 sented herein enables prediction of bed configuration under weak bedload transport con-  
 29 ditions.

30 **1 Introduction**

31 Self-organized bedforms like ripples and dunes are essential equilibrium features  
 32 of fluid driven sediment transport. Bedform dynamics are germane to problems in ge-  
 33 omorphology, river engineering, and geology because they influence macroscopic flow and  
 34 sediment transport through roughness and drag partitioning effects (Einstein, 1950; En-  
 35 gelund & Hansen, 1967; Smith & Mclean, 1977; Fredsoe, 1982; van Rijn, 1984; Wright  
 36 & Parker, 2004; Best, 2005) and produce cross-bedded sedimentary architecture that can  
 37 be used to interpret past flow conditions (Paola & Borgman, 1991; Leclair & Bridge, 2001;  
 38 Mahon & McElroy, 2018; Leary & Ganti, 2020). They form under a wide range of con-  
 39 ditions; however, planar or quasi-planar topography is thought to be stable under weak  
 40 bedload transport conditions near the threshold of motion in sand and gravel (Leeder,  
 41 1980; Southard & Boguchwal, 1990; Van den Berg & Van Gelder, 1993; Best, 1996; Car-  
 42 ling, 1999).

43 Predicting the occurrence of planar topography under weak bedload transport con-  
 44 ditions is important from a practical standpoint because (a) grain roughness is the pri-  
 45 mary source of flow resistance (Engelund & Fredsoe, 1982), (b) sediment transport is ef-  
 46 ficient because energy is not lost to form drag (Wiberg & Smith, 1989), and (c) primary  
 47 current stratification lacks recognizable cross-bedded structures (Leeder, 1980; Baas et  
 48 al., 2016). Weak bedload transport conditions are common in rivers and are responsi-  
 49 ble for a significant fraction of fluvial stratigraphy due to quasi-universal relations gov-  
 50 erning the geometry of self-formed channels (Lacey, 1930; Schumm, 1960; S. Ikeda et al.,  
 51 1988; Dade & Friend, 1998; Eaton et al., 2004; Parker et al., 2007; Wilkerson & Parker,  
 52 2010; Métivier et al., 2017; Dunne & Jerolmack, 2018). In practice, weak bedload trans-  
 53 port conditions prevail in gravel bed rivers during floods and in sand bed rivers during  
 54 low flows.

55 Despite being a geomorphically and geologically significant phenomenon, the mech-  
 56 anisms that determine whether planar topography is stable under specific flow conditions  
 57 are poorly understood. Numerous studies describe turbulent flow and sediment trans-  
 58 port processes during the initial phase of bedform initiation (Venditti et al., 2005a; Cole-  
 59 man & Nikora, 2009, 2011, references therein); however, these typically focus on flow con-  
 60 ditions above the threshold of bedform development and neglect the mechanics of trans-  
 61 port over stable plane beds. Theoretical stability analyses predict the occurrence of pla-  
 62 nar topography when mechanisms that attenuate topographic perturbations outpace am-

63 plification at every wavelength (Engelund & Fredsoe, 1982; McLean, 1990; Charru et al.,  
 64 2013), but depend on continuum models that are incompatible with the rarefied nature  
 65 of sediment transport near the threshold of motion (Furbish et al., 2017). As a result,  
 66 they cannot capture grain-scale effects that many authors argue are an essential com-  
 67 ponent of the bedform initiation process (Bagnold, 1935; Langbein & Leopold, 1968; Costello,  
 68 1974; Coleman & Melville, 1996; Coleman & Nikora, 2009). Attempts to delineate plane-  
 69 bed stability fields empirically are hindered by overlapping observations of ripples, dunes  
 70 and a suite of small-scale features like bedload sheets (Whiting et al., 1988; Best, 1996;  
 71 Carling, 1999; Venditti et al., 2008), particle clusters (Best, 1996; Strom et al., 2004),  
 72 and low-relief bedforms (H. Ikeda, 1983; Hubbell et al., 1987; Gomez et al., 1989; Best,  
 73 1996; Carling et al., 2005) that are thought to be distinct from well-developed ripples  
 74 and dunes due to the absence of strong flow separation and scour at the point of reat-  
 75 tachment (Best, 1996; Seminara et al., 1996; Carling, 1999; Carling et al., 2005).

76 The goal of this study is to clarify the mechanisms that control the onset of rip-  
 77 ple and dune development from lower-stage plane bed (LSPB) topography under weak  
 78 bedload transport conditions (Figure 1). As a starting point, we propose a definition of  
 79 LSPB that encompasses quasi-planar “microforms” like bedload sheets, particle clusters,  
 80 and other low-amplitude bedforms. In other words, we explicitly define LSPB as a macro-  
 81 scopic description of bed configuration characterized by the absence of well-developed  
 82 ripples and dunes. We argue that this definition is appropriate because it is aligned with  
 83 the practical considerations outlined above (related to flow, sediment transport, and strati-  
 84 graphic architecture) and reflects a fundamental transition in process regime marked by  
 85 the onset of nonlinear morphodynamic coarsening.

86 To elaborate this point, consider that a precise definition of LSPB must recognize  
 87 that the the concept of planar topography breaks down at the granular scale. The ran-  
 88 dom motion of particles driven by turbulent fluid flow causes disturbances in bed ele-  
 89 vation (Leeder, 1980; Gyr & Schmid, 1989; Best, 1992) such that the minimum relief of  
 90 a mobile bed undergoing active sediment transport is several times the nominal parti-  
 91 cle diameter (Whiting & Dietrich, 1990; Clifford et al., 1992). Rather than being com-  
 92 pletely uncorrelated, these disturbances tend organize into recognizable structures due  
 93 to interactions between moving particles (i.e. “kinematic clumping”, Bagnold, 1935; Lang-  
 94 bein & Leopold, 1968; Costello, 1974; Venditti et al., 2006). In other words, particles ag-  
 95 gregate into mobile clusters through viscous-damped collisions and produce localized dis-  
 96 turbances in bed elevation when they come to rest (Coleman & Melville, 1994, 1996; Cole-  
 97 man & Eling, 2000; Coleman & Nikora, 2009, 2011). Microforms are likely an inevitable  
 98 outcome of this process (Shinbrot, 1997).

99 Organized grain-scale bed disturbances may remain stable, or they may initiate pat-  
 100 tern coarsening through nonlinear morphodynamic feedbacks. Previous studies observed  
 101 the onset of significant flow separation behind disturbances (Williams & Kemp, 1971;  
 102 Leeder, 1980; Best, 1996; Gyr & Kinzelbach, 2004) and defect propagation through scour-  
 103 deposition waves (Raudkivi, 1963, 1966; Southard & Dingler, 1971; Costello & Southard,  
 104 1981; Gyr & Schmid, 1989; Best, 1992; Venditti et al., 2005a) when bed disturbances ex-  
 105 ceed a critical height of 2-4 particle diameters (Williams & Kemp, 1971; Leeder, 1980;  
 106 Costello & Southard, 1981; Coleman & Nikora, 2009, 2011). We suggest that this thresh-  
 107 old defines a transition in process regime that suitably differentiates morphodynamically-  
 108 scaled “mesoforms” (ripples and dunes, *contra* Carling, 1999) from microforms that scale  
 109 primarily with particle diameter. Below this threshold, the bed configuration may be as-  
 110 sumed to be quasi-planar in practical applications because (a) mobile bed roughness mod-  
 111 els already include the effect of microforms (Whiting & Dietrich, 1990; Clifford et al.,  
 112 1992), (b) flow separation is poorly developed such that drag partitioning effects can be  
 113 ignored for the purposes of predicting sediment load, and (c) preserved cross-bedding  
 114 structures have a maximum thickness of several particle diameters and are likely be in-  
 115 distinguishable from planar laminations in the rock record.

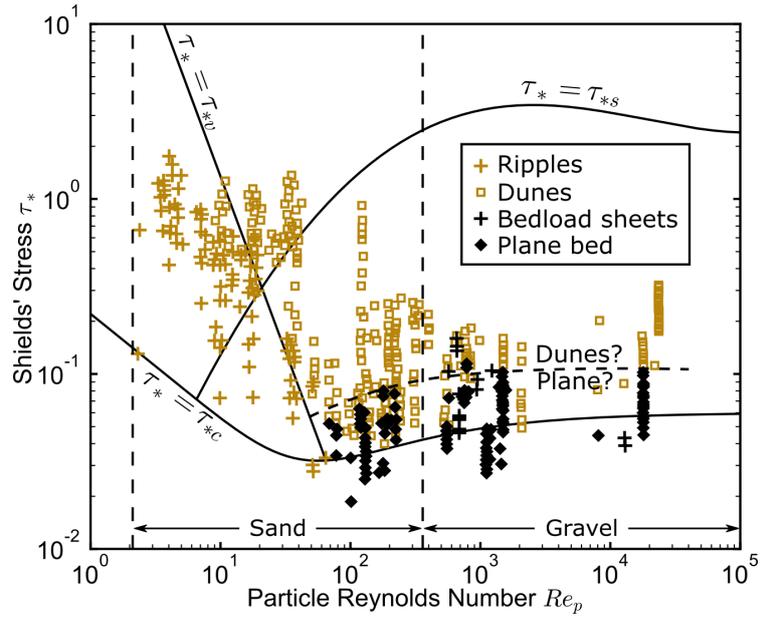
116 We hypothesize that interactions between mobile particles (“collisions”) play a crit-  
 117 ical role in determining whether microforms achieve sufficient relief to initiate morpho-  
 118 dynamic coarsening. Similar ideas have been promoted by numerous authors through-  
 119 out the history of bedform research (Bagnold, 1935; Langbein & Leopold, 1968; Costello,  
 120 1974). Most recently, a series of papers by S. E. Coleman and others (Coleman & Melville,  
 121 1994, 1996; Coleman & Eling, 2000; Coleman & Nikora, 2009, 2011) argued that bed-  
 122 form initiation occurs when interactions between clusters of mobile particles cause a bed  
 123 disturbance that interrupts the bedload layer. We present a precise kinematic interpre-  
 124 tation of this hypothesis that is tested directly using experimental observations of tracer  
 125 particle motion.

126 Topographic evolution occurs through the entrainment and disentrainment of in-  
 127 dividual sediment particles, thus, the morphodynamic importance of particle collisions  
 128 may be evaluated by comparing the particle collision frequency  $Z_g$  ( $L^{-2}T^{-1}$ ) (particle  
 129 collision events per second per unit bed area) with the particle entrainment frequency  
 130  $E_g$  ( $L^{-2}T^{-1}$ ) (particle entrainment events per second per unit bed area). The ratio  $\theta =$   
 131  $Z_g/E_g$  (henceforth, the “collision number”), characterizes the potential for particle col-  
 132 lisions to influence topographic change and may be interpreted as the average number  
 133 of particle collisions per particle transport event from entrainment to disentrainment.  
 134 Thus, we hypothesize that LSPB is stable if  $\theta < 1$ , meaning collisions are rare and most  
 135 transport events, or “hops”, involve no collisions. As a corollary, we hypothesize that bed-  
 136 form initiation occurs when  $\theta > 1$  such the collisions are frequent relative to exchanges  
 137 with the bed.

138 In order to test this hypothesis, we compare particle entrainment and collision fre-  
 139 quencies over stable and unstable planar topography. This is accomplished using dig-  
 140 itized motions of tracer particles that comprise a known fraction of the bed material. Col-  
 141 lision frequencies are estimated using using kinetic theory of gasses (Kauzmann, 2012),  
 142 which has previously been used by Sommerfeld (2001) and Oesterle and Petitjean (1993)  
 143 to describe particle collisions in turbulent flow, and by Bialik (2011) to predict collisions  
 144 among saltating particles. We find that the transition from stable to unstable planar to-  
 145 pography corresponds to the transition from rarefied to congested transport. This find-  
 146 ing leads to an explicit theoretical prediction of the LSPB stability field in terms of par-  
 147 ticle Reynolds number and Shields stress that is consistent with observations compiled  
 148 by Carling (1999).

## 149 2 Theory

150 Here, we present a simplified kinetic description of particle collisions assuming (a)  
 151 the motion of each particle is independent of other particles, (b) that the bedload layer  
 152 near the threshold of motion is thin such that particles may not move above or below  
 153 one another without interacting (reducing the problem to two spatial dimensions), and  
 154 (c) particle interactions occur when their surfaces come in contact and not before. Un-  
 155 der these assumptions, the collision frequency depends on the concentration of particles  
 156 in the bedload layer particles as well as their sizes and relative velocities (Sommerfeld,  
 157 2001). We recognize that these assumptions are not strictly valid because particle mo-  
 158 tions driven by turbulent fluid flow are not independent (Oesterle & Petitjean, 1993; Som-  
 159 merfeld, 2001), the bedload layer may be several particle diameters thick (Wiberg & Smith,  
 160 1985; Wiberg, 1987), and particles influence each other without coming into into direct  
 161 contact through viscous boundary layer and turbulent wake effects (Schmeeckle et al.,  
 162 2001; Marshall, 2011). However, a simplified theoretical approach provides a first-order  
 163 estimate of the relative importance of particle collisions. In principle, we assume that  
 164 appropriate corrections are similar in both experiments and small relative to the primary  
 165 effects considered here.



**Figure 1.** Shields-Parker river sedimentation diagram with empirical LSPB-Dune threshold (blue dashed line) adapted from García (2008). The observations of bed configuration reported by Carling (1999) are plotted for comparison. Here,  $\tau_{*v}$  is the viscous threshold Shields stress (García (2008), Equation 2-78),  $\tau_{*s}$  is the suspension threshold Shields stress (Equation 2-75), and  $\tau_{*c}$  is the critical Shields stress for sediment motion (Equation 2-59a). Observations of ripples and dunes below the plane/dune transition may be low-amplitude features that are distinct from well-developed ripples and dunes following Best (1996), Seminara et al. (1996), and Carling et al. (2005).

166 Consider two circular particles with radius  $r$  moving in a 2-dimensional plane. The  
 167 particles collide if their boundaries overlap; this occurs if their centers pass within a distance  
 168 of  $2r = D$ . Thus, a single moving particle sweeps out a rectangle with width  $2D$ ,  
 169 called the “collision cross-section”. The mean free path  $\lambda$  describes the average distance  
 170 a particle may move before colliding with another particle and is given by:

$$\lambda = \frac{1}{2D\gamma_g} \quad (1)$$

171 where  $\gamma_g$  ( $\text{L}^{-2}\text{T}^{-1}$ ) is average number of moving particles per unit bed area, referred to  
 172 here as the granular particle activity. The reciprocal of the mean free path  $2D\gamma_g$  may  
 173 be interpreted as the average number of particles contained within a unit length rect-  
 174 angle of width  $2D$ .

175 If particle motions are independent, the long-term average collision frequency for  
 176 a single particle may be estimated from the mean deviatoric speed, denoted by the short-  
 177 hand  $\tilde{u}_p = \langle \|\mathbf{u}_p - \langle \mathbf{u}_p \rangle\| \rangle$ , where  $\mathbf{u}_p$  is the instantaneous velocity vector, vertical lines  
 178 denote vector magnitude and angle brackets denote averaging over the statistical-mechanical  
 179 ensemble (Furbish et al., 2012). The mean deviatoric speed is the average speed a par-  
 180 ticle is moving relative to mean advective field. Kinetic theory predicts that an individ-  
 181 ual particle will experience an average of  $\tilde{u}_p/\lambda$  collisions per unit time.

182 Finally, the collision frequency of all particles may be estimated from the collision  
 183 frequency of a single particle. If there are  $\gamma_g$  moving particles per unit bed area, each  
 184 of which experiences  $\tilde{u}_p/\lambda$  collisions per unit time, then the average number of collisions  
 185 per unit bed area per unit time is given by:

$$Z_g = \gamma_g \frac{\tilde{u}_p}{\lambda}. \quad (2)$$

186 Thus,  $\theta$  may be estimated from parametric descriptions of particle motion as:

$$\theta = \frac{2D\tilde{u}_p\gamma_g^2}{E_g} \quad (3)$$

187 An alternative formulation can be obtained under steady, uniform macroscopic bound-  
 188 ary conditions through the following equivalence:

$$E_g = \frac{\gamma_g}{T_p}, \quad (4)$$

189 where  $T_p$  is the average particle travel time. This expression can be obtained from the  
 190 equivalent volumetric statement (Furbish et al., 2012, Equation E5) by dividing both sides  
 191 by the nominal particle volume  $V_p$  ( $\text{L}^3$ ). From (4),  $\theta$  can be rewritten as

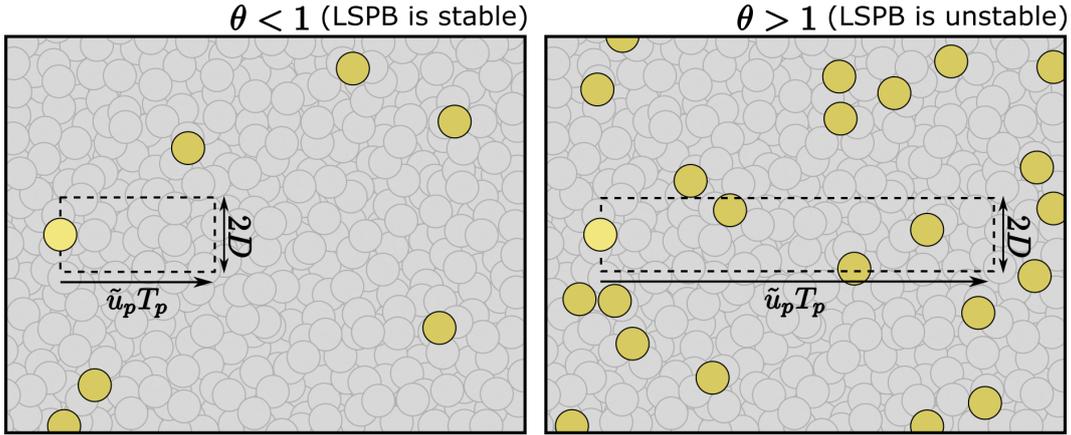
$$\theta = 2D\tilde{u}_pT_p\gamma_g = \frac{\tilde{u}_pT_p}{\lambda}. \quad (5)$$

192 A schematic interpretation of this expression is presented in Figure 2. Here, we note that  
 193  $1/\theta$  is like a Knudsen number with characteristic length  $\tilde{u}_pT_p$  (Furbish, 1997; Furbish  
 194 et al., 2017; Rapp, 2017). The Knudsen number quantifies the transition from rarefied  
 195 to congested transport, providing an alternative interpretation of our hypothesis; that  
 196 is, plane-bed topography is stable when sediment transport is rarefied at the scale of in-  
 197 dividual particle hops and becomes unstable when the bedload layer behaves like a con-  
 198 tinuum.

### 199 3 Description of Experiments

#### 200 3.1 Overview

201 Two laboratory flume experiments were conducted in order to test the hypothe-  
 202 sis presented above. Our primary objective was to measure  $\theta$  using Equation (3) under



**Figure 2.** Schematic illustrating rarefied ( $\theta < 1$ ) and congested ( $\theta > 1$ ) transport conditions. Mobile particles are shown in yellow, and immobile particles are shown in grey. A typical particle (light yellow) sweeps out a rectangle with area  $2D \times \tilde{u}_p T_p$  during its transit from entrainment to disentrainment. The collision number  $\theta$  may be interpreted as the average number of particles contained within this rectangle.

203 two conditions characterized by (a) stable and (b) unstable planar topography, for which  
 204 we expect to measure  $\theta$  values below and above 1, respectively.

205 Experiments were conducted in a 1.19 m wide, 14 m long flume capable of recir-  
 206 culating sediment and water. Flow conditions in the flume could be adjusted by vary-  
 207 ing (a) the water discharge, (b) the flume slope, and (c) the flow depth at the down-  
 208 stream end. We chose to vary flow conditions by changing the water discharge while holding the  
 209 outlet flow depth (12 cm) and flume slope (0.001) constant. This allowed for variation  
 210 in the bed stress while maintaining a constant relative submergence (the ratio of flow  
 211 depth to grain size). Although this necessarily invokes backwater hydrodynamics, the  
 212 flow may be treated as quasi-normal because the backwater length  $L_{BW} = H/S$  (which  
 213 characterizes the spatial scale over which flow conditions vary due to backwater effects)  
 214 was much longer than the length of the test reach. For our experiments, the backwater  
 215 length was approximately  $L_{BW} = O(100)$  m while the test reach was approximately  
 216 2 m.

217 In order to achieve flow conditions straddling the the threshold of bedform devel-  
 218 opment, we initially allowed topography to equilibrate to a discharge known to produce  
 219 bedload dominated bedforms (35 L/s). Then, we incrementally reduced the discharge  
 220 by 5 L/s until planar topography was observed. The bed configuration was allowed to  
 221 adjust over a period of 24 hours after each reduction in discharge. Using this procedure,  
 222 we established that plane-bed topography was stable at a water discharge of 20 L/s while  
 223 bedforms were stable at a water discharge of 25 L/s.

224 Measurements of flow velocity, bed topography, and particle motion were collected  
 225 over equilibrium LSPB topography as described in more detail below. Flow velocity was  
 226 then increased to 25 L/s and identical measurements were immediately made over un-  
 227 stable plane-bed topography. Finally, the bed configuration was allowed to equilibrate  
 228 to the increased water discharge for roughly 24 hours to verify the presumed instabil-  
 229 ity. Throughout the remainder of this paper, we refer to the stable lower-stage plane bed  
 230 condition corresponding to 20 L/s water discharge as “SPB”, and we refer to the unsta-  
 231 ble plane-bed condition corresponding to 25 L/s water discharge as “UPB”. For clarity,  
 232 we refer generally to lower-stage plane bed topography as “LSPB”.

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### 3.2 Sediment Characteristics and Flow Conditions

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The bed material was composed of polystyrene particles with a geometric mean diameter of 2.1 mm and a density of 1.055 g/cm<sup>3</sup>. The base-2 logarithmic standard deviation of the grain size distribution was 0.32 (68% of the bed material had a diameter within a factor of  $2^{0.32} = 1.24$  of the geometric mean, which is narrower than most naturally-sorted sediments. For this reason, our analyses assume a single grain size sediment equal to the geometric mean grain size. The dimensionless particle Reynolds number ( $Re_p = \sqrt{gRD^3}/\nu$ , where  $R$  is the submerged specific gravity of the sediment,  $\nu$  is the kinematic viscosity of the fluid, and  $g$  is gravitational acceleration) was approximately 70.7, which is equivalent to quartz sand ( $R = 1.65$ ) with diameter  $D = 0.68$  mm.

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Flow velocity and bed elevation profiles were measured using a Nortek Vectrino Profiler. Shear stress was computed from velocity profiles using a linear fit to the velocity profile (Bagherimiyab & Lemmin, 2013). Shear velocity at 20 L/s water discharge (SPB) computed using this procedure was 0.77 cm/s. Immediately after changing the discharge to 25 L/s (UPB), the ADV-estimated shear velocity was 0.94 cm/s. The dimensionless Shields stresses ( $\tau^* = u_*^2/gRD$ ) were 0.052 and 0.077, respectively. The critical Shield's stress for sediment motion estimated from the the formula of Brownlie (1981) is  $\tau_{*c} = 0.032$ .

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Bed elevation profiles were used to quantify variability in bed elevation characteristic of qualitatively planar topography in our experiments. Small surface undulations with slopes well below the angle of repose (maximum 3 degrees) and heights of roughly  $H = 3D$  are evident under stable and unstable plane-bed conditions. After the bed was allowed to equilibrate to the 25 L/s water discharge condition, we observed well-developed "3D" dunes (*sensu* Venditti et al., 2005b) with measured lee slopes at the angle of repose (maximum 35 degrees). Bedform height, length, and migration velocity was estimated using crest and trough picking methods from six repeat longitudinal scans covering a distance of 2 m. Measured bedforms had an average height of 2.9 cm, a length of 64 cm, and a migration velocity of 1.4 cm/minute.

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### 3.3 Particle Tracking

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Parameters describing the kinematic properties of particle motion were extracted from manually-digitized tracer particle paths. To this end, a small fraction of the bed material was removed from the flume and coated with a thin layer of fluorescent spray paint. These particles were then added back to the flume and allowed to mix with the bed material under a range of flow conditions prior to these experiments. Illuminating the bed with a blacklight increases the contrast of tracer particles relative to other particles so that individual particles can be confidently tracked over long distances. This procedure is also helpful because it reduces the amount of labor required to obtain an unbiased sample of particle motion over a large area and duration.

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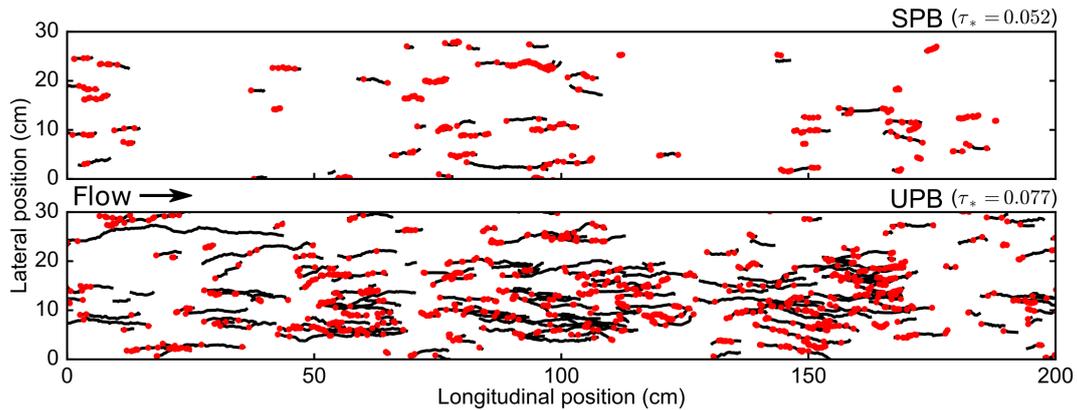
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Tracer particle motions were recorded using a downward facing digital camera attached to a fixed boom 2.05 meters above the water surface. Because the flow velocities needed to mobilize the polystyrene particles were low relative to quartz sand, particles could be tracked through the water surface with a high degree of precision. Videos were rectified and registered using OpenCV (Bradski, 2000) in Python. Manual digitization of particle motions was performed using TrackMate (Tinevez et al., 2017), an open source particle tracking package for ImageJ (Schindelin et al., 2012). In order to minimize sampling bias, all tracer particle motions that occurred within the sampling window during the specified time interval were tracked. Two ten second videos comprising a total of twenty seconds of observations from each experiment were used for this study. After registration, rectification, and trimming, both videos covered a streamwise distance of 230 cm and a cross-stream distance of 108 cm. Analyses reported here were performed using particle motions that occurred within a 30 cm wide, 2 m long control volume in the center



**Figure 3.** Tracer particle paths (black lines) and entrainment event locations (red dots) for stable lower-stage plane bed and unstable plane bed conditions. Data are from the same total duration for both experiments (20 s) such that apparent differences are representative of the relative sediment loads and entrainment frequencies.

284 of the flume in order to minimize sidewall effects. Tracked particle paths are plotted in  
 285 Figure 3.

286 Particle tracking software records particle location with an arbitrary degree of pre-  
 287 cision depending on image magnification. Thus, particles which are qualitatively iden-  
 288 tified as immobile may possess nonzero measured velocities. Furthermore, it is not al-  
 289 ways clear whether a particle should be considered mobile or immobile. As an example,  
 290 a resting particle may make several short hops at high velocities separated by only a few  
 291 frames where the velocity is near-zero; it is unclear whether these should be treated as  
 292 one or several hops. Following previous studies (e.g., Lajeunesse et al., 2010; Liu et al.,  
 293 2019; Ashley, Mahon, et al., 2020), we employed a velocity threshold criteria to distin-  
 294 guish mobile and immobile particles. Velocity thresholds provide a robust, reproducible  
 295 solution to this problem. Recognizing that the motion state of certain particles is un-  
 296 clear, we inspected motions identified using a range of velocity thresholds and found that  
 297 values between  $u_c = 0.005$  m/s to  $u_c = 0.01$  m/s differentiated between mobile and im-  
 298 mobile particles in a manner that is consistent with visual identification. Below 0.005  
 299 m/s, particles which remain in the same location for significant durations are identified  
 300 as mobile, and above 0.01 m/s, particles which are clearly in motion in the bedload phase  
 301 are identified as immobile. The exact values of certain computed quantities are sensi-  
 302 tive to the specific choice of velocity threshold within this range, however the primary  
 303 findings of this work are not. Detailed sensitivity analysis was performed using veloc-  
 304 ity thresholds ranging from 0.0001 m/s to 0.1 m/s and is discussed in detail in Section  
 305 6.2. Reported results were obtained using a velocity threshold of 0.007 m/s, which is ap-  
 306 proximately the geometric midpoint of the optimum range (0.005 m/s to 0.01 m/s).

307 In order to estimate certain bulk statistics of sediment transport from tracer parti-  
 308 cle statistics, it was necessary to estimate the tracer fraction in the flume. This was  
 309 accomplished by collecting a sample of the bed material from three locations dispersed  
 310 across the bed after the experimental campaign was complete. The total mass of the sam-  
 311 ple was 760 g. Tracer particles were separated by hand under a blacklight and then weighed.  
 312 The total mass of tracer particles in the sample was 1.49 g. Thus, we estimate the tracer  
 313 fraction to be 0.00196.

## 4 Methods for Computing Particle Motion Statistics From Digitized Particle Paths

### 4.1 Particle Position and Velocity

The kinematic statistics of particle motion needed to estimate  $\theta$  using equation (3) were computed from digitized particle paths following Ballio et al. (2018). We consider digitized particle motions within a 2.0 m long by 0.3 m wide control volume extending from the flume bottom to the water surface are projected onto a 2 dimensional plane  $A$  (Figure 3). Each particle motion is defined by a sequence of discrete measurements of particle position on the domain of longitudinal position  $x$ , and lateral position  $y$ . The position of the  $i^{\text{th}}$  of  $m$  tracked particles in the  $j^{\text{th}}$  of  $n$  frames is expressed by the vector  $\mathbf{x}_{i,j}$  with longitudinal and lateral components  $x_{i,j}$  and  $y_{i,j}$ .

Particle velocities are computed by comparing subsequent positions of a particle. Measured velocities therefore represent temporal averages between the two measurements of particle position; however, the time between frames  $\delta t$  is sufficiently small that it may be viewed as an instantaneous velocity for the purpose of differentiating between mobile and immobile particles. The velocity vector  $\mathbf{u}_{i,j}$  with longitudinal and lateral components  $u_{i,j}$  and  $v_{i,j}$  is computed as

$$\mathbf{u}_{i,j} = \frac{\mathbf{x}_{i,j+1} - \mathbf{x}_{i,j}}{\delta t}. \quad (6)$$

### 4.2 Mean Granular Activity $\gamma_g$

We focus primarily on count-based descriptions of particle motion which pertain directly to the estimation of  $\theta$  as opposed to volumetric quantities like the volumetric activity  $\gamma$  (L) and the volumetric entrainment rate  $E$  (L/T). Count-based (granular) quantities are denoted by the subscript  $g$ .

The mean granular activity is computed by counting the number of active tracer particles in the control volume in each frame and averaging. This is accomplished using an Eulerian clipping function  $M^A$  to quantify whether the  $i^{\text{th}}$  tracer particle is within the control area  $A$  in the  $j^{\text{th}}$  frame:

$$M_{i,j}^A = \begin{cases} 1, & \text{if } \mathbf{x}_{i,j} \in A \\ 0, & \text{otherwise} \end{cases}. \quad (7)$$

Additionally, a velocity threshold  $u_c$  is used to define the state of motion of a particle quantified by the clipping function  $M^m$ :

$$M_{i,j}^m = \begin{cases} 1, & \text{if } \|\mathbf{u}_{i,j}\| \geq u_c \\ 0, & \text{otherwise} \end{cases} \quad (8)$$

where  $\|\mathbf{u}_{i,j}\|$  is the particle speed. Thus, the number of mobile tracer particles in the control volume in frame  $j$  is given by:

$$N_j^{m,A} = \sum_{i=1}^m M_{i,j}^m M_{i,j}^A. \quad (9)$$

Tracer particle positions recorded in  $n$  frames lead to  $n - 1$  measurements of velocity, and the average number of moving tracer particles within the control volume over all frames with valid velocity measurements is given by:

$$\langle N^{m,A} \rangle = \frac{1}{n-1} \sum_{j=1}^{n-1} N_j^{m,A}. \quad (10)$$

Here, angle brackets denote sample averages which we assume provide unbiased estimates of the ensemble average.

349 The granular activity is estimated by dividing  $\langle N^{m,A} \rangle$  by the tracer particle frac-  
 350 tion  $\psi$  and the control volume area:

$$\gamma_g = \frac{\langle N^{m,A} \rangle}{\psi A}. \quad (11)$$

351 Note that  $\gamma_g$  is an estimate of a mean, but angle brackets are dropped to simplify no-  
 352 tation in Section 2.

### 353 4.3 Mean Deviatoric Speed $\tilde{u}_p$

354 In order to estimate the mean deviatoric speed, it is first necessary to compute the  
 355 mean particle velocity vector. The mean velocity of moving tracer particles in the con-  
 356 trol volume is given by

$$\langle \mathbf{u}^{m,A} \rangle = \frac{1}{(n-1)\langle N^{m,a} \rangle} \sum_{i=1}^m \sum_{j=1}^n \mathbf{u}_{i,j} M_{i,j}^m M_{i,j}^A \quad (12)$$

357 where  $(n-1)\langle N^{m,a} \rangle$  is the total number of measurements of tracer particle speed that  
 358 exceed the threshold speed. The mean deviatoric speed of tracer particles is then esti-  
 359 mated as

$$\langle \tilde{u}^{m,A} \rangle = \frac{1}{(n-1)\langle N^{m,a} \rangle} \sum_{i=1}^m \sum_{j=1}^n \|\mathbf{u}_{i,j} - \langle \mathbf{u}^{m,A} \rangle\| M_{i,j}^m M_{i,j}^A \quad (13)$$

360 We assume that the average deviatoric speed of tracer particles in the control volume  
 361 is equivalent to the average deviatoric speed of all mobile particles characteristic of macro-  
 362 scopic flow conditions, that is,

$$\tilde{u}_p = \langle \tilde{u}^{m,A} \rangle. \quad (14)$$

363 Again, this quantity is an estimate of a mean; however, angle brackets are dropped to  
 364 simplify notation in Section 2.

365 The mean longitudinal particle velocity  $u_x$  can be estimated by substituting  $u_{i,j}$   
 366 for  $\mathbf{u}_{i,j}$  in equation (12). Once the granular activity  $\gamma_g$  and mean longitudinal velocity  
 367  $u_x$  are known, the ensemble average granular particle flux characteristic of macroscopic  
 368 flow conditions  $q_{sg}$  ( $\text{L}^{-1}\text{T}^{-1}$ ) may be estimated as  $q_{sg} = \gamma_g u_x$ .

### 369 4.4 Granular Entrainment Frequency $E_g$

370 The final relevant quantity that must be estimated to compute  $\theta$  with equation (3)  
 371 is the entrainment frequency  $E_g$ . Entrainment and disentrainment events are defined as  
 372 transitions between the mobile and immobile states and are quantified by differentiat-  
 373 ing  $M^m$  with respect to time (Ballio et al., 2018). Presently, we define an entrainment  
 374 function  $M^E$  as

$$M_{i,j}^E = M_{i,j}^m - M_{i,j-1}^m. \quad (15)$$

375 This function may take on values of 1, 0, or  $-1$ , signifying an entrainment event, no event,  
 376 or a disentrainment event. Assuming the spatially-averaged time rate of change of bed  
 377 elevation is zero within and around the control volume, the entrainment frequency  $E_g$   
 378 and the disentrainment frequency  $D_g$  must be equal. Consequently, the spatially aver-  
 379 aged entrainment and disentrainment frequencies can be estimated from the absolute value  
 380 of  $M^E$  as

$$E_g = D_g = \frac{1}{(n-2)\delta t} \sum_{i=1}^m \sum_{j=2}^{n-1} \frac{1}{2} |M_{i,j}^E| M_{i,j}^A. \quad (16)$$

381 Here,  $(n-2)\delta t$  is the total time over which it is possible to detect entrainment events  
 382 occurring in  $n$  frames.

**Table 1.** Summary of Experiments

	SPB	UPB
Boundary Conditions		
Geometric mean particle diameter $D$	2.1 mm	2.1 mm
Sediment density $\rho_s$	1.055 g/cm <sup>3</sup>	1.055 g/cm <sup>3</sup>
Particle Reynolds Number $Re_p$	70.7	70.7
Unit water discharge $q_w$	0.016 m <sup>2</sup> /s	0.021 m <sup>2</sup> /s
Flow depth in test area $h$	0.11 m	0.11 m
ADV Shear velocity $u_*$	0.0077 m/s	0.0094 m/s
Shields stress $\tau_*$	0.052	0.077
Results		
Granular activity $\gamma_g$	3800 m <sup>-2</sup>	20,300 m <sup>-2</sup>
Mean deviatoric speed $\tilde{u}_p$	3.6 cm/s	4.1 cm/s
Mean longitudinal velocity $u_x$	2.8 cm/s	3.3 cm/s
Entrainment frequency $E_g$	15400 m <sup>-2</sup> s <sup>-1</sup>	43300 m <sup>-2</sup> s <sup>-1</sup>
Mean travel time $\tau$	0.25 s	0.47 s
Granular sediment flux $q_{sg}$	106 m <sup>-1</sup> s <sup>-1</sup>	668 m <sup>-1</sup> s <sup>-1</sup>
Volumetric sediment flux $q_s$	$5.15 \times 10^{-7}$ m <sup>2</sup> /s	$3.24 \times 10^{-6}$ m <sup>2</sup> /s
Einstein bedload number $q_*$	0.0073	0.046
Mean free path $\lambda$	6.3 cm	1.2 cm
Characteristic transport length $\tilde{u}_p\tau$	0.9 cm	1.9 cm
Collision number $\theta$	<b>0.14</b>	<b>1.65</b>

## 5 Results

For the SPB condition, the experimental procedure described above yielded a total of 2685 measurements of particle speed in excess of the threshold speed in the control volume belonging to 65 unique particles (Figure 3). The entrainment function (equation 15) was used to identify a total of 725 tracer particle exchanges with the bed (entrainment and disentrainment events). The ensemble average tracer particle flux was 0.21 particles per second per meter width. This leads to a total granular flux  $q_{sg} = 106$  particles per second per meter width and a dimensionless bedload flux  $q_* = q_g V_p / \sqrt{RgD^3}$  of 0.0073. Solving the Wong and Parker (2006) bedload equation for shear velocity using the critical Shields stress predicted from Brownlie (1981) leads to  $u_* = 0.0073$  m/s compared with 0.0077 m/s estimated using acoustics.

For the UPB condition, experiments produced 14309 measurements of mobile particles in the control volume belonging to 231 unique particles (Figure 3). The entrainment function identified 2032 exchanges with the bed. The ensemble average tracer particle flux was 1.3 particles per second per meter width leading to a total granular flux of  $q_{sg} = 668$  particles per second per meter width and a dimensionless bedload number of  $q_* = 0.045$ . The shear velocity estimated from  $q_*$  was  $u_* = 0.0097$  m/s compared with 0.0094 m/s estimated using acoustics.

Experimental results are reported in Table 5. Notably, the collision number varies by over an order of magnitude between the two experiments from 0.14 to 1.65. In terms of the Knudsen number interpretation of  $\theta$ , the observed difference reflects both an increase in the characteristic length  $\tilde{u}_p\tau$  and a decrease in the mean free path  $\lambda$ .

## 6 Discussion

For the experimental conditions considered here, we find that the transition from LSPB to bedforms corresponds to the transition from rarefied to congested sediment transport conditions parameterized by the collision number  $\theta$ . Despite only a small increase in shear stress,  $\theta$  increases by over a factor of 10, from 0.14 for the SPB condition to 1.65 for the UPB condition. Our results demonstrate that a careful interpretation of observations made by previous authors (e.g., Coleman & Nikora, 2011) leads to a quantitative prediction that is consistent with measurements, supporting a hypothesized causal link between particle collisions and bedform development.

Here, we consider the theoretical implications of this finding by reexamining the arguments used to justify our hypothesis. In Section 1, we argued that well-developed ripples and dunes are distinct from microforms like bedload sheets, particle clusters, and low-amplitude ripples and dunes due to a transition in process regime and scaling. Three mechanisms are invoked to explain this transition, each of which represents a coherent synthesis of previous observations and theory. We emphasize that these mechanisms are not evaluated independently, but are considered here because they provide a mechanical explanation of our results and a starting point for future studies.

First, we suggest that microforms are an inevitable outcome of fluid driven sediment transport. This follows from the notion that quasi-random motions of particles produce grain-scale disturbances in bed elevation. The formation of grain-scale disturbances driven by turbulent fluid flow has been described by a number of authors (Williams & Kemp, 1971; Best, 1992); Whiting and Dietrich (1990) and Clifford et al. (1992) argue that the difference between fixed- and mobile- bed roughness is explained by this phenomenon. More generally, we suggest that microforms are a manifestation of inevitable self-organization of granular bed disturbances through inelastic particle collisions (Shinbrot, 1997).

Second, we suggest that microform amplitude scales with particle diameter and collision frequency. Coleman and Nikora (2009, 2011) argued that interactions between mobile clusters of particles increase the size of disturbances in bed elevation. This implies that there is a balance between disturbance growth and decay, where growth is related to particle collisions and decay is related to disturbance size, perhaps due to the fact that particles are more likely to be eroded from topographic highs and deposited in topographic lows. We suggest that the stable microform amplitude  $H_\mu$  is related to the collision number, for example as  $H_\mu/D \propto \theta$ .

Finally, we suggest that microforms are stable up to a critical amplitude, above which flow separation and scour at the point of reattachment cause nonlinear pattern coarsening. Studies that describe bedform growth from artificial or natural defects typically find that small defects are suppressed rather than amplified (Southard & Dingler, 1971; Gyr & Schmid, 1989; Gyr & Kinzelbach, 2004; Venditti et al., 2005a; Coleman & Nikora, 2009). Only when defects exceed a critical height, usually reported as a constant multiple of particle diameter ranging from 2-4, do they stabilize and propagate (Williams & Kemp, 1971; Leeder, 1980; Costello & Southard, 1981; Coleman & Nikora, 2009, 2011). This transition in process regime fundamentally distinguishes quasi-planar configurations from well-developed ripples and dunes.

### 6.1 Implications for Stability Diagrams

Here, we demonstrate that our results are consistent with empirical stability fields proposed based on observations of topographic configuration under a wide range of conditions (e.g., Van den Berg & Van Gelder, 1993; Southard & Boguchwal, 1990; Carling, 1999; García, 2008). This is accomplished by combining existing theoretical and empirical relations to obtain an expression for  $\theta$  in terms of macroscopic boundary conditions.

Specifically, we derive an expression of the form

$$\theta = f(\tau_*, Re_p), \quad (17)$$

such that the threshold of bedform development can be represented as  $f(\tau_*, Re_p) = 1$ . Starting with equation 5, this expression may be obtained by invoking four relations outlined here and discussed in more detail below. These are (a) an expression relating the mean longitudinal particle velocity to the mean deviatoric particle speed, (b) a kinematic description of the volumetric flux in terms of the mean longitudinal velocity, the granular particle activity, and the particle volume (c) an empirical relation for the mean particle travel time, and (d) an empirical bedload transport formula.

The first element (a) is necessary because the mean deviatoric particle speed is a relatively obscure quantity that is not referenced in existing literature. In contrast, the mean longitudinal velocity is an essential component of the flux and is relatively well-studied (Lajeunesse et al., 2010, references therein). These quantities may be related by assuming a joint probability distribution model for longitudinal and lateral particle velocity. Several authors have proposed functional forms for the margins of this distribution (e.g., Furbish & Schmeeckle, 2013; Fathel et al., 2015; Furbish et al., 2016; Liu et al., 2019), however the correlation behavior and relative magnitudes of longitudinal and lateral components are not well-constrained, precluding the possibility of a purely theoretical derivation. Instead, we assume

$$\tilde{u}_p = \alpha u_x, \quad (18)$$

where  $\alpha$  is a coefficient of order unity. Neglecting lateral velocities and assuming longitudinal velocities are exponentially distributed leads to  $\alpha = 2/e \approx 0.73$ . This may be interpreted as a lower bound because upstream motions and nonzero lateral velocities will increase the mean deviatoric speed relative to the mean longitudinal speed. We find that  $\alpha = 1.28$  for the SPB condition and  $\alpha = 1.26$  for the UPB condition. For simplicity, we assume a fixed value of  $\alpha = 5/4$ .

The second element (b) is an exact expression for the average bedload flux  $q_b$  under steady, uniform macroscopic transport conditions (Furbish et al., 2012) given by

$$q_b = \gamma u_x. \quad (19)$$

Here, we point out that this expression may be combined with (18), and substituted into (5) to obtain:

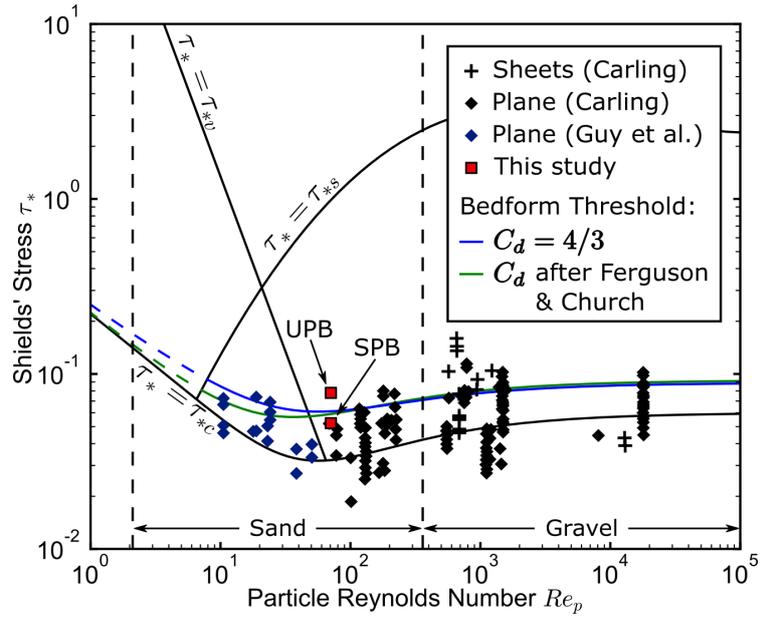
$$\theta = \frac{12\alpha q_b T_p}{\pi D^2}. \quad (20)$$

noting that  $\gamma = \gamma_g V_p$ , where  $V_p$  is a characteristic particle volume taken to be the volume of a sphere with diameter  $D$ .

The third element (c) is an empirical relation for the mean particle travel time  $T_p$ . This is perhaps the most uncertain element in predicting  $\theta$ , owing in part to experimental censorship and discrepancies in the strategies employed in different studies to delineate mobile and immobile particles (Hosseini-Sadabadi et al., 2019). Lajeunesse et al. (2010) reviewed previous work and concluded based on physical and dimensional arguments that the mean travel should be predicted as

$$T_p = \beta \frac{D}{\omega_s} \left( \frac{u_* - u_{*c}}{\omega_s} \right)^\varepsilon \quad (21)$$

where  $\omega_s$  is the particle settling velocity,  $u_*$  is the shear velocity,  $u_{*c}$  is the critical shear velocity for sediment motion, and  $\beta$  and  $\varepsilon$  are empirical coefficients. Based on available data, they suggest that that  $\beta = 10.7$  and  $\varepsilon = 0$ , removing the dependence on shear velocity. The settling velocity may be expressed by  $\omega_s = \sqrt{4RgD/3C_d}$ , where  $C_d$  is a



**Figure 4.** Shields-Parker river sedimentation diagram with theoretical microform-mesoform transition (Equation 24) for two particle settling models. Dashed segment indicates the region where model assumptions are not expected to hold due to significant suspension. As expected, the SPB condition plots below the threshold while the UPB condition plots above the threshold. The observations of planar topography and bedload sheets reported by Carling (1999) are plotted in for comparison. Also plotted are observations of planar topography reported by Guy et al. (1966) that were ignored by Southard and Boguchwal (1990) and Van den Berg and Van Gelder (1993) in delineating classic stability fields.

495 drag coefficient. Combining equations (20) and (21) with suggested values for  $\alpha$  and  $\beta$   
 496 leads to

$$\theta = 44.2\sqrt{C_d}q_* \quad (22)$$

497 where  $q_* = q_b/\sqrt{gRD^3}$  is the Einstein bedload number.

498 The final component (d) is the empirical bedload transport equation of Wong and  
 499 Parker (2006) given by

$$q_* = 3.97(\tau_* - \tau_{*c})^{3/2}. \quad (23)$$

500 Substituting this expression into (22) and setting  $\theta = 1$  provides a prediction of the thresh-  
 501 old Shields stress for bedform development  $\tau_{*\theta}$  corresponding to the transition from rar-  
 502 eified to congested transport:

$$\tau_{*\theta} = \left(\frac{0.0057}{\sqrt{C_d}}\right)^{2/3} + \tau_{*c} \quad (24)$$

503 where  $\tau_{*c} = f(Re_p)$  after Brownlie (1981) and  $C_d = f(Re_p)$  after Ferguson and Church  
 504 (2004). We also note that neglecting viscous settling,  $C_d \approx 4/3$  following Lajeunesse  
 505 et al. (2010) results in almost no change in the stability field for LSPB topography (Fig-  
 506 ure 4). Similarly, nonzero values of  $\varepsilon$  will shift the value of  $\tau_{*\theta}$  up or down slightly with-  
 507 out significantly altering the shape or qualitative fit to existing data.

508 The stability field for LSPB topography implied by this expression is plotted in Fig-  
 509 ure 4. We find that the theoretical prediction is aligned with observational data com-  
 510 piled by Carling (1999). This figure also includes observations of planar topography re-  
 511 ported by Guy et al. (1966) that were ignored in subsequent stability diagrams because  
 512 they are within the hydraulically smooth regime. (Southard & Boguchwal, 1990) asserted  
 513 that these conditions would have eventually produced ripples, however we suggest that  
 514 the relief of stable ripples would be small leading to poorly-developed flow separation.  
 515 As a result, they could be considered quasi-planar microforms by the criteria proposed  
 516 above.

517 We note here that the empirical stability fields for planar topography and bedforms  
 518 overlap substantially, with many observations of bedforms occurring in the region where  
 519  $\theta < 1$ . We offer several possible explanations. First, low-amplitude bedforms with poorly  
 520 developed flow separation could potentially appear qualitatively similar to ripples and  
 521 dunes in planform. In this case, they might be labeled as bedforms while being more ap-  
 522 propriately classified as microforms in the context of the present research. Second, there  
 523 is substantial variability in methodology used to compute the Shields' stress across dif-  
 524 ferent studies, and uncertainty is large for low values near the threshold of motion. Third,  
 525 the observed overlap may be a genuine feature of the data. If this is true, it implies that  
 526 either (a) the method for estimating  $\theta$  as a function of  $\tau_{*c}$  and  $Re_p$  is incomplete, or  
 527 (b)  $\theta = 1$  merely provides an upper limit for plane-bed stability. In either case, the bed  
 528 configuration likely depends on an additional parameter not considered here like the slope  
 529 or the Froude number.

## 530 **6.2 Sensitivity of Results to the Choice of Mobility Threshold $u_c$**

531 Sensitivity analysis was performed to determine whether results are sensitive to the  
 532 value of  $u_c$ , the cutoff value for particle velocity used to identify mobile particles (equa-  
 533 tion 8). All quantities were computed using 20 logarithmically spaced values for  $u_c$  rang-  
 534 ing from 0.001 m/s to 0.1 m/s. Select results are plotted in Figure (5).

535 The main objective of this exercise is to determine whether small changes in  $u_c$  in-  
 536 fluence our conclusions regarding  $\theta$ . While the values of  $\theta$  are sensitive to  $u_c$ , we find that  
 537 the the value for the UPB condition exceeds the value for the SPB condition by over an  
 538 order of magnitude across the full range of  $u_c$  values tested (Figure 5A). We also find

539 the value for the UPB condition exceeds 1 while the value for the SPB condition is less  
 540 than 1 for reasonable values of  $u_c$  identified by inspecting particle motions. Above  $u_c \approx$   
 541 0.15 m/s, we find  $\theta < 1$  for the UPB experiment, however this result is unrealistic be-  
 542 cause clearly mobile particles are ignored. Furthermore,  $\theta = O(1)$  up to  $u_c \approx 0.03$  for  
 543 UPB, compared with SPB, for which  $\theta = O(0.1)$ . While results obtained using 0.015  
 544 m/s  $< u_c < 0.03$  m/s independently are equivocal, we argue that the behavior of  $\theta$  as  
 545 a function of  $u_c$  is expected and holistically supports the hypothesis and interpretations  
 546 discussed above.

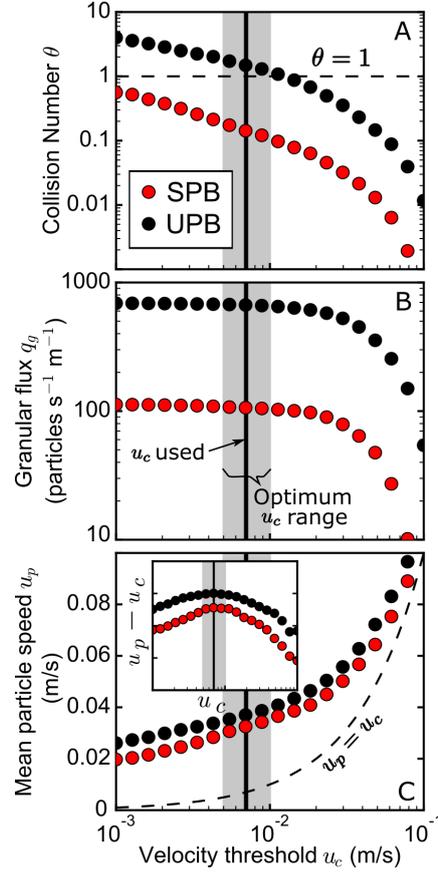
547 Estimates of tracer particle flux, total granular flux, and volumetric flux (which are  
 548 related by the tracer fraction and nominal particle volume) are also not sensitive to  $u_c$   
 549 across the optimum range. However, computed sediment load decreases rapidly for  $u_c >$   
 550 0.02 m/s because particles that contribute significantly to the measured sediment load  
 551 are ignored (Figure 5B). This observation provides a quantitative upper bound for  $u_c$   
 552 and supports the notion that  $\theta$  values computed above this bound are unreasonable. In  
 553 contrast, arbitrarily low values of  $u_c$  provide consistent estimates of flux. This is also ex-  
 554 pected; recall that the flux is calculated as  $q_b = \gamma_g u_x$ . Including immobile particles with  
 555 near-zero velocities in the calculation of sediment load increases  $\gamma_g$  but decreases  $u_x$  by  
 556 reciprocal factors such that there is no change in estimates of  $q_b$ .

557 Other relevant quantities (for example, entrainment rates, activities, velocities) are  
 558 sensitive to the choice of velocity threshold. Computed quantities typically vary slowly  
 559 as monotonic functions of  $u_c$  up to the point where  $u_c$  is a significant fraction of the max-  
 560 imum measured particle speed (roughly  $u_c = 0.02$  m/s in our experiments). Above this  
 561 threshold, computed quantities vary rapidly with  $u_c$  as mobile particles are increasingly  
 562 ignored. The average particle speed (the magnitude of the velocity vector) exemplifies  
 563 this behavior (Figure 5C). Interestingly, we find that the difference between the mean  
 564 computed particle speed and the threshold speed ( $u_p - u_c$ ) is maximized across the op-  
 565 timum range of velocity values that was determined independently by inspecting par-  
 566 ticle motions. Below this range, immobile particles included in the computation of mean  
 567 velocity cause a decrease in the excess particle speed; above, the threshold speed begins  
 568 to approach the maximum measured particle speed. This observation potentially pro-  
 569 vides an objective approach for selecting a velocity threshold.

## 570 7 Conclusions

571 This study clarifies the nature of lower-stage plane bed topography and the gran-  
 572 ular mechanics of ripple and dune initiation. As a starting point, we recognize that the  
 573 concept of planar topography breaks down at the granular scale and propose a defini-  
 574 tion of lower-stage plane bed topography that encompasses microforms like bedload sheets,  
 575 particle clusters, and other low-amplitude bedforms. This definition is appropriate be-  
 576 cause it is aligned with a hypothesized transition in process regime corresponding to the  
 577 onset of defect propagation and nonlinear coarsening. It is also aligned with practical  
 578 considerations related to form roughness, drag partitioning, and preserved sedimentary  
 579 structures.

580 Previous studies suggest that particle collisions are important during the initial phase  
 581 of bedform development. We formalize this idea to propose a quantitative hypothesis that  
 582 is tested using experimental observations of tracer particle motion over stable and un-  
 583 stable planar topography. Specifically, we hypothesize that quasi-planar topography be-  
 584 comes unstable when the particle collision frequency exceeds the particle entrainment  
 585 frequency. The dimensionless ratio of these quantities, called the “collision number”, is  
 586 like an inverse Knudsen number commonly used in fluid physics to quantify the tran-  
 587 sition from rarefied to continuum transport. We find that the collision number is 0.14  
 588 in the stable plane bed condition and 1.65 in the unstable plane bed condition despite  
 589 only a small increase in bed stress, supporting our hypothesis.



**Figure 5.** Plot illustrating the effect of the velocity threshold  $u_c$  on the measured variables. Although  $\theta$  is sensitive to the choice of velocity threshold, it varies by an order of magnitude regardless of the specific value used (A). Additionally, measured values straddle  $\theta = 1$  within the optimum  $u_c$  range. Sediment load is not sensitive to  $u_c$  except at very large values because particles that meaningfully contribute to the measured sediment load are ignored (B). We find that the optimum  $u_c$  range determined by inspection (Section 6.2) corresponds to the maximum difference between the mean measured particle speed and  $u_c$  (C).

590 Combining empirical and theoretical expressions enables prediction of the collision  
 591 number (and as a result, bed configuration) as a function of macroscopic boundary con-  
 592 ditions. We find that the predicted stability field for microforms is consistent with ob-  
 593 servations of lower-stage plane bed topography and bedload sheets reported by Carling  
 594 (1999) and Guy et al. (1966). Although ripples and dunes have been observed in the re-  
 595 gion where the collision number is predicted to be less than 1, this may be explained by  
 596 misclassification of low-amplitude bedforms or uncertainty in measurements of stress.  
 597 If the overlap is genuine, bed configuration may exhibit weak dependence on an addi-  
 598 tional parameter like slope or Froude number.

599 In summary, our primary hypotheses represents a coherent synthesis of existing process-  
 600 based descriptions of bedform initiation focused on various elements of turbulent fluid  
 601 flow, grain-scale transport, and topographic change. It is supported by experiments re-  
 602 ported here and observations of bed configuration reported by previous authors. Three  
 603 mechanisms are proposed to explain this finding. First, we suggest that grain-scale bed  
 604 disturbances inevitably self-organize into microforms like bedload sheets, particle clus-  
 605 ters, and other low-amplitude bedforms. Second, we suggest that microform amplitude  
 606 scales with particle diameter and collision frequency. Finally, we suggest that defect prop-  
 607 agation and nonlinear coarsening occurs when microform height exceeds a critical height  
 608 that is a constant multiple of particle diameter. These mechanisms provide a possible  
 609 explanation for our results and a starting point for future studies that aim to investi-  
 610 gate the mechanisms that determine the stable bed configuration under weak bedload  
 611 transport conditions.

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 617 periments and particle tracking. Data and code are available through Figshare (Ashley,  
 618 Naqshband, & McElroy, 2020)

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