1  **A new method for the detection of siliceous microfossils on sediment microscope**
2  **slides using convolutional neural networks**

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9  **Key Points:**

10  • Faster R-CNN models are efficient at detecting marine diatom frustules on microscope
11    slide images.

12  • These models can be applied to detect the diatoms on images from a diverse array of
13    environmental conditions.

14  • Adequate sample preparation and image quality enhance model results.
15

**Abstract**

Diatom communities preserved in sediment samples are valuable indicators for understanding the past and present dynamics of phytoplankton communities, and their response to environmental changes. These studies are traditionally achieved by counting methods using optical microscopy, a time-consuming process that requires taxonomic expertise. With the advent of automated image acquisition workflows, large image datasets can now be acquired, but require efficient preprocessing methods. Detecting diatom frustules on microscope images is a challenge due to their low relief, diverse shapes, and tendency to aggregate, which prevent the use of traditional thresholding techniques. Deep learning algorithms have the potential to resolve these challenges, more particularly for the task of object detection. Here we explore the use of a Faster R-CNN (Region-based Convolutional Neural Network) model to detect siliceous biominerals, including diatoms, in microscope images of a sediment trap series from the Mediterranean Sea. Our workflow demonstrates promising results, achieving a precision score of 0.72 and a recall score of 0.74 when applied to a test set of Mediterranean diatom images. Our model performance decreases when used to detect fragments of these microfossils; it also decreases when particles are aggregated or when images are out of focus. Microfossil detection remains high when the model is used on a microscope image set of sediments from a different oceanic basin, demonstrating its potential for application in a wide range of contemporary and paleoenvironmental studies. This automated method provides a valuable tool for analysing complex samples, particularly for rare species under-represented in training datasets.

**Plain Language Summary**

Microfossils preserved in ocean sediments are studied to explore the impact of climate change on planktonic communities. The usual way to count these microfossils is slow and requires an expert to identify them on microscope images. In this study, we explore how artificial intelligence can be used on microscope images to detect the microfossils produced by one particular group, diatoms. Our results show that models can be trained to identify these objects, including the ones that were not specifically shown to the model during the training phase. However, the quality of the microscope image, and of the sample preparation beforehand, can affect how well the model works. This new protocol has good potential to be used on diatom images differing in age and geographical origins. Adopting this method could make it possible to rapidly increase the temporal resolution and spatial extent of existing data on diatom diversity, which could thus improve our knowledge of plankton resilience to climate change.

**1 Introduction**

There exists a significant variability in size, growth rates, nutrient acquisition, and trophic interactions within and between different phytoplankton groups. This diversity exerts a fundamental control on biogeochemical cycles, for instance through its influence on carbon export from the surface ocean and on food web dynamics. Ongoing climate change, through a comprehensive set of processes, impacts phytoplankton diversity and size structure, with consequences both for carbon storage and trophic efficiency (Henson et al., 2021; Passow & Carlson, 2012). As a result, efforts have been made to integrate phytoplankton diversity into Earth system models (Le Quéré et al., 2005), to better predict the effect of different climate scenarios on biogeochemical cycling and food web efficiency.

The study of phytoplankton communities is traditionally achieved by manually counting species identified in sediment or plankton net samples, a time-consuming process that requires specific taxonomic expertise. Consequently, existing time series of plankton changes often have low temporal and spatial resolution. Moreover, counting methodologies may vary between research groups, making interlaboratory comparisons difficult (Zingone et al., 2015). As a response to these challenges, a variety of proxies have been proposed to describe the

65 phytoplankton community (Lombard et al., 2019), including (but not limited to) the use of
66 satellite ocean colour (Hirata et al., 2008; Mouw et al., 2017; Nair et al., 2008), DNA meta-
67 barcoding analyses (De Vargas et al., 2015), pigment analysis (Claustre, 1994) and fluorescence
68 (Petit et al., 2022). These methods yield information on the planktonic community's size
69 distribution and taxonomic composition over a broad range of sizes. However, their analyses
70 operate at different levels (functional, genetic, etc.), which may only partially align with the
71 traditional approach of morphological taxonomy. In parallel, efforts have been made to develop
72 automated imaging techniques, making it possible to obtain taxonomical and morphological data
73 on both single organisms and the total population (reviewed in Lombard et al. 2019). The palette
74 of methods described above is powerful for monitoring present-day plankton diversity and
75 provides a means of obtaining standardized phytoplankton time series.

76        The study of the sediment record of the biominerals produced by different phytoplankton
77 groups constitutes a different type of archive. It can be used to study the past sensitivity of the
78 phytoplankton community to environmental change and its implications on the past strength of
79 the biological pump (Kohfeld et al., 2005). The taxonomic composition of phytoplankton is also
80 used as a proxy for various environmental variables (Abrantes et al., 2007; Marino et al., 2014).
81 The study of the sedimentary record of biomineralisation is typically achieved using light
82 microscopy on fixed samples. The development of automated image acquisition techniques using
83 electron scanning or optical microscopy has made it possible to acquire large sets of plankton
84 images from sediment samples with limited human intervention. These methods have been used
85 successfully to obtain large image datasets documenting the past production of a variety of fossil
86 organisms in marine and freshwater environments, including coccoliths, radiolarians,
87 foraminifera, or pollen grains (Beaufort et al., 2014; Bourel et al., 2020; Marchant et al., 2020;
88 Tetard et al., 2020). To treat these large image datasets, studies increasingly rely on machine
89 learning algorithms for object detection and identification. While the use of these techniques was
90 once limited to IT experts, their recent integration into user-friendly software such as EcoTaxa
91 (Picheral et al., 2017) or ParticleTrieur (Marchant et al., 2020) now makes it possible for
92 researchers without specific training in plankton identification to obtain plankton counts from
93 their images or to build and train a classification model based on their own image library. This is
94 a handy feature when studying fossil data (Carlsson et al., 2023), for which annotated datasets
95 are rare. Among machine learning techniques, the use of deep-learning algorithms has been
96 generalized (Borowiec et al., 2022), encouraged by the increasing amount of publicly available
97 software libraries and the advent of fast and affordable GPU-based computing systems. The use
98 of convolutional neural networks (CNNs) for image recognition has been developed in
99 particular; CNNs are able to extract the features of interest in an image, which makes them
100 useful and efficient for tasks such as object detection and object classification (Borowiec et al.,
101 2022; Serre, 2019). To date, fully automatic workflows have been successfully developed to
102 study the fossil record of a variety of biominerals (Beaufort & Dollfus, 2004; Tetard et al., 2020,
103 2020); however, there exists to our knowledge no means of performing such studies on the
104 diatom record. This, in part, is due to the difficulties in efficiently detecting them on a
105 microscope image.

106        Diatoms are a phytoplankton group of particular interest, as they live in most marine and
107 freshwater environments, which makes them responsible for one-fifth of the photosynthesis on
108 Earth (Armbrust, 2009). They are often the dominant phytoplankton group in turbulent and
109 nutrient-rich environments (Kemp & Villareal, 2018; Margalef, 1978). Diatoms produce
110 remarkable species-specific silicified cell walls called frustules. At the end of their life cycle,
111 these biominerals are transported through the water column and accumulate in the sediments,
112 creating deposits that can reach, in some areas, more than several hundred meters in thickness
113 (Armbrust, 2009). The number and large size of these frustules in comparison to the biominerals
114 produced by other phytoplankton groups makes them one of the main contributors to the
115 biological pump (Jin et al., 2006). The blooms formed by some diatom species have also been

116 shown to contribute significantly to carbon export from the surface ocean in more oligotrophic
117 regions such as the Mediterranean Sea (Leblanc et al., 2018). Studies have shown, however, that
118 the diatoms' contribution to carbon export depends on the group's composition (Ragueneau et
119 al., 2006; Tréguer et al., 2018). Climate-induced changes in the diversity of this group could,
120 therefore, have implications for the biological pump. Furthermore, the decrease in diatom
121 abundance in the total phytoplankton assemblage in favour of nanoplankton groups, including
122 coccolithophores, has been linked in some environments to a decrease in primary productivity
123 and carbon export (Iriarte & González, 2004). It is thus essential to describe how the diatom
124 community responds to climate change, both within the group and in comparison to other
125 phytoplankton groups.

126 Diatom identification in sediments is traditionally achieved using optical and electron
127 scanning microscopy (SEM). Detecting diatom frustules on a microscope image remains a
128 challenge. Implementing an automated object detection workflow for diatoms is indeed hindered
129 by the difficulty of isolating these minerals from the background image. Traditional thresholding
130 techniques have proven effective to segment calcareous nanofossils, due to their birefringence
131 properties (Beaufort et al., 2021), as well as radiolarians, which exhibit high relief (Tetard et al.,
132 2020). They have also been used to detect diatoms from images of modern-day river samples
133 (Bueno et al., 2017) or, more generally, on frustule images obtained using brightfield microscopy
134 (Kloster et al., 2014). However, the low relief of diatom frustules on sediment slides, the
135 diversity of frustule shapes, and a tendency for frustules to cluster or break complicate the use of
136 existing plankton detection workflows (Kloster et al., 2014). As a result, studies increasingly
137 explore the use of deep neural networks (Kloster et al., 2020, 2023) to extract individual diatom
138 frustules from a raw image. However, most deep learning-based attempts at detecting diatoms on
139 microscope images have focused on samples used for water monitoring (Bueno et al., 2018;
140 Kloster et al., 2023) or for forensic analyses (Yu et al., 2022). These models have been either
141 developed for living cells (Li et al., 2020) or for images acquired using SEM (Yu et al., 2022)
142 and thus are not directly transposable to marine sediment samples, which present a lot of
143 damaged and broken cells.

144 In this study, we propose and test the use of a Faster RCNN model to detect diatom
145 frustules on images obtained from sediment slides using an automated microscope. We detail
146 how the images in the dataset were acquired, how they were annotated to constitute a training
147 and validation library, and how the CNN model performed when compared to a test set. We
148 investigate which factors influence the detection performance.

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## 2 Materials and Methods

### 2.1 Image acqusition

152 We trained an object detection model using images from samples collected from the Lionceau
153 sediment trap series located in the Gulf of Lion in the NW Mediterranean Sea (42°N, 4.5° E,
154 2400 m). This series comprises 80 samples collected between 2010 and 2018. The Gulf of Lion
155 is among the most productive areas in the Mediterranean Sea and exhibits a relatively large
156 diversity of siliceous biomineralizers, including diatoms and silicoflagellates (Rigual-Hernández
157 et al., 2013). Each sample's collection period was two weeks, on average, and the samples span
158 the entire seasonal cycle. To evaluate how the model performs on an image dataset from a
159 different oceanographical setting, we also included images from three sediment samples aged
160 less than 100 years from the core B1404-11 (14.14°S, 76.50°W, 302 m) recovered from the
161 Peruvian upwelling zone in 2014.

162 Sediment trap and core samples were prepared using the random settling method (Beaufort et al.,
163 2014; Tetard et al., 2020), a protocol that can also be used to study calcareous nanofossils. A
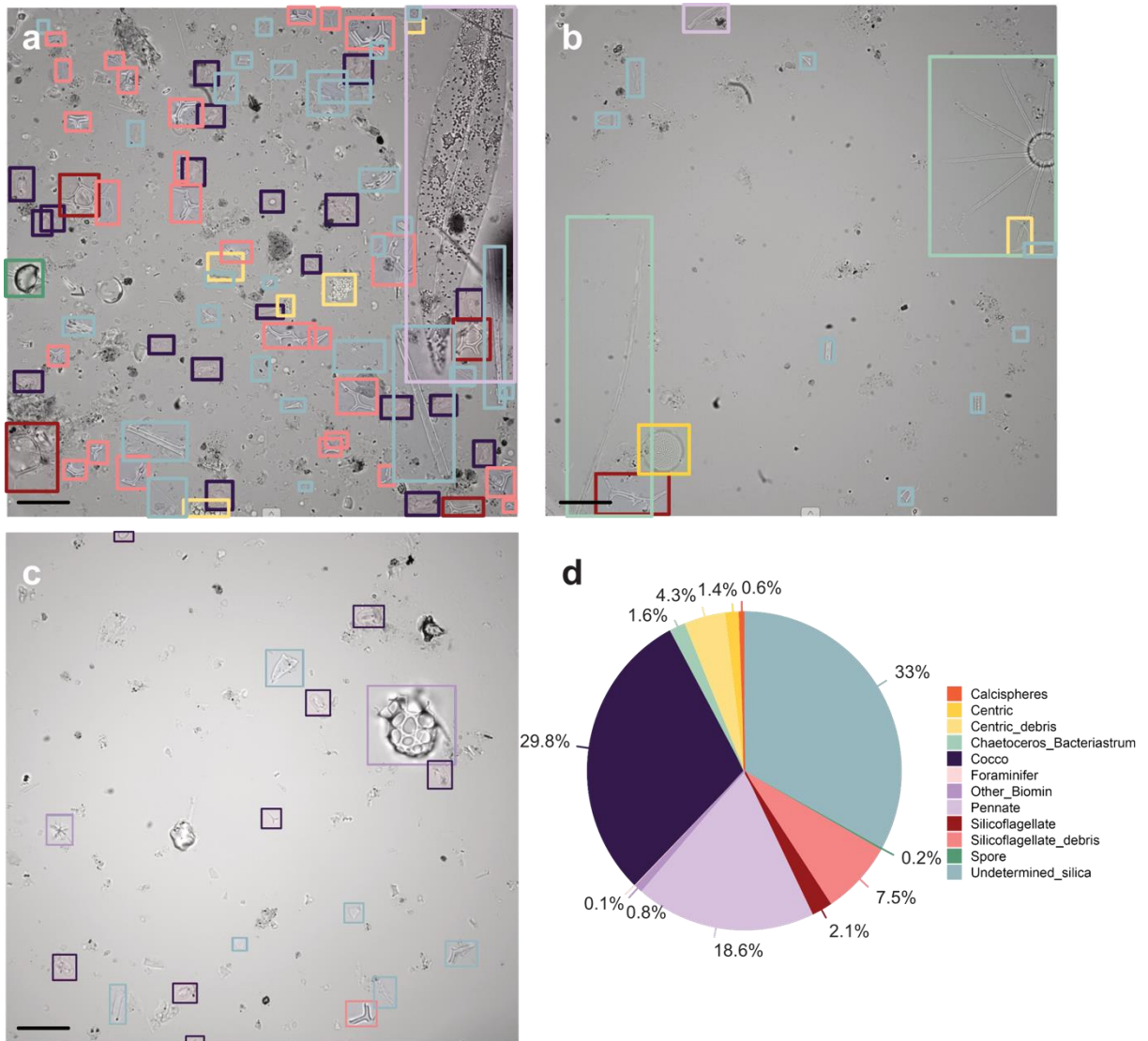
164  couple of milligrams of dried sediment were resuspended in water and ultrasonicated for less
165  than a minute to remove major aggregates. Around 3 ml of the suspension was collected, left to
166  settle for four hours on 12 mm x 12 mm coverslips, and left to dry overnight after pipetting the
167  excess water. Subtracting the initial mass from the final mass of the coverslips yielded a mass of
168  sediment on each coverslip within the range of 50 to 150 µg. Sets of eight coverslips were then
169  mounted on a microscope slide using Norland Optical Adhesive 81. Each slide was mounted
170  consecutively on a Leica DMR6000 B automated transmitted light microscope with 630x
171  magnification using a HCX PL FLUOTAR 63× Leica lens. Images (210 µm x 210 µm) were
172  taken using a Hamamatsu ORCA-Flash4.0 LT camera, controlled via a LabVIEW (National
173  Instruments) interface. We acquired images for around 250 fields of view for each sample. For
174  each field of view, we acquired 15 images of different focal lengths to image a depth of at least
175  100 µm. Hyperfocused stacks were created from these 15 images using the Helicon Focus 7
176  software (Helicon Soft).

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178  2.2 Experimental design for automatic diatom detection using deep learning approaches

179  *2.2.1 Training and validation image dataset*

180  The use of deep learning methods requires the creation of a labelled set of images for training.
181  For this experiment, we randomly chose 253 images from the Lionceau image set (corresponding
182  to 39 samples). We used the Computer Vision Annotation Tool (CVAT) developed by Intel to
183  label these 8-bit images of 2048 x 2048 pixels.

184  We drew bounding boxes around all microfossil material identified on the images for a total of
185  10293 bounding boxes. We attributed each bounding box to twelve different microfossil
186  categories (*i.e.* silicoflagellates, diatoms, coccoliths, other biominerals, etc.; **Figure 1**) but
187  pooled all the boxes into a single "microfossil" category for training. Our dataset is dominated
188  by small fragmented elements ("Undetermined_silica"), pennates (often fragmented), and large
189  coccoliths ("Cocco") (**Figure 1**).

**Figure 1:** CVAT screenshots of different microscope images annotated (a-c) and relative contribution of different microfossil material to the total bounding box dataset (d). The color code for the bounding boxes is reported in panel (d). The models were not trained for object classification, however the training set is dominated by small fractured elements ("Undetermined_silica"), pennates (often fragmented), and large coccoliths ("Cocco"). The scale is 20 micrometers

### 2.2.2 Test image dataset

To test the model, a second set of randomly selected images of the Lionceau sediments was manually annotated to generate a set of ground-truth bounding boxes. This test set includes 66 annotated images for a total of 2165 bounding boxes. These bounding boxes were attributed to one of the twelve categories used for the training set to better constrain the objects that the model might overlook. In addition, descriptive tags were associated with the images of the dataset to investigate how the image or sample quality could impact the detection model. These descriptive tags account for images with one or several characteristics, including low concentration of elements, high concentration of fragmented elements, presence of aggregates, image out of focus, and image darker in appearance due to the use of a different set of light parameters on the microscope. Images that did not fall into these categories were labelled as "good quality".

### *2.2.3 Model training*

The model was trained using 80% of the images as a training set and the remaining 20% for validation. All bounding boxes drawn on CVAT were pooled into a single "microfossil" category for model training. This was intended as a way of generating a model capable of detecting any microfossil on a microscope image regardless of its species or type, including rare species for which collecting a detailed dataset can be a time-consuming task. A Faster R-CNN (faster region-based convolutional neural network) object detection model with a ResNet50 backbone was trained on the data. Faster R-CNN models were indeed shown to perform better on diatom images from microscope observations than other deep-learning algorithms such as You Only Look Once (YOLOv3), which did not perform very well on small objects, and single-shot multi-box detector (SSD) (Li et al., 2020). Faster R-CNN feeds the initial image to a backbone CNN to generate a feature map of the image. The features propose regions that may correspond to objects, and these regions are subsequently pooled before being classified into object classes using fully connected prediction layers. In our case, we use the ResNet50 CNN pre-trained on the COCO dataset as the backbone. Faster R-CNN provides bounding box coordinates and class labels for the detected objects.

Training was performed using data augmentations such as random horizontal flip, random vertical flip, and random photometric distortion (brightness, contrast, saturation, hue), using either the stochastic gradient descent (SGD) or Adam optimisers with learning rate adjusted using the adaptive learning rate scheduler (ALRS) described in (Marchant et al., 2020). We experimented with different training set sizes, optimisation methods, and ALRS parameters. Code for the training routine is available at https://github.com/microfossil/particle-object-detection.

### *2.2.4 Model testing*

Using the object detection model that was most performant on the training and validation set, we generated a set of "modelled" bounding boxes on our test set, which we compared to the "ground-truth" bounding boxes drawn manually on the test set. The comparison of the sets of ground-truth bounding boxes with the modelled set was achieved using the bounding box coordinates. We calculated the "intersection over union" (IoU; **Table 1**) metric for all possible pairs of ground-truth and modelled bounding boxes of a single image. In general, a higher IoU score indicates a better performance, an IoU score of 1.0 being the perfect case. We matched the best pairs of bounding boxes using a cost algorithm (R package RcppHungarian). True positives ($t_p$) were calculated for the dataset as the number of bounding box pairs with an IoU metric greater than or equal to 0.5. Unattributed ground-truth bounding boxes were counted as false negatives ($f_n$), while unattributed modelled bounding boxes were counted as false positives ($f_p$). With these different metrics, we could generate the model's precision and recall metrics (**Table 1**).

254 **Table 1: definition of the metrics used to evaluate the performance of the object detection**
255 **model**

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| Metric | Formula | Description |
|---|---|---|
| Intersection over Union (IoU) | $$\frac{BB_1 \cap BB_2}{BB_1 \cup BB_2}$$ | The ratio of area of overlap between bounding boxes 1 ($BB_1$) and 2 ($BB_2$) to the total area represented by $BB_1$ and $BB_2$. |
| Precision | $$\frac{\sum t_p}{\sum t_p + \sum f_p}$$ | The number of correct predictions to the total number of predictions made by the model |
| Recall | $$\frac{\sum t_p}{\sum t_p + \sum f_n}$$ | The number of correct predictions to the total number of initial ground-truth bounding boxes |

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259 **3 Results and Discussion**
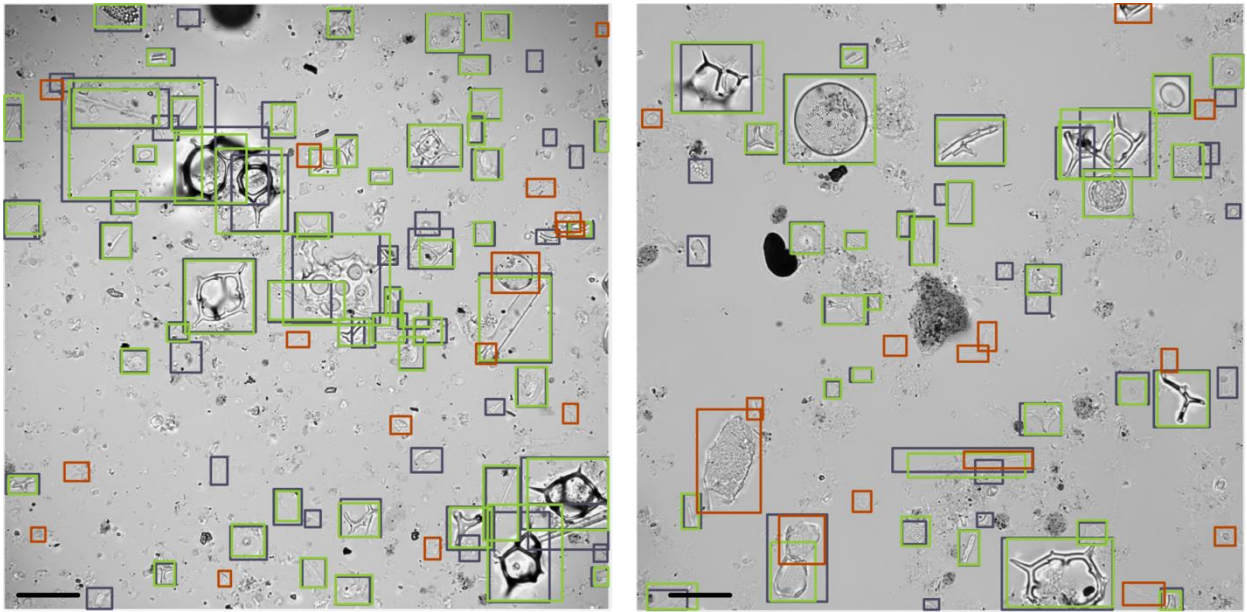
260       3.1 Training outputs

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262 The different model outputs can be compared using standard COCO object detection metrics
263 (**Table 2**). To account for the large number of microfossils in each image, we increased the
264 maximum number of objects from 100 to 300. The precision metric for an IoU of 0.50 is, on
265 average, 0.717 (± 0.006) across the different models runs. The mean recall for all bounding
266 boxes across an IoU range of 0.50 to 0.95 is, on average, 0.537 (± 0.007). The model performs
267 better across all trainings on objects that are comparatively larger than others (*i.e.* area larger
268 than 96x96 pixels), with precision and recall scores being consistently better for large objects
269 than for medium (*i.e.* area between 32x32 pixels and 96x96 pixels) objects (**Table 2**).

270 Results show that increasing the training set size from 10293 bounding boxes to 12458 (+21%)
271 (using the added annotations from the test set) slightly decreases model performance for all
272 model metrics observed. Changing the optimizing method from SGD, used as default, to Adam
273 increases model precision and recall on medium-sized objects, but it decreases the overall model
274 precision for an IoU of 0.5 as well as the model recall for all objects. Changing the ALRS epochs
275 parameter (*i.e.* the learning rate scheduler watches to check if training is not improving) from 10
276 to 20 does not change the model precision for an IoU of 0.5 and decreases the model recall when
277 all objects are considered.

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**Table 2: Outputs from the different model runs performed using Faster R-CNN with the training and validation dataset**. Output variables are standard COCO object detection metrics, modified to detect up to 300 objects in a single image. Average precision (AP) is the precision metric averaged over a range of IoUs from 0.50 to 0.95, for medium (area between 32x32 pixels and 96x96 pixels) and large (larea larger than 96x96 pixels) objects. Recall scores are all calculated over a range of IoUs from 0.50 to 0.95. The best model result for each metric considered is shown in bold.

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| Input | | | | | | Output | | | |
|---|---|---|---|---|---|---|---|---|---|
| Model Number | Test description | Total images (training + validation) | Total bounding boxes | ALRS epochs | Optimiser | Precision:<br>• IoU = 0.5<br>• IoU = 0.75 | Average precision: @0.50:0.95<br>• Medium<br>• Large | Recall: Max detections = 300 Area=all | Recall: Max detections = 300<br>• Medium<br>• Large |
| 1 | Base parameters | 253 (203+50) | 10293 | Default (10) | Default (SGD) | • **0.720**<br>• 0.531 | • 0.381<br>• **0.574** | **0.545** | • 0.475<br>• 0.649 |
| 2 | Increase dataset size | 319 (256+63) | 12458 | Default (10) | Default (SGD) | • 0.706<br>• 0.508 | • 0.350<br>• 0.571 | 0.525 | • 0.446<br>• 0.637 |
| 3 | Change optimiser from "SGD" to "Adam" | 253 (203+50) | 10293 | Default (10) | Adam | • 0.716<br>• **0.543** | • **0.382**<br>• 0.561 | 0.539 | • **0.479**<br>• 0.627 |
| 4 | Change ALRS epochs from 10 to 20 | 253 (203+50) | 10293 | 20 | Default (SGD) | • **0.720**<br>• 0.516 | • 0.376<br>• 0.540 | 0.540 | • 0.466<br>• **0.650** |

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**Figure 2 – Prediction results on a test set using a detection threshold of 0.3.** Ground-truth
bounding boxes are represented in dark blue. True positive bounding boxes are in green, and
false positives are shown in orange. The scale is 20 micrometers. Images are acquired in optical
microscopy from the Lionceau sediment trap series in the Gulf of Lion. Left: sample collected in
July 2011, Right: sample collected in April 2014.

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### 3.2. Model performance on a test set

The model trained using the base parameters, which showed the best overall performance on the
trap sediment images, was then applied to a test set of images from the same sediment trap
series. Bounding boxes were matched when the IoU metric was over 0.50 (see example outputs
and cropping results in **Figure 2**). Of the 2165 ground-truth bounding boxes on which the model
was tested, the model recognized 1569 objects (recall = 0.725) when a detection threshold of 0.5
was used. The model generated 565 false positive bounding boxes (precision = 0.735). Lowering
the detection threshold to 0.3 increases the number of true positives (1599) and, thus, recall
(0.739) (**Table 3**). However, using a detection threshold of 0.3 also increases the number of false
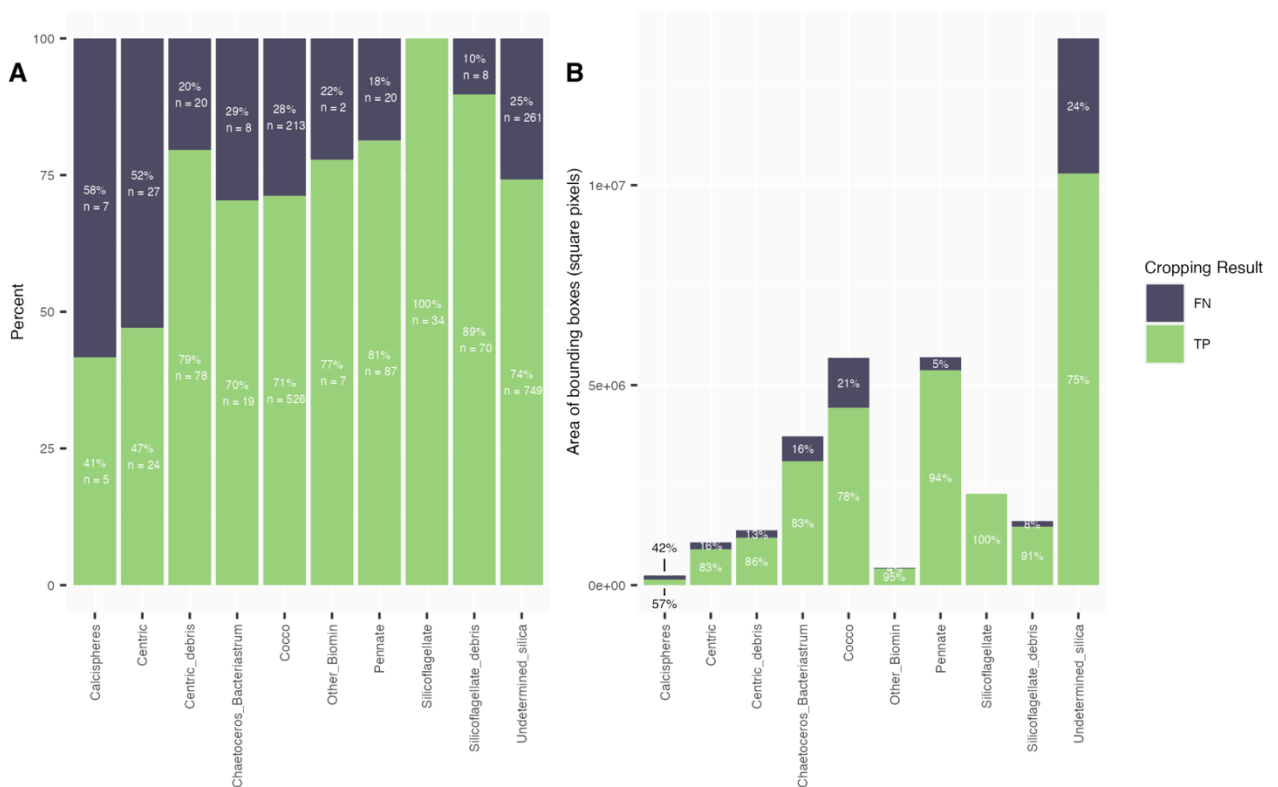positive bounding boxes (623) and thus leads to lower model precision (0.72).

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#### *3.2.1. Controls on model recall*

To ensure that all objects present on the raw images are efficiently cropped to be used in a
further classification algorithm, we are most interested in maximising model recall – i.e. its skill
at detecting any object – and identifying which of the ground-truth boxes the model misses. In
detail, not all microfossil categories are detected the same way by the model (**Figure 3**). Results
show that recall scores are better for high relief particles such as silicoflagellates, with 100%
particles identified, than for Chaetoceros spp. (70%) which exhibit lower relief and are prone to
dissolution due to less robust frustules. The lowest recall scores are obtained for calcispheres and
centric diatoms.

When considering the total category area instead of category counts, it appears that the model
captures more than 80% of the ground-truth area in each category, except for calcispheres (57%),
which are only present as fragments in this test dataset. The model also exhibits low recall values
for total coccolith area (78%) and for the total area of silica not attributed to a specific producer
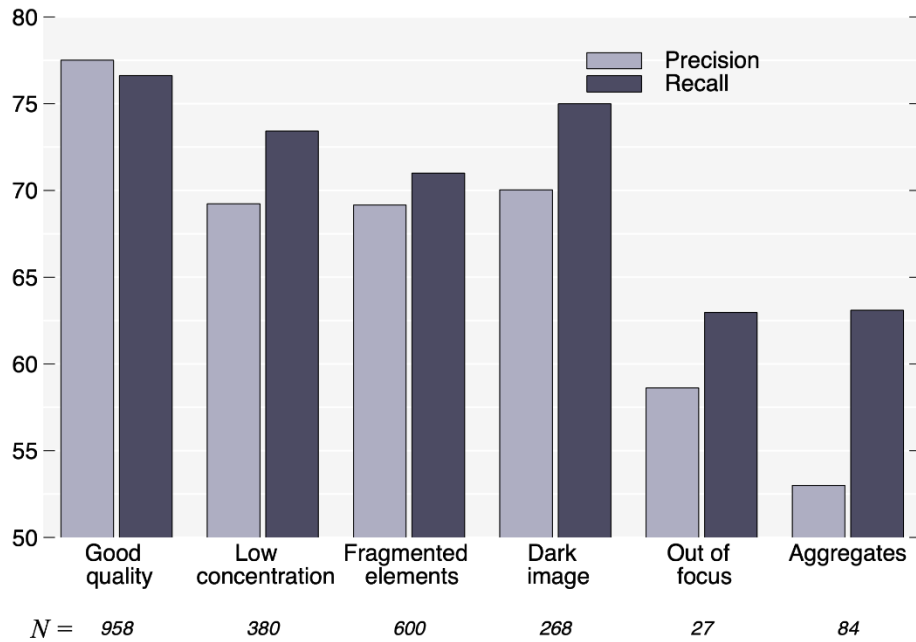
320    (75%), despite these classes dominating the training set (**Figure 1**). These results and the raw
321    model outputs suggest that the object detection model works best for the large elements across
322    all categories.

323    Model precision and recall may be affected by the quality of the sample image. We pooled all
324    the ground-truth bounding boxes into categories corresponding to the descriptive tags listed in
325    the Methods section. Due to multiple tags being sometimes attributed to the same image, some
326    bounding boxes are present in different categories. We calculated precision and recall scores for
327    each descriptive tag (**Figure 4**). Good-quality images display the best precision and recall scores
328    (0.775 and 0.766 respectively). Changes in microscope acquisition parameters, which can yield
329    darker images and/or less contrasted images, decrease precision (0.70) and, to a lesser extent,
330    recall (0.75). A low concentration of objects of interest, which in the images observed can be
331    attributed to some extent to dissolution, reduces precision (0.692) and recall (0.734). The
332    presence of fragmented elements also reduces precision (0.691) and recall (0.71) scores. This
333    could be explained by the fact that the model appears to perform more poorly on small objects.
334    Images that are out of focus generate more false positives and negatives, with precision and
335    recall scores of 0.586 and 0.63. The presence of aggregates on the images, which lead to more
336    objects being superimposed, also impacts the quality of object detection, with precision and
337    recall scores of 0.53 and 0.631.

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339    **Figure 3 – Object detection performance on a test set using the base model with a detection**
340    **threshold of 0.3. a.** Stacked bar plot of the percentage of false negative (FN) and true positive
341    (TP) bounding boxes obtained, per ground-truth box category. **b.** Bar plot of the total predicted
342    bounding box area per ground-truth bounding box category. The color code is the same as for
343    panel A. Model recall is highest for silicoflagellates and pennates. When considering the
344    bounding box area instead of total counts, the model appears to perform better, suggesting that
345    small elements are more likely to lead to false negatives.

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**Figure 4 – Object detection performance on a test set, per descriptive tag.** The set of predicted bounding boxes was generated using the base model with a detection threshold of 0.3. Acquiring images with a different set of light parameters on the microscope has little effect on model recall, but may lead to a reduction in model precision. However, the detection model does not perform as well when images are out of focus, and/or have a low concentration of elements (usually linked to dissolution), and/or include fragments and/or aggregates.

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358        3.2.2. Model precision

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Model precision is low when the model generates many false positive bounding boxes. One issue with low model precision in a detection task is the generation of multiple bounding boxes per microfossil (**Figure 2**). This can lead to certain particles being transferred multiple times to a classification algorithm and thus counted twice. We reviewed the false positive bounding boxes generated using a detection threshold of 0.3 (**Figure 5**) into five categories to evaluate this bias. Results show that 37 of the 623 false positives are duplicate bounding boxes, which represents 1.7% of the ground-truth bounding boxes. Therefore, it appears that the generation of multiple bounding boxes of the same microfossil occurs marginally in our dataset.

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We find that 30 of the $f_p$ bounding boxes generated by the model partially overlap a ground-truth bounding box. However, they are not counted as $t_p$ due to low IoU scores ($< 0.5$): the predicted bounding box may capture only part of the microfossil (n=16, **Figure 5**) or be too large or shifted (n=14) compared to the ground-truth bounding boxes. Additionally, 37 of the $f_p$ bounding boxes are actual microfossils that were overlooked during annotation. The remaining 526 $f_p$ bounding boxes do not correspond to a microfossil and can easily be eliminated in a classification step.
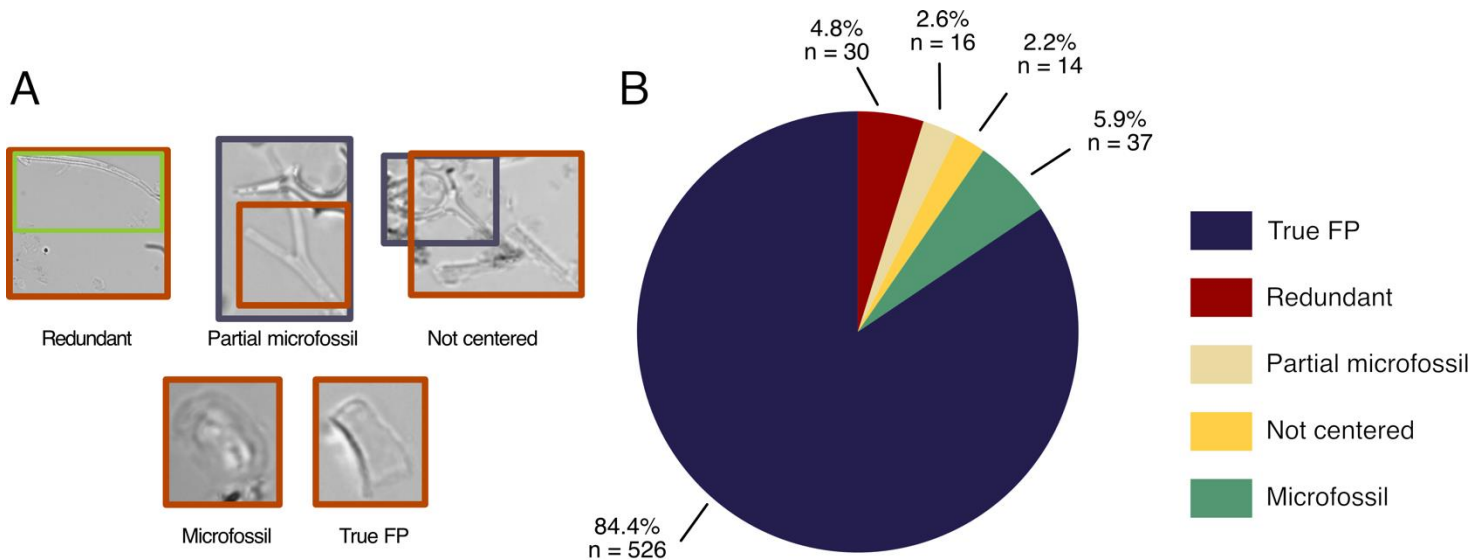
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378        3.3. Transfer to a new dataset

379    One of the goals of this experiment is to test the potential for a CNN-based model to perform
380    diatom frustule detection for samples originating from various oceanographical settings and time
381    periods. Indeed, deep neural networks have a limited capability of transferring to image datasets
382    which differ from the training set (Serre, 2019). We explore how the detection model trained on
383    images from Mediterranean trap sediments performs on a set of images from a sediment core of
384    the Peruvian upwelling. Although these images were acquired using a similar methodology, they
385    contain microfossils from species that are not present in the Mediterranean dataset. Similarly to
386    the test set from the Mediterranean sediment traps, we labelled 37 images, drawing 1868 ground-
387    truth bounding boxes, which were attributed to twelve categories. We apply the base model with
388    a detection threshold of 0.3 and compare it to a set of ground-truth bounding boxes using the
389    same method as for the Mediterranean sediment trap test dataset (see Methods section).

390    The comparison of these two bounding box datasets yields precision and recall scores of 0.729
391    and 0.754 respectively. The model thus performs slightly better on this new test set of images
392    from the Peruvian setting than on the test set of images from the Mediterranean trap (**Table 3**).
393    Multiple factors might explain this result, such as (1) the smaller abundance of coccoliths in
394    these samples, which were shown to be less well captured by the model, (2) the good
395    preservation of these diatom-rich sediments formed in an environment with a high accumulation
396    rate, and (3) a smaller amount of out-of-focus images than in the test dataset.
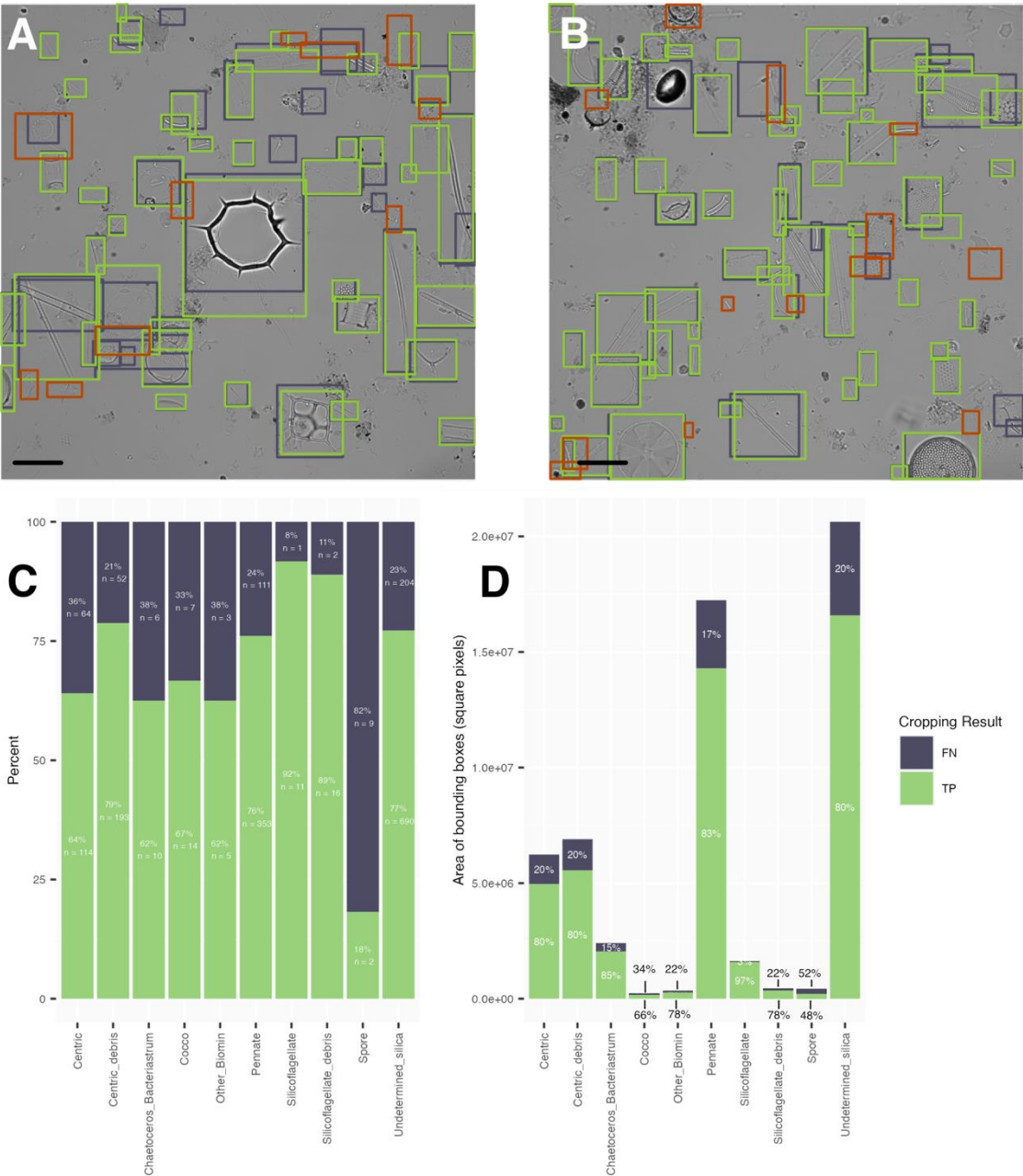
397    As for the Mediterranean dataset, the model performs better on the largest particles present on
398    the images, especially on silicoflagellates. Interestingly, the model detects plankton species and
399    morphospecies that are absent from the test set, including the silicoflagellate *Octactis* genus and
400    the diatom genus *Actinoptychus* (**Figure 6**). However, the model performs poorly on detecting
401    diatom resting spores, which are nearly absent from the training set (**Figure 1**). These results
402    suggest that this CNN-based object detection protocol has the potential to be used across a
403    variety of image datasets from sediment samples but could still benefit from being trained
404    specifically on some particles not captured by our training set.



405    **Figure 5 – False positive outputs for the test dataset**. **a.** Classification scheme for the false
406    positive bounding boxes; see Fig.**2** for color scheme explanation. **b.** Distribution of false positive
407    bounding boxes.

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**Figure 6 – Prediction results on an image dataset from the Peruvian upwelling zone. a.** – **b.**: Ground-truth bounding boxes are represented in dark blue. True positive bounding boxes are in green, and false positives are shown in orange. The scale is 20 micrometers. **c.** Stacked bar plot of the percentage of false negative (FN) and true positive (TP) bounding boxes obtained, per ground-truth box category. **d.** Bar plot of the total predicted bounding box area per ground-truth bounding box category. The color code is the same as for panel A.

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419 **Table 3: Performance of the object detection model applied to different test sets**.

| Test set | Model used | TP bounding boxes | FN bounding boxes | FP bounding boxes | Precision | Recall |
|---|---|---|---|---|---|---|
| Mediterranean sediment trap | Detection model with base parameters applied with a 0.5 detection threshold | 1569 | 596 | 565 | 0.7352 | 0.7247 |
| Mediterranean sediment trap | Detection model with base parameters applied with a 0.3 detection threshold | 1599 | 566 | 623 | 0.720 | 0.739 |
| Peruvian sediments | Detection model with base parameters applied with a 0.3 detection threshold | 1408 | 460 | 524 | 0.729 | 0.754 |

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423    **4. Conclusions**

424    In this study, we developed an object detection workflow using Faster R-CNN model which
425    allows for the automatic detection of diatom frustules on sample slides. Given their non-
426    birefringent nature, wide variety in shapes and sizes, and tendency to overlap, diatom frustules
427    remain challenging to detect and crop with traditional thresholding techniques. The method
428    showed promising results for detecting diatom frustules on microscope images, with a precision
429    score reaching 0.72 for an IoU of 0.5, and a corresponding recall score of 0.58 for IoU scores
430    ranging from 0.5 to 0.95. The comparison of modelled bounding boxes with a test set showed
431    that, for the generally accepted IoU threshold of 0.5, the recall for the model reaches an
432    acceptable level for analyzing real and complex samples, with a value of 0.73. Large and high
433    relief particles are well detected by the Faster R-CNN (**Figure 3**) despite making up a smaller
434    fraction of the training dataset. Our workflow can deal with overlapping particles, however the
435    proposed method is not completely efficient on large aggregates (**Figure 4**). Ensuring properly
436    focused microscope images and reducing the number of images containing fragments and
437    dissolved elements minimizes potential errors in the detection process.

438    Decoupling the detection from the identification makes our method interesting for the detection
439    of rare species which may be under-represented in the training dataset. A possible solution to
440    combine detection and identification into a single deep-learning model would be to test the use
441    of virtual slides to artificially increase the instances of rare microfossils in the training set
442    (Venkataramanan et al., 2023), however this solution would still require the acquisition of a large
443    image dataset to cover the full diversity spectrum.

444    Prospects for this particular workflow include incorporating this detection and cropping
445    algorithm into a more general identification workflow, specific to siliceous biominerals. The
446    microfossil crops generated from the microscope images by the workflow can be uploaded into
447    open-access computer programs such as ParticleTrieur (Marchant et al., 2020) for labelling and
448    training a classification model. The microscope slides processed in this workflow are also
449    suitable for analysis by the SYRACO software to obtain coccolith counts and morphology
450    (Beaufort & Dollfus, 2004) and radiolarian analysis (Tetard et al., 2020). This makes it possible
451    to study the changes in species composition within and between different groups of marine
452    phytoplankton, a critical step when studying biogeochemical cycles and changes in planktonic
453    communities.

454    This workflow has the potential to detect microfossils present on sediment samples from
455    different spatial and temporal settings, both from sediment traps and sediment coring systems
456    (**Figure 6**). Future work will focus on enriching the image database used for training to include
457    microfossils that require better detection, to obtain a model applicable to any sedimentary sample
458    containing siliceous biominerals.

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464 **Acknowledgments**

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472 **Open Research**

473 The code for the object detection workflow is available at 10.5281/zenodo.10591771
474 (geometrikal, 2024).

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