

Deep-learning-based phase picking for volcano seismicity

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Key Points:

- We compile the first data set of seismic waveforms from various volcanic regions globally.
- We show that existing deep-learning phase pickers' performances deteriorate with decreasing volcanic earthquake frequency content.
- Our retrained models perform better and are more generalizable for monitoring volcano seismicity, especially long-period earthquakes.

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Abstract

The application of deep-learning-based seismic phase pickers for earthquake monitoring has surged in recent years. However, the efficacy of these models when applied to monitoring volcano seismicity has yet to be evaluated. Here, we first compile a dataset of seismic waveforms from various volcanoes globally. We then show that the performances of two widely used deep-learning pickers deteriorate systematically as the earthquakes' frequency content decreases. Therefore, the performances are especially poor for long-period earthquakes often associated with fluid/magma movement. Subsequently, we train new models which perform significantly better, including when tested on volcanic earthquake waveforms from northern California where no training data are used and tectonic low-frequency earthquakes along the Nankai Trough. Our model/workflow can be applied to improve monitoring of volcano seismicity globally while our compiled dataset can be used to benchmark future methods for characterizing volcano seismicity, especially long-period earthquakes which are difficult to monitor.

Plain Language Summary

Earthquake activity at volcanic regions is often monitored to indicate volcanic activity. Identifying the time when the energy radiated from an earthquake source arrives at a seismometer is essential for locating the earthquake, which can be difficult for volcanic earthquakes because of high noise levels, high event rates, and obscured onsets. Previous studies have demonstrated that deep learning, a type of artificial intelligence, can excel in picking the arrival times of regular earthquakes. However, the efficacy of these models when applied to monitoring volcanic earthquakes has yet to be evaluated. Here, we first compile a dataset of earthquakes from various volcanoes globally. We then show that existing deep-learning-based models do not work well for these events, especially those with predominantly low-frequency energy. We then train two new models which

perform better than existing models for volcanic earthquakes. Our model/workflow can be applied to improve monitoring of volcanic earthquakes globally.

1 Introduction

Detecting and identifying onsets of seismic phases is fundamental to locating seismicity. Manual inspection by experienced analysts is viewed as the gold standard but is extremely laborious and time-consuming. This makes it difficult to handle the ever-increasing volumes of seismic data and periods with extremely high seismicity rate such as during volcanic unrests. On the other hand, early automatic methods, such as the short-term average over long-term average method (STA/LTA) (Allen, 1978), suffer from low accuracy and require a number of parameters to be tuned carefully. Over the past two decades, the matched-filter technique has been shown to be an effective method (Gibbons & Ringdal, 2006; Chamberlain et al., 2017) to search for repeating or near-repeating earthquakes based on waveform similarity. However, this method is only capable of detecting earthquakes in the vicinity of known template events. In recent years, deep-learning-based pickers (e.g. Ross et al., 2018; Zhu & Beroza, 2019; Mousavi et al., 2020; Soto & Schurr, 2021) have been gaining increasing attention due to their picking accuracy being comparable to human analysts (Chai et al., 2020) and high efficiency. Their application has surged in recent years, including for delineating seismicity in fault zones, subduction zones, oceanic transform faults, and volcanoes (e.g. Tan et al., 2021; Jiang et al., 2022; Chen et al., 2022; Gong et al., 2023; Liu et al., 2023; Wilding et al., 2023; Garza-Girón et al., 2023). However, it can be difficult to predict deep-learning models' performance for out-of-distribution data that are not well represented by training data (Wenzel et al., 2022; Teney et al., 2022).

Seismicity which often correlate with magmatic/volcanic processes and sometimes represent eruption precursors (White & McCausland, 2019; Acocella et al., 2023) is an important monitoring observable at volcanoes. Two types of earthquakes are commonly

64 observed in volcanic regions: volcano-tectonic earthquakes (VTs) and long-period earth-
65 quakes (LPs), which are classified mainly based on their waveform frequency content but
66 may imply different source processes (e.g. Chouet & Matoza, 2013; Saccorotti & Lok-
67 mer, 2021; Matoza & Roman, 2022, and references therein). VTs share common spec-
68 tral characteristics with regular tectonic earthquakes and have impulsive onsets. They
69 mostly originate from shear fractures in the solid part of an edifice or the underlying crust,
70 hence only indirectly indicate magmatic activity. In comparison, most conceptual source
71 models of LPs involve fluids, e.g. resonating fluid-filled cracks (Chouet & Matoza, 2013),
72 thermal stresses in cooling magmas (Aso & Tsai, 2014), pressurization of exsolved volatiles
73 from stalled magmas (Wech et al., 2020), and rapidly growing bubble in ascending mag-
74 mas (Melnik et al., 2020). Therefore, LPs are often interpreted as a more direct evidence
75 of fluid movement (e.g. Song et al., 2023). However, compared to VTs, LPs are more
76 difficult to detect because they are depleted of high frequency content and have emer-
77 gent phase onsets (Pitt et al., 2002; Shapiro et al., 2017).

78 Some recent studies have applied existing deep-learning phase pickers, which were
79 trained using regular tectonic earthquake waveforms, to monitor volcano seismicity (Mittal
80 et al., 2022; Bannister et al., 2022; Suarez et al., 2023; Li et al., 2023; Garza-Girón et
81 al., 2023; Wilding et al., 2023). However, there is currently no large-scale, systematic eval-
82 uation of the efficacy of these existing models for volcano monitoring. For instance, their
83 performances for volcanic earthquakes may be impaired by different waveform charac-
84 teristics, emergent onsets of long-period events, and high/different background noise in
85 volcanic regions (Lapins et al., 2021). While there have been a few models trained with
86 seismic data near volcanoes (Lapins et al., 2021; Kim et al., 2023; Armstrong et al., 2023),
87 limited data distribution (individual volcano) make these models less generalizable to
88 other volcanic regions. In addition, none of these studies explicitly included long-period
89 earthquakes in their analyses (Lapins et al., 2021; Kim et al., 2023; Armstrong et al., 2023).

90 In this study, we first compile a data set of seismic waveforms from various volcanic
91 regions. We then show that the performances of two widely used deep-learning pickers,
92 PhaseNet (Zhu & Beroza, 2019) and EQTransformer (Mousavi et al., 2020), deteriorate
93 when applied off-the-shelf to volcanic seismic data, especially for long-period earthquakes.
94 We then train new models that achieve significantly better performances for monitor-
95 ing volcano seismicity.

96 **2 Dataset of seismic waveforms from volcanic regions**

97 We assemble a data set of 156,272 LP waveforms (34,980 events), 156,498 VT wave-
98 forms (38,115 events), and 20,000 noise waveforms recorded by seismic stations deployed
99 around 34 volcanoes in Alaska (Power et al., 2019), 6 volcanoes in Hawaii (Hawaiian Vol-
100 cano Observatory/USGS, 1956), 8 volcanoes in northern California (NCEDC, 2014) and
101 88 volcanoes in Japan (National Research Institute for Earth Science and Disaster Re-
102 siliance, 2019). The geographical distribution of the events is shown in Figure 1. See Ta-
103 ble S1 in the supporting information for more details about data set splitting, Figure S1
104 for the distribution of recording stations, Figure S2 for the distribution of volcanoes and
105 Figures S3-S14 for other properties of the data. All the event waveforms have both man-
106 ually picked P and S phase arrivals. Most waveforms contain 3 components (77%) (Fig-
107 ure S3) and are from earthquakes located within 50 km of an active volcano (95%) (Fig-
108 ure S4). Since there are far more available VTs than LPs, we only include a similar num-
109 ber of VT waveforms as the number of available LP waveforms. We remove data with
110 large spikes and errors (e.g. events with S pick prior to P pick). For waveforms from Japan,
111 we download event waveforms whose length may vary for different events and different
112 stations. For waveforms from the US, we download event waveforms starting from 60s
113 before the P pick and ending 60s after the S pick. Hence waveforms in our data set have
114 different lengths, which will be trimmed in the subsequent processing stages. Compared
115 with previous datasets, e.g. STEAD (Mousavi et al., 2019) and INSTANCE (Michelin
116 et al., 2021), our data set has a wider distribution of frequency index (Figures S7-S10)

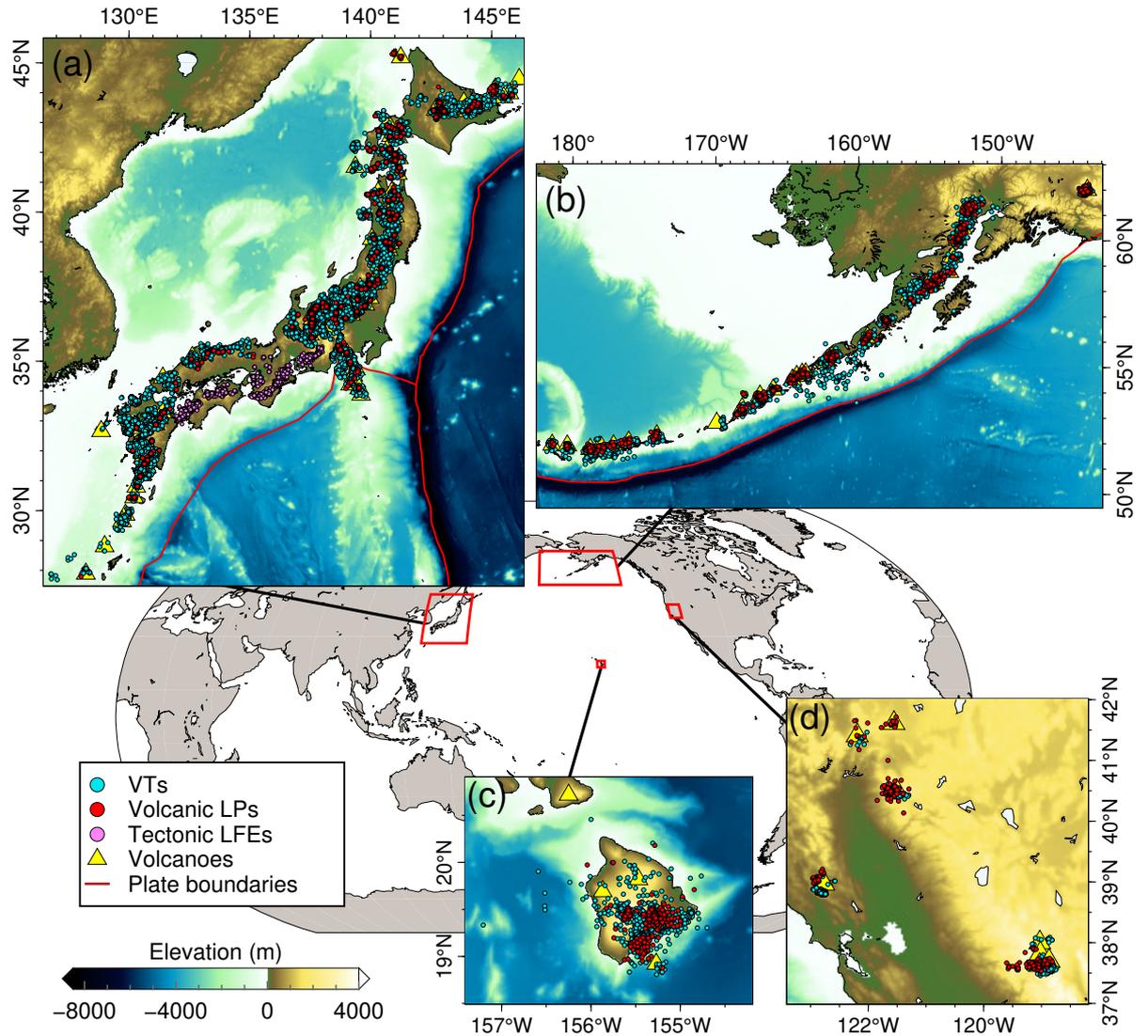


Figure 1. Geographical distribution of the earthquakes used in this study. The seismic data of volcano-tectonic earthquakes (cyan circles) and volcanic long-period earthquakes (red circles) from Japan (a), Alaska (b) and Hawaii (c) are split into a training set, a validation set and a test set, while the data from northern California (d) and the tectonic low-frequency earthquakes (LFEs) (purple circles) from Japan are only used for testing. Yellow triangles mark active volcanoes with seismic events used in this study.

117 which is a measure of the dominant frequency content of an earthquake (Buurman & West,
118 2010) (Text S1), suggesting it includes a greater variety of seismic events. To the best
119 of our knowledge, this is the first data set of seismic waveforms compiled from various
120 volcanic regions globally for machine learning.

121 **3 Evaluation of existing deep-learning phase pickers**

122 We use 15,078 LP waveforms and 15,057 VT waveforms from Alaska, Hawaii and
123 Japan to evaluate two most widely used models: PhaseNet (Zhu & Beroza, 2019) and
124 EQTransformer (Mousavi et al., 2020), which are the best performing architectures in
125 a recent benchmark study (Münchmeyer et al., 2022). PhaseNet is a U-net with 1D con-
126 volutional layers originally trained on earthquakes from northern California. EQTrans-
127 former is a stack of convolutional layers, long short-term memory (LSTM) units, and self-
128 attentive layers originally trained on the global data set STEAD (Mousavi et al., 2019).
129 We divide the testing waveforms into subsets according to frequency index values to eval-
130 uate how the model performance varies with the dominant frequency content. We ran-
131 domly extract 30s windows around the manual picks of the testing waveforms. For each
132 waveform, the same window is used to test different models. Since EQTransformer op-
133 erates on a 60s window, we will only focus on the 30s target window of the output (Münchmeyer
134 et al., 2022). We use precision, recall and F1-score to evaluate the results. Precision is
135 the fraction of output picks that are actually correct. Recall is the fraction of manual
136 picks that are correctly identified by the model. F1 score is the harmonic mean of pre-
137 cision and recall (Text S2). Considering that the original EQTransformer and PhaseNet
138 were trained under the TensorFlow framework (Abadi et al., 2015) that is different from
139 the platform we use (pyTorch) and that they were not trained on the same data set, we
140 also include the variants of EQTransformer and PhaseNet trained on the INSTANCE
141 data set (Michellini et al., 2021) for comparison, which were trained by Münchmeyer et
142 al. (2022) and available in the SeisBench package (Woollam et al., 2022). The model out-
143 put is time series of “probability” of P and S. To get predicted picks from the probabil-

144 ity time series output by the models, we first extract segments of probability curves above
 145 a given threshold and the peak positions of these extracted segments are considered as
 146 pick times. The model-specific threshold is tuned (Figure S15) on the validation set (Ta-
 147 ble S1).

148 The recalls, precisions and F1 scores of the original models decrease systematically
 149 with decreasing frequency index (Figure 2). For example, the F1 score of PhaseNet de-
 150 creases from ~ 0.9 to ~ 0.5 for P picking and from ~ 0.85 to ~ 0.25 for S picking as the
 151 frequency index decreases from ~ 0.5 to ~ 1.7 . Compared with precision, the recall ex-
 152 hibits a greater deterioration, which can be as low as 0.4 for P picking and 0.2 for S pick-
 153 ing, indicating that most LPs in the test set have been overlooked. We observe a sim-
 154 ilar trend for the models trained on INSTANCE (Münchmeyer et al., 2022). This is un-
 155 likely to be related to changes in signal-to-noise ratio since we do not observe significant
 156 systematic changes in signal-to-noise ratio with frequency index (Figure S17). Our re-
 157 sults suggest that these existing models will likely underreport LPs compared to VTs
 158 when directly applied to monitoring volcano seismicity (Bannister et al., 2022; Mittal
 159 et al., 2022; Wilding et al., 2023; Garza-Girón et al., 2023; Suarez et al., 2023; Li et al.,
 160 2023), which is not ideal since LPs often indicate fluid/magma movements (Chouet &
 161 Matoza, 2013; Matoza & Roman, 2022). Therefore, we decided it would be valuable to
 162 train a new phase picker specifically for volcano seismicity.

163 **4 Training deep-learning phase pickers for volcano seismicity**

164 Among our data set, 151,431 LP waveforms, 151,657 VT waveforms and 20,000 noise
 165 waveforms from Alaska, Hawaii and Japan corresponding to 70,352 events are grouped
 166 into a training set (83.64%), a validation set (5.49%) and a test set (10.87%) (Table S1).
 167 Here, the earthquake waveforms in the test set are the same as those presented in the
 168 previous section. An extra test set comprising 4,841 waveforms from 1,094 LP events and
 169 4,841 waveforms from 1,649 VT events near 8 volcanoes in northern California is used

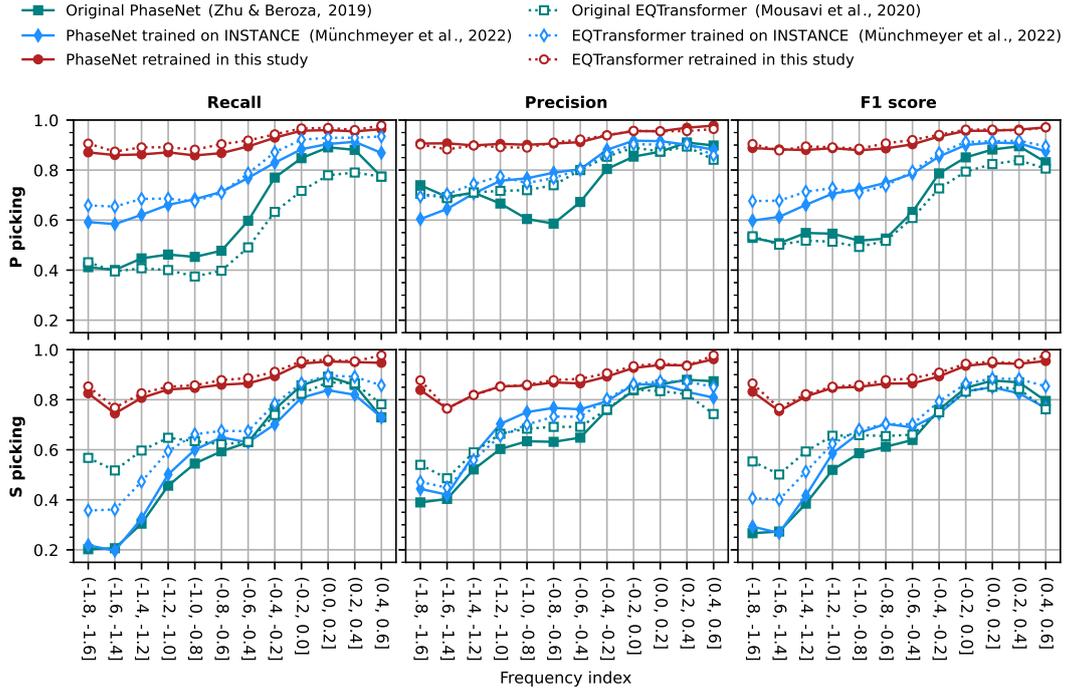


Figure 2. Performances of various models on subsets of testing waveforms with different frequency index values. The F1 scores here is slightly higher than those in Figure 3a because noise waveforms, to which frequency index is not applicable, are not included in this test.

170 to test how our model generalizes to a region where no training data have been used. In
171 addition, 6,224 waveforms of 2,356 tectonic low-frequency earthquakes (LFEs) along the
172 Nankai trough in Japan are used as another test set to investigate whether our model
173 works for tectonic LFEs associated with shear slip on the subduction zone plate inter-
174 face (Obara & Kato, 2016).

175 We use our data set to train two new models based on the PhaseNet and EQTrans-
176 former architectures implemented in the SeisBench package (Woollam et al., 2022). All
177 the waveforms are resampled to 100 Hz. We normalize each component of a waveform
178 by removing the mean and dividing it by the maximum value. We perform data augmen-
179 tation by randomly modifying the waveforms at each step of training. The modifications
180 include randomly shifting waveforms, adding gaps to waveforms, adding Gaussian noise
181 and superimposing a training example on the shifted and rescaled version of another train-
182 ing example. Each type of augmentation is performed with a given probability. Normal-
183 ization is performed before and after data augmentation. The labels for phase arrivals
184 are Gaussian functions with peaks aligning with manual picks. At each step of training,
185 a batch of waveform examples are randomly selected, normalized, randomly augmented,
186 labelled, and input into the Adam optimization algorithm (Kingma & Ba, 2015) to ad-
187 just the model weights.

188 The validation set is used to tune hyperparameters. We try various learning rates
189 0.0001/0.0005/0.001 and batch sizes 512/1024 to obtain a series of models. Each model
190 is trained for 400 epochs. Loss function on the validation set is monitored for each epoch
191 and the model snapshot at the epoch with the lowest validation loss is used as the final
192 model. For each model, we test different decision thresholds and choose the one with the
193 highest F1-score as the optimal threshold. Then we evaluate each model on the valida-
194 tion set and choose the one with the highest F1-score (Tables S2-3). The preferred learn-
195 ing rate and batch size for PhaseNet are 0.0005 and 512, respectively. They are 0.001
196 and 1024 for EQTransformer, respectively. We also compare random initialization and

197 initialization from the network weights pre-trained on the INSTANCE data set (Melnik
 198 et al., 2020; Münchmeyer et al., 2022), and we choose the one with the highest F1-score
 199 on the validation set (Table S4).

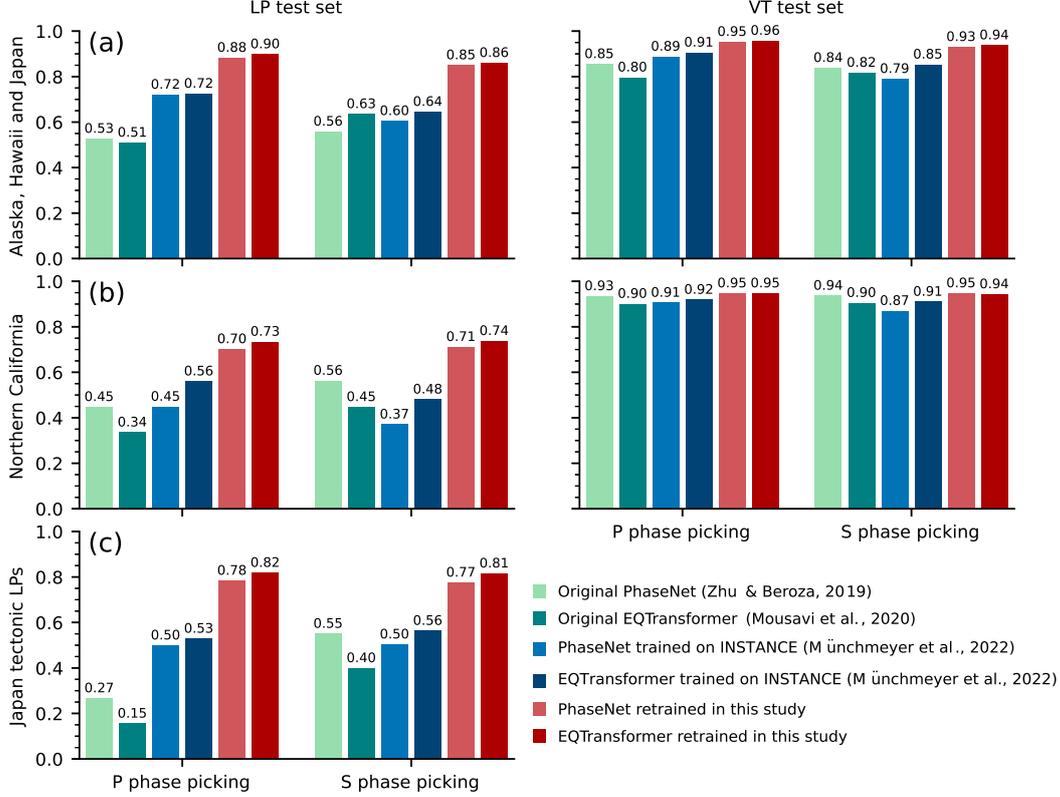


Figure 3. F1 scores of different models evaluated on the testing waveforms from (a) the same regions as the training data, (b) northern California from where no training data are used and (c) tectonic LFEs in Japan. The precision and recall are given in Figures S24-S25 in the supplement.

200 We first test our models on subsets with different frequency index values as described
 201 in the previous section. Our models trained for volcano seismicity show significant per-
 202 formance improvement for waveforms with low frequency index values compared to ex-
 203 isting models, with F1 scores for P and S picking of ~ 0.9 and ~ 0.8 , respectively (Fig-
 204 ure 2). There is also a slight improvement for waveforms with high frequency index. The
 205 overall performances of various models on the whole test set are shown in Figure 3a, where
 206 our models show the best performances for both LPs and VTs for both P and S pick-

207 ing. For the LPs, the EQTransformer-based network trained in this study achieves an F1
208 score of 0.9 for P picking and 0.86 for S picking, which are 0.39 (P picking) and 0.23 (S
209 picking) higher than those of the original EQTransformer. The performance improve-
210 ment is smaller for the VTs: the retrained EQTransformer achieves F1 scores 0.16 and
211 0.12 higher than the original EQTransformer model for P and S picking respectively. The
212 EQTransformer trained on INSTANCE has similar performance to the original EQTrans-
213 former except for P picking on the LPs, for which the F1 score of the INSTANCE-based
214 EQTransformer is ~ 0.2 higher than that of the original EQTransformer but ~ 0.2 lower
215 than that of our retrained EQTransformer. A similar amount of improvement is obtained
216 by the PhaseNet-based network trained on our data set. Furthermore, our models give
217 lower picking residuals as indicated by the narrower histograms of residuals (Figure S19-
218 S20). The retrained EQTransformer shows only a marginally higher F1 score than the
219 retrained PhaseNet, suggesting that the data set plays a more important role than the
220 network architecture in differences in model performances.

221 Subsequently, we use the test set from northern California to investigate how our
222 models generalize to regions where no training data are used (Figure 3b). All the mod-
223 els show great performance for VTs, with F1 scores for P picking larger than 0.9 and F1
224 scores for S picking larger than 0.87, and our models achieve the highest F1 scores (0.95).
225 Notably, the existing pickers perform poorly for LPs, with F1 score ranging from 0.34
226 to 0.56. Although all the models experience some performance degradation for LPs com-
227 pared with the previous test, our retrained models still perform significantly better than
228 the existing models, with F1 scores ranging from 0.70 to 0.74. The performance varia-
229 tion with frequency index for this test set (Figure S18) also suggests that our models have
230 better generalization abilities when applied to a new region. The poorer performances
231 for LPs could be partly explained by the LP waveforms in this test set having lower signal-
232 to-noise ratios than VT waveforms (Figures S6 and S18).

233 Finally, we investigate whether our models also work for tectonic LFEs since both
234 tectonic LFEs and volcanic LPs appear to have similar frequency content, though they
235 are often inferred to reflect different source processes (Aso et al., 2013). Our training set
236 does not explicitly include any tectonic LFE. Here we test the models on LFEs along the
237 Nankai trough from Japan. The result is shown in Figure 3c. Our retrained models out-
238 perform the original models and the INSTANCE-based models by a large margin for both
239 P and S picking, with F1 scores of ~ 0.8 . We further confirmed that our models also work
240 for regular tectonic earthquakes, since they achieve F1 scores of 0.89 and 0.75 for P and
241 S picking respectively when tested on the INSTANCE data set (Michelini et al., 2021),
242 which is slightly better than the original EQTransformer and PhaseNet but unsurpris-
243 ingly inferior to the models trained on the INSTANCE data set (Figure S29).

244 **5 Discussion**

245 **5.1 Comparison with existing methods**

246 Deep-learning-based pickers have higher accuracy and require less parameters to
247 manually tune than traditional pickers, e.g. STA/LTA (Allen, 1978) and the Baer-Kradolfer
248 picker (Baer & Kradolfer, 1987), as demonstrated in previous studies (e.g. Zhu & Beroza,
249 2019; Mousavi et al., 2020; Münchmeyer et al., 2022). Also, deep-learning-based pick-
250 ers have greater flexibility than template matching as they are not limited by the avail-
251 ability of suitable template events. Compared with previous deep-learning models aimed
252 at tectonic earthquakes, our models can better pick volcano seismicity and thus can help
253 to improve volcano monitoring. Our compiled waveform dataset can also be used to bench-
254 mark future methods for monitoring volcanic earthquakes.

255 Our study is different from a few recent studies that have also trained models on
256 volcanic earthquakes (Lapins et al., 2021; Kim et al., 2023; Armstrong et al., 2023) in
257 two aspects. First, the previous studies focused exclusively on one volcano and thus it
258 is unclear how well these models can generalize to other volcanoes, while we use data around

259 136 active volcanoes from different regions. Second, LPs were not considered in the pre-
260 vious studies despite being an important form of volcano seismicity, while we included
261 LP earthquakes for training. We subsequently demonstrated that our models perform
262 well for both LPs and VTs, and can be generalized to other volcanoes. However, since
263 these studies adopted different data formats, input/output formats, machine-learning frame-
264 works and not all of these models are available, it would be hard to make direct com-
265 parisons.

266 Finally, our study is different from recent studies which focused on tectonic LFEs
267 (Thomas et al., 2021; Lin et al., 2023; Münchmeyer et al., 2023) in terms of training data
268 and targets. These studies focused on tectonic LFEs which are a manifestation of creep
269 or slow fault slips (Behr & Bürgmann, 2021), while our target is to pick volcano seismic-
270 ity including both VTs and LPs. The capability of our models to pick tectonic LFEs is
271 a side benefit and demonstrates that (1) our models are generalizable to other tectonic
272 environments and (2) tectonic LFEs and volcanic LPs have relatively similar waveform
273 characteristics.

274 **5.2 Different ways of performance evaluation**

275 The presented evaluation results for different models depend on the metrics used
276 and how they are calculated, which may vary in different studies. Therefore, it might
277 not be appropriate to directly compare the values reported in different papers. For in-
278 stance, some studies calculate true positive (TP), false positive (FP), true negative (TN)
279 and false negative (FN) based on waveform traces so that any of the four outcomes TP/FP/TN/FN
280 is assigned to each testing waveform (e.g. Zhu & Beroza, 2019; Mousavi et al., 2020).
281 In this case, a waveform is considered as a true positive as long as there is a predicted
282 pick sufficiently close to the manual pick even if there may also be some falsely predicted
283 picks for the same waveform. Hence, false predictions may be underreported. In contrast,
284 the definition of positive and negative in this paper is based on sampling points, where
285 any of TP/FP/TN/FN is assigned to each sampling point of a waveform rather than the

286 whole waveform (Text S2). The different definitions of FP and FN lead to different val-
287 ues of recall and precision. We have also calculated the model performances using the
288 definition of positive/negative based on waveform traces (Zhu & Beroza, 2019; Mousavi
289 et al., 2020), and the results (Figure S26-S27) show similar trends as those presented in
290 the previous section (Figure 2-3) except that the absolute values are slightly higher.

291 Alternatively, Münchmeyer et al. (2022) decomposed the evaluation into 3 tasks:
292 event detection, phase identification and onset time picking. This evaluation workflow
293 avoids the ambiguity in the definition of positive/negative for phase picking. However,
294 it uses the maximum probability value within the tested window as the prediction re-
295 sult, which may be inconsistent with the practical application of a deep-learning picker
296 where a trigger algorithm is used to retrieve picks from an output probability curve. Nev-
297 ertheless, our models also show better performances than existing models when evalu-
298 ated on the 3 tasks following Münchmeyer et al. (2022)’s workflow (Figure S21-S23 and
299 Table S5-S6), although existing models also perform well on the task of event detection
300 which is easier than phase picking. Therefore, our models show consistently better per-
301 formances than existing models regardless of the method of performance evaluation.

302 **6 Conclusion**

303 In this study, we first compile a dataset of seismic waveforms from various volcanic
304 regions globally, which has a wider distribution of frequency index than previous datasets
305 of tectonic earthquakes. We then show that existing deep-learning-based phase pickers
306 do not generalize well for volcanic earthquakes, with their performances deteriorating
307 as the earthquakes’ frequency content decreases, hence direct applications for monitor-
308 ing volcano seismicity is suboptimal with biases. Finally, we train and test new models
309 using our data set. The test results show that our models can better pick P and S phases
310 of VTs and LPs, and can be generalized to other regions not included in our training data

311 set, including for tectonic LFEs. Therefore, our results can benefit future efforts to im-
312 prove monitoring of volcano seismicity.

313 **Open Research Section**

314 Our models have been uploaded for peer review, with the archiving at Zenodo cur-
315 rently underway. All seismic data used in this study are publicly available. The seismic
316 waveforms and catalogs in Japan are from the Japan Meteorological Agency ([http://](http://www.jma.go.jp)
317 www.jma.go.jp) and the National Research Institute for Earth Science and Disaster Re-
318 siliance (<https://www.hinet.bosai.go.jp>) (National Research Institute for Earth Sci-
319 ence and Disaster Resilience, 2019). The seismic data and catalogs for Hawaii and Alaska
320 are from USGS (Hawaiian Volcano Observatory/USGS, 1956; Alaska Volcano Observa-
321 tory/USGS, 1988) and Incorporated Research Institutions for Seismology Data Manage-
322 ment center (IRIS-DMC, <https://ds.iris.edu/ds/nodes/dmc>). The seismic data and
323 catalogs for northern California are from the Northern California Earthquake Data Cen-
324 ter (NCEDC, 2014) (<https://ncedc.org>). We use the plate boundaries by Bird (2003)
325 in Figure 1. The volcano locations are from the Japan Meteorological Agency ([https://](https://www.data.jma.go.jp/vois/data/tokyo/STOCK/souran.eng/menu.htm)
326 www.data.jma.go.jp/vois/data/tokyo/STOCK/souran.eng/menu.htm), Geological Sur-
327 vey of Japan (https://gbank.gsj.jp/volcano/Quat.Vol/index_e.html), Alaska Vol-
328 cano Observatory (<https://www.avo.alaska.edu/volcano/>), Hawaiian Volcano Ob-
329 servatory (<https://www.usgs.gov/observatories/hvo>) and California Volcano Ob-
330 servatory (www.usgs.gov/observatories/calvo). We use ObsPy (Krischer et al., 2015)
331 and HinetPy (Tian et al., 2022) to facilitate waveform downloading. We use the network
332 architectures implemented in the SeisBench package (Woollam et al., 2022). We train
333 the networks under the PyTorch framework (Paszke et al., 2019) using the pytorch-lightning
334 package (Falcon & The PyTorch Lightning team, 2019).

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